

Review



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A statistical state dynamics approach to wall turbulence

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This paper reviews results obtained using statistical state dynamics (SSD) that demonstrate the benefits of adopting this perspective for understanding turbulence in wall-bounded shear flows. The SSD approach used in this work employs a second-order closure that retains only the interaction between the streamwise mean flow and the streamwise mean perturbation covariance. This closure restricts nonlinearity in the SSD to that explicitly retained in the streamwise constant mean flow together with nonlinear interactions between the mean flow and the perturbation covariance. This dynamical restriction, in which explicit perturbation–perturbation nonlinearity is removed from the perturbation equation, results in a simplified dynamics referred to as the restricted nonlinear (RNL) dynamics. RNL systems, in which a finite ensemble of realizations of the perturbation equation share the same mean flow, provide tractable approximations to the SSD, which is equivalent to an infinite ensemble RNL system. This infinite ensemble system, referred to as the stochastic structural stability theory system, introduces new analysis tools for studying turbulence. RNL systems provide computationally efficient means to approximate the SSD and produce self-sustaining turbulence exhibiting qualitative features similar to those observed in direct numerical simulations despite greatly simplified dynamics. The results presented show that RNL turbulence can be supported by as few as a single streamwise varying component interacting with the streamwise constant mean flow and that judicious selection of this truncated support or ‘band-limiting’ can be used to improve quantitative accuracy of RNL turbulence. These results suggest that the SSD

approach provides new analytical and computational tools that allow new insights into wall turbulence.

This article is part of the themed issue ‘Toward the development of high-fidelity models of wall turbulence at large Reynolds number’.

1. Introduction

Wall turbulence plays a critical role in a wide range of engineering and physics problems. Despite the acknowledged importance of improving understanding of wall turbulence and an extensive literature recording advances in the study of this problem, fundamental aspects of wall turbulence remain unresolved. The enduring challenge of understanding turbulence can be partially attributed to the fact that the Navier–Stokes (NS) equations, which are known to govern its dynamics, are analytically intractable. Even though there has been a great deal of progress in simulating turbulence [1–6], a complete understanding of the physical mechanisms underlying turbulence remains elusive. This challenge has motivated the search for analytically simpler and computationally more tractable dynamical models that retain the fundamental mechanisms of turbulence while facilitating insights into the underlying dynamics and providing a simplified platform for computation. A statistical state dynamics (SSD) model comprising coupled evolution equations for a mean flow and a perturbation covariance provides a new framework for analysing the dynamics of wall turbulence. The restricted nonlinear (RNL) approximation in which the perturbation covariance is approximated using a finite number of realizations of the perturbation equation that share the same mean flow provides complementary tools for tractable computations.

The use of statistical variables is well accepted as an approach to analysing complex spatially and temporally varying fields arising in physical systems, and analysing observations and simulations of turbulent systems using statistical quantities is a common practice. However, it is less common to adopt statistical variables explicitly for expressing the dynamics of the turbulent system. An early attempt to exploit the potential of employing SSD directly to provide insights into the mechanisms underlying turbulence involved formal expansion of the equations in cumulants [7,8]. Despite its being an important conceptual advance, the cumulant method was subsequently restricted in application, in part owing to the difficulty of obtaining robust closure of the expansion when it was applied to homogeneous isotropic turbulence. Another familiar example of a theoretical application of SSD to turbulence is provided by the Fokker–Planck equation. Although this expression of SSD is insightful, attempting to use it to evolve high dimensional dynamical systems leads to intractable representations of the associated SSD. These examples illustrate one of the key reasons SSD methods have remained underexploited: the assumption that obtaining the dynamics of the statistical states is prohibitively difficult in practice. This perceived difficulty of implementing SSD to study systems of the type typified by turbulent flows has led to a focus on simulating individual realizations of state trajectories and then analysing the results to obtain an approximation to the assumed statistically steady probability density function of the turbulent state or to compile approximations to the statistics of variables. However, this emphasis on realizations of the dynamics has at least one critical limitation: it fails to provide insights into phenomena that are intrinsically associated with the dynamics of the statistical state, which is a concept distinct from the dynamics of individual realizations. While the role of multiscale cooperative phenomena involved in the dynamics of turbulence is often compellingly apparent in the statistics of realizations, the cooperative phenomena involved influence the trajectory of the statistical state of the system, the evolution of which is controlled by its SSD. For example, stability analysis of the SSD associated with barotropic and baroclinic beta-plane turbulence predicts a spontaneous formation of jets with the observed structure. These results are consistent with jet formation and maintenance observed in the atmospheres of the gaseous planets arising from an unstable mode of the SSD that has no

analytical counterpart in realization dynamics. This jet formation instability has clear connections to observed behaviour, so while jet formation is clear in realizations, it cannot be comprehensively understood within the framework of realization dynamics [9–14]. This example demonstrates how SSD can bring conceptual clarity to the study of turbulence. This clarification of concept and associated deepening of understanding of turbulence dynamics constitutes an important contribution of the SSD perspective.

In this work, we focus on the study of wall turbulence. The mean flow is taken to be the streamwise averaged flow [15], and the perturbations are the deviations from this mean. Restriction of the dynamics to the first two cumulants involves either parametrizing the third cumulant by stochastic excitation [16–18] or, as we adopt in this work, setting it to zero [14, 19–21]. Either of these closures retain only interaction between the perturbations and the mean while neglecting the perturbation–perturbation interactions. This results in nonlinear evolution equations for the statistical state of the turbulence comprising the mean flow and the second-order perturbation statistics. If the system being studied has sufficiently low dimension, these second-order perturbation statistics can be obtained from a time-dependent matrix Lyapunov equation corresponding to an infinite ensemble of realizations. Results obtained from studying jet formation in the two-dimensional turbulence of planetary atmospheres [9–14] and more recent results in which SSD methods were applied to study low Reynolds number wall turbulence [22] motivated further work in analysing and simulating turbulence by directly exploiting SSD methods and concepts as an alternative to the traditional approach of studying the dynamics of single realizations. However, an impediment to the project of extending SSD methods to higher Reynolds number turbulence soon became apparent: because the second cumulant is of dimension N^2 for a system of dimension N , direct integration of the SSD equations is limited to relatively low-resolution systems and therefore low Reynolds numbers. In this paper, the focus is on methods for extending application of the SSD approach by exploiting the RNL model, which has recently shown success in the study of a wide range of flows [19, 22–26]. The RNL model implementations of SSD comprise joint evolution of a coherent mean flow (first cumulant) and an ensemble approximation to the second-order perturbation statistics which is considered conceptually to be an approximation to the covariance of the perturbations (second cumulant), although this covariance is not explicitly calculated.

One reason the SSD modelling framework provides an appealing tool for studying the maintenance and regulation of turbulence is that RNL turbulence naturally gives rise to a ‘minimal realization’ of the dynamics [22, 24]. This ‘minimal realization’ does not rely on a particular Reynolds number or result from restricting the channel size, and therefore Reynolds number trends as well as the effects of increasing the channel size can be explored within the RNL framework [24]. A second advantage of the RNL framework is that it does not explicitly assume particular flow features, such as the roll and the streak, but rather captures the dynamics of these structures as part of the holistic turbulent dynamics [19].

2. A statistical state dynamics model for wall-bounded turbulence

Consider a parallel wall-bounded shear flow with streamwise direction x , wall-normal direction y , and spanwise direction z with respective channel extents in the streamwise, wall-normal and spanwise directions L_x , 2δ and L_z . The non-dimensional NS equations governing the dynamics assuming a uniform density incompressible fluid are

$$\partial_t \mathbf{u}^{\text{tot}} + \mathbf{u}^{\text{tot}} \cdot \nabla \mathbf{u}^{\text{tot}} = -\nabla p + \frac{\Delta \mathbf{u}^{\text{tot}}}{Re} - (\partial_x p_\infty) \hat{\mathbf{x}} + \mathbf{f}, \quad \text{with } \nabla \cdot \mathbf{u}^{\text{tot}} = 0, \quad (2.1)$$

where $\mathbf{u}^{\text{tot}}(\mathbf{x}, t)$ is the velocity field, $p(\mathbf{x}, t)$ is the pressure field, $\hat{\mathbf{x}}$ is the unit vector in the x -direction and \mathbf{f} is a divergence-free external excitation. In the non-dimensional equation (2.1), velocities have been scaled by the characteristic velocity of the laminar flow U_m , lengths by the characteristic length δ and time by δ/U_m , and $Re = U_m \delta / \nu$ is the Reynolds number with kinematic viscosity ν . The velocity scale U_m is specified according to the flow configuration of interest.

For example, (2.1) with no imposed pressure gradient (i.e. $(\partial_x p_\infty)\hat{\mathbf{x}}=0$), U_m equal to half the maximum velocity difference across a channel with walls at $y/\delta = \pm 1$ and boundary conditions $\mathbf{u}^{\text{tot}}(x, \pm 1, z) = \pm \hat{\mathbf{x}}$ describes a plane Couette flow. Equation (2.1) with a constant pressure gradient $\partial_x p_\infty$, a characteristic velocity scale U_m equal to the centreline or bulk velocity (for the laminar flow) with boundary conditions $\mathbf{u}^{\text{tot}}(x, \pm 1, z) = 0$ describes a Poiseuille (channel) flow. Throughout this work, we impose periodic boundary conditions in the streamwise and spanwise directions. We discuss how this equation can be used to represent a half-channel flow in §5.

Pressure can be eliminated from these equations, and non-divergence enforced using the Leray projection operator, $P_L(\cdot)$ [27]. Using the Leray projection, the NS, expressed in velocity variables, becomes:¹

$$\partial_t \mathbf{u}^{\text{tot}} + P_L \left(\mathbf{u}^{\text{tot}} \cdot \nabla \mathbf{u}^{\text{tot}} - \frac{\Delta \mathbf{u}^{\text{tot}}}{Re} \right) = \mathbf{f}. \quad (2.2)$$

Obtaining equations for the SSD of channel flow requires an averaging operator, denoted with angle brackets, $\langle \cdot \rangle$, which satisfies the Reynolds conditions:

$$\langle \alpha f + \beta g \rangle = \alpha \langle f \rangle + \beta \langle g \rangle, \langle \partial_t f \rangle = \partial_t \langle f \rangle, \langle \langle f \rangle g \rangle = \langle f \rangle \langle g \rangle, \quad (2.3)$$

where $f(\mathbf{x}, t)$ and $g(\mathbf{x}, t)$ are flow variables, and α, β are constants (cf. [28, section 3.1]). The SSD variables are the spatial cumulants of the velocity. In contrast to the SSD of homogeneous isotropic turbulence, the SSD of wall-bounded turbulence can be well approximated by retaining only the first two cumulants [22]. The first cumulant of the flow field is the mean velocity, $\mathbf{U} \equiv \langle \mathbf{u}^{\text{tot}} \rangle$, with components (U, V, W) , whereas the second is the covariance of the perturbation velocity, $\mathbf{u} = \mathbf{u}^{\text{tot}} - \mathbf{U}$, between two spatial points, \mathbf{x}_1 and \mathbf{x}_2 : $C_{ij}(1, 2) \equiv \langle u_i(\mathbf{x}_1, t) u_j(\mathbf{x}_2, t) \rangle$.

Averaging operators satisfying the Reynolds conditions include ensemble averages and spatial averages over coordinates. Spatial averages will be denoted by angle brackets with a subscript indicating the independent variable over which the average is taken, i.e. streamwise averages by $\langle \cdot \rangle_x = L_x^{-1} \int_0^{L_x} \cdot dx$ and averages in both the streamwise and spanwise by $\langle \cdot \rangle_{x,z}$. Temporal averages are indicated by an overline, $\bar{\cdot} = (1/T) \int_0^T \cdot dt$, with T sufficiently large.

An important consideration in the study of turbulence using SSD is choosing an averaging operator that isolates the primary coherent motions. The associated closure must also retain the interactions between the coherent mean and incoherent perturbation structures involved in the physical mechanisms underlying the turbulence dynamics. The detailed structure of the coherent components is critical in producing energy transfer from the externally forced flow to the perturbations, therefore retaining the nonlinearity and structure of the mean flow components is crucial. In contrast, nonlinearity and comprehensive structure information is not required to account for the role of the incoherent motions, and therefore the statistical information contained in the second cumulant is sufficient to capture the influence of the perturbations on the turbulence dynamics. Retaining the complete structure and dynamics of the coherent component while retaining only the necessary statistical correlation for the incoherent component results in a great practical as well as conceptual simplification.

In the case of wall-bounded shear flows, there is a great deal of experimental and analytical evidence indicating the prevalence and central role of streamwise elongated coherent structures [16,29–38]. It is of particular importance that the mean flow dynamics capture the interactions between streamwise elongated streak and roll structures associated with the self-sustaining process (SSP) [39–43]. Streamwise constant models [44–46], which implicitly simulate these structures, have been shown to capture mechanisms such as the nonlinear momentum transfer and associated increased wall shear stress characteristic of wall turbulence [15,47–49]. On the other hand, taking the mean over both homogeneous directions (x and z) does not capture the roll/streak SSP dynamics and this mean does not result in a second-order closure that maintains turbulence [40].

¹The Leray projection annihilates the gradient of a scalar field. For this reason the p_∞ term does not appear in the projected equations.

We therefore select $\mathbf{U} = \langle \mathbf{u}^{\text{tot}} \rangle_x$ as the first cumulant, which leads to a streamwise constant mean flow that captures the dynamics of coherent roll/streak structures. We define the streak component of this mean flow by $U_s \equiv U - \langle U \rangle_z$ and the corresponding streak energy density as

$$E_s = \int_{-1}^1 \frac{1}{2} \langle U_s^2 \rangle_z dy. \quad (2.4)$$

The streamwise mean velocities of the roll structures are obtained from V and W , and the roll energy density is defined as

$$E_r = \int_{-1}^1 \frac{1}{2} \langle V^2 + W^2 \rangle_z dy. \quad (2.5)$$

The energy of the incoherent motions is determined by the perturbation energy

$$E_p = \int_{-1}^1 \frac{1}{2} \langle \|\mathbf{u}\|^2 \rangle_{x,z} dy. \quad (2.6)$$

The perturbation or streamwise-averaged Reynolds stress components are here defined as $\tau_{ij} \equiv \langle u_i(\mathbf{x}, t) u_j(\mathbf{x}, t) \rangle_x \equiv C_{ij}(1, 1)$.

The external excitation, \mathbf{f} in (2.2), is assumed to be a temporally white noise process with zero mean which satisfies

$$\langle f_i(\mathbf{x}_1, t_1) f_j(\mathbf{x}_2, t_2) \rangle_\infty = \delta(t_1 - t_2) Q_{ij}(1, 2), \quad (2.7)$$

where $\langle \cdot \rangle_N$ indicates an ensemble average over N forcing realizations. The ergodic hypothesis is invoked to equate the ensemble mean, $\langle \cdot \rangle_\infty$, with the streamwise average, $\langle \cdot \rangle_x$. $\mathbf{Q}(1, 2)$ is the matrix covariance between points \mathbf{x}_1 and \mathbf{x}_2 . We assume that $\mathbf{Q}(1, 2)$ is homogeneous in both x and z , i.e. it is invariant to translations in x and z and therefore has the form $\mathbf{Q}(x_1 - x_2, y_1, y_2, z_1 - z_2)$.

Averaging (2.2), we obtain the equation for the first cumulant:

$$\partial_t \mathbf{U} = \mathbf{P}_L \left(-\mathbf{U} \cdot \nabla \mathbf{U} + \frac{1}{Re} \Delta \mathbf{U} \right) + \mathcal{L} \mathbf{C}. \quad (2.8)$$

In equation (2.8), the streamwise average Reynolds stress divergence $\mathbf{P}_L \langle (-\mathbf{u} \cdot \nabla \mathbf{u})_x \rangle$, which depends linearly on \mathbf{C} , has been expressed as $\mathcal{L} \mathbf{C}$ where \mathcal{L} is a linear operator.

At this point, it is important to note that the first cumulant is not set to zero, as is commonly done in the study of statistical closures for identifying equilibrium statistical states in homogeneous isotropic turbulence. In contrast to the case of homogeneous isotropic turbulence, retaining the dynamics of the mean flow, \mathbf{U} , is of paramount importance in the study of wall turbulence.

The second cumulant equation is obtained by differentiating $C_{ij}(1, 2) = \langle u_i(\mathbf{x}_1) u_j(\mathbf{x}_2) \rangle_x$ with respect to time and using the equations for the perturbation velocities:

$$\partial_t \mathbf{u} = \mathbf{A}(\mathbf{U}) \mathbf{u} + \mathbf{f} - \mathbf{P}_L (\mathbf{u} \cdot \nabla \mathbf{u} - \langle \mathbf{u} \cdot \nabla \mathbf{u} \rangle_x). \quad (2.9)$$

Under the ergodic assumption that streamwise averages are equal to ensemble means, we obtain

$$\partial_t C_{ij}(1, 2) = A_{ik}(1) C_{kj}(1, 2) + A_{jk}(2) C_{ik}(2, 1) + Q_{ij}(1, 2) + G_{ij}. \quad (2.10)$$

In (2.9), $\mathbf{A}(\mathbf{U})$ is the linearized operator governing the evolution of perturbations about the instantaneous mean flow, \mathbf{U} :

$$A(\mathbf{U})_{ij} u_j = \mathbf{P}_L \left(-\mathbf{U} \cdot \nabla u_i - \mathbf{u} \cdot \nabla U_i + \frac{1}{Re} \Delta u_i \right). \quad (2.11)$$

Notation $A_{ik}(1) C_{kj}(1, 2)$ indicates that operator \mathbf{A} operates on the velocity variable of \mathbf{C} at position 1, and similarly for $A_{jk}(2) C_{ik}(2, 1)$. The term \mathbf{G} in (2.10) is proportional to the third cumulant, so that the dynamics of the second cumulant is not closed.

The first SSD we wish to describe is referred to as the stochastic structural stability theory (S3T) system, and it is obtained by closing the cumulant expansion at second order either by assuming that the third cumulant term \mathbf{G} in (2.10) is proportional to a state-independent covariance homogeneous in x and z or by setting the third cumulant to zero. The former

is equivalent to parametrizing the term $\mathbf{P}_L(\mathbf{u} \cdot \nabla \mathbf{u} - \langle \mathbf{u} \cdot \nabla \mathbf{u} \rangle_x)$, representing the perturbation–perturbation interactions, in (2.9) by a stochastic excitation. This implies that the perturbation dynamics evolve according to

$$\partial_t \mathbf{u} = \mathbf{A}(\mathbf{U})\mathbf{u} + \sqrt{\varepsilon} \mathbf{f}, \quad (2.12)$$

where the stochastic term $\sqrt{\varepsilon} \mathbf{f}(\mathbf{x}, t)$, with spatial covariance $\varepsilon \mathbf{Q}(1, 2)$ (cf. (2.7)), parametrizes the endogenous third-order cumulant in addition to the exogenous external stochastic excitation, and ε is a scaling parameter. The covariance \mathbf{Q} can be normalized in energy, so that ε is a parameter indicating the amplitude of the stochastic excitation. Equations (2.8) and (2.12) define what will be referred to as the RNL dynamics. Under this parametrization, the perturbation nonlinearity responsible for the turbulent cascade in streamwise Fourier space has been eliminated. Consequently, the S3T system is

$$\partial_t \mathbf{U} = \mathbf{P}_L \left(-\mathbf{U} \cdot \nabla \mathbf{U} + \frac{1}{Re} \Delta \mathbf{U} \right) + \mathcal{L} \mathbf{C} \quad (2.13a)$$

and

$$\partial_t C_{ij}(1, 2) = A_{ik}(1)C_{kj}(1, 2) + A_{jk}(2)C_{ik}(1, 2) + \varepsilon Q_{ij}(1, 2). \quad (2.13b)$$

This is the ideal SSD for studying wall turbulence using second-order SSD.

Given that the full covariance evolution equation becomes too large to be directly integrated as the dimension of the dynamics rises with Reynolds number, a finite number of realizations, N , can be used to approximate the exact covariance evolution that results in the N member ensemble restricted nonlinear system (RNL _{N}):

$$\partial_t \mathbf{U} = \mathbf{P}_L \left(-\mathbf{U} \cdot \nabla \mathbf{U} + \frac{1}{Re} \Delta \mathbf{U} - \langle \langle \mathbf{u} \cdot \nabla \mathbf{u} \rangle_x \rangle_N \right) \quad (2.14a)$$

and

$$\partial_t \mathbf{u}_n = \mathbf{A}(\mathbf{U})\mathbf{u}_n + \sqrt{\varepsilon} \mathbf{f}_n, \quad (n = 1, \dots, N). \quad (2.14b)$$

The average $\langle \cdot \rangle_N$ in (2.14a) is obtained using an N -member ensemble of realizations of (2.14b) each of which results from a statistically independent stochastic excitation \mathbf{f}_n but which all share the same \mathbf{U} . When an infinite ensemble is used, the RNL _{∞} system is obtained which is equivalent to the S3T system (2.13). Remarkably, a single ensemble member often suffices to obtain a useful approximation to the covariance evolution, albeit with substantial statistical fluctuations. In the case $N = 1$, equation (2.14) can be viewed either as an approximation to the SSD or as a realization of RNL dynamics. When $N > 1$, it is only interpretable as an approximation to the SSD.

3. Using stochastic structural stability theory to obtain analytical solutions for turbulent states

Streamwise roll vortices and associated streamwise streaks are prominent features in transitional boundary layers [50]. The ubiquity of the roll and streak structures in these flows presents a problem, because the laminar state of these flows is linearly stable. However, because of the high non-normality of the NS dynamics linearized about a strongly sheared flow the roll/streak exhibits high transient growth providing an explanation for its arising from perturbations to the flow [51,52]. However, S3T reveals an alternative explanation: the roll/streak structure can be destabilized by systematic organization by the streak of the perturbation Reynolds stress associated with low levels of background turbulence [22]. Destabilization of the roll/streak can be traced to a universal positive feedback mechanism operating in turbulent flows: the coherent streak distorts the incoherent turbulence so as to induce ensemble mean perturbation Reynolds stresses that force streamwise mean roll circulations configured to reinforce the streak (cf. [22]). The resulting instability does not have analytical expression in eigenanalysis of the NS dynamics but it can be solved for by performing an eigenanalysis on the S3T system.

Consider a laminar plane Couette flow subjected to stochastic excitation that is statistically streamwise and spanwise homogeneous and has zero spatial and temporal mean. S3T predicts

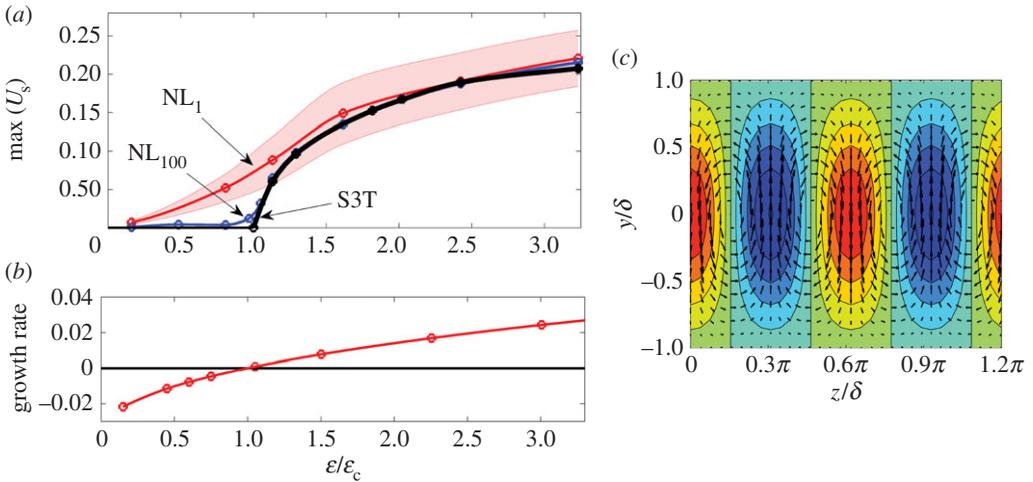


Figure 1. Analysis of roll/streak formation from a statistical state dynamics (SSD) bifurcation in a minimal channel plane Couette flow forced by background turbulence. (a) Streak amplitude, U_s , as a function of the stochastic excitation amplitude, ε , reveals the bifurcation as predicted by S3T (black) and the reflection of this prediction in an NL_1 simulation (red) and in an NL_{100} simulation (blue). The NL_1 simulations exhibit fluctuations from the analytically predicted roll/streak structure with 1 standard deviation of the fluctuations indicated by shading. The critical value, ε_c , is obtained from S3T stability analysis of the spanwise homogeneous state. The underlying S3T eigenmode is shown in (b) and its growth rate in (c). In (b), streak velocity, U_s , is indicated by contours and the velocity components (V, W) by vectors. At $\varepsilon = \varepsilon_c$, the S3T spanwise uniform equilibrium bifurcates to a finite amplitude equilibrium with perturbation structure close to that of the most unstable eigenfunction shown in (b). The channel is minimal with $L_x = 1.75\pi$ and $L_z = 1.2\pi$ [53], the Reynolds number is $Re = 400$ and the stochastic forcing excites only Fourier components with streamwise wavenumber $k_x = 2\pi/L_z = 1.143$. Numerical calculations employ $N_y = 21$ grid points in the wall-normal direction and 32 harmonics in the spanwise and streamwise directions (adapted from [54]). (Online version in colour.)

that a bifurcation occurs at a critical amplitude of excitation, ε_c , in which an unstable mode with roll/streak structure emerges (in the example, ε_c corresponds to an energy input rate that would sustain background turbulence energy of 0.14% of the laminar flow). As the excitation parameter, ε in (2.13b), is increased finite amplitude roll/streak structures equilibrate from this instability [22]. While these equilibria underlie the dynamics of roll/streak formation in the pre-transitional flow, they are imperfectly reflected in individual realizations (cf. [9,54]). One can compare this behaviour to that of the corresponding NS solutions by defining the N ensemble nonlinear system (NL_N) in analogy with the RNL_N in (2.14) as follows:

$$\partial_t \mathbf{U} = \mathbf{P}_L \left(-\mathbf{U} \cdot \nabla \mathbf{U} + \frac{1}{Re} \Delta \mathbf{U} - \langle \langle \mathbf{u} \cdot \nabla \mathbf{u} \rangle_x \rangle_N \right) \tag{3.1a}$$

and

$$\partial_t \mathbf{u}_n = \mathbf{A}(\mathbf{U}) \mathbf{u}_n + \sqrt{\varepsilon} \mathbf{f}_n - \mathbf{P}_L (\mathbf{u}_n \cdot \nabla \mathbf{u}_n - \langle \mathbf{u}_n \cdot \nabla \mathbf{u}_n \rangle_x), \quad (n = 1, \dots, N). \tag{3.1b}$$

Note that as $N \rightarrow \infty$ this system provides the second-order SSD of the NS without approximation. Figure 1 compares the analytical bifurcation structure predicted by S3T, the quasi-equilibria obtained using a single realization of the NS (NL_1) and the near-perfect reflection of the S3T bifurcation in a 100 member NS ensemble (NL_{100}) (cf. [22,54]).

With continued increase in ε a second bifurcation occurs in which the flow transitions to a chaotic time-dependent state. For the parameters used in our example, this second bifurcation occurs at $\varepsilon_t/\varepsilon_c = 5.5$. Once this time-dependent state is established, the stochastic forcing can be removed, and this state continues to be maintained as a self-sustaining turbulence. Remarkably, this self-sustaining turbulence naturally simplifies further by evolving to a minimal turbulent system in which the dynamics is supported by the interaction of the roll/streak structures with

a perturbation field comprising a small number of streamwise harmonics (as few as 1). This minimal self-sustaining turbulent system, which proceeds naturally from the S3T dynamics, reveals an underlying SSP that can be understood with clarity. The basic ingredient of this SSP is the robust tendency for streaks to organize the perturbation field so as to produce streamwise Reynolds stresses supporting the streak, as in the S3T instability mechanism shown in figure 1c. Although the streak is strongly fluctuating in the self-sustaining state, the tendency of the streak to organize the perturbation field is retained. It is remarkable that the perturbations, in this highly time-dependent state, produce torques that maintain the streamwise roll not only on average, but also at nearly every instant in time. As a result, in this self-sustaining state, the streamwise roll is systematically maintained by the robust organization of perturbation Reynolds stress by the time-dependent streak while the streak is maintained by the streamwise roll through the lift-up mechanism [22,23]. Through the resulting time-dependence of the roll/streak structure the constraint on instability imposed by the absence of inflectional instability in the mean flow is bypassed as the perturbation field is maintained by parametric growth [22,55].

4. Self-sustaining turbulence in a restricted nonlinear model

The previous sections demonstrated that the S3T system (2.13) provides an attractive theoretical framework for studying turbulence through analysis of its underlying SSD. However, this SSD has the perturbation covariance as a variable and its dimension, which is $O(N^2)$ for a system of dimension $O(N)$, means that it is directly integrable only for low-order systems. In this section, we demonstrate that this computational limitation to the extension of SSD to higher Re can be overcome by instead simulating the N ensemble member RNL_N (2.14), using a finite number of realizations of the perturbation field (2.14b). In particular, we perform computations for a plane Couette flow at $Re = 1000$, which show that a single realization ($N = 1$) suffices to approximate the ensemble covariance allowing computationally efficient studies of the dynamical restriction underlying the S3T dynamics. We then demonstrate that the single ensemble member RNL_1 (which we interchangeably refer to as the RNL system) reproduces self-sustaining turbulent dynamics that reproduce the key features of turbulent plane Couette flow at low Reynolds numbers. We show that in correspondence with the S3T results, RNL turbulence is supported by a perturbation field comprising only a few streamwise varying modes (harmonics or $k_x \neq 0$ Fourier components in a Fourier representation) and that its streamwise wavenumber support can be reduced to a single streamwise varying mode interacting with the streamwise constant mean flow.

We initiate turbulence in all of the RNL plane Couette flow simulations in this section by applying a stochastic excitation \mathbf{f} in (2.14b) over the interval $t \in [0, 500]$. We employ a similar procedure to initiate turbulence in the DNS, through \mathbf{f} in (2.1), and S3T simulations, through its spatial covariance $\mathbf{Q}(1, 2)$ in (2.13b). All results reported are for $t > 1000$, unless otherwise stated. The DNS results are obtained from the Channelflow NS solver [56,57], which is a pseudo-spectral code. The RNL simulations use a modified version of the same code. Complete simulation details are provided in [19].

A comparison of the velocity field obtained from S3T and RNL_1 simulations that have reached self-sustaining states (i.e. for $t > 1000$) is shown in figure 2a,b. These panels depict contour plots of an instantaneous snapshot of the streamwise component of the mean velocity with the vectors indicating velocity components (V, W) superimposed for the respective S3T and RNL flows at $Re = 600$ in a minimal channel; see the caption of figure 1 for the details. The same contour plot for a DNS is provided in figure 2c for comparison. These plots demonstrate the qualitative similarity in the structural features obtained from an S3T simulation, where the mean flow is driven by the full covariance, and the RNL simulation in which the covariance is approximated with a single realization of the perturbation field. Both flows also show good qualitative agreement with the DNS data.

Having established the ability of the RNL system to provide a good qualitative approximation of the S3T turbulent field, we now proceed to discuss the features of RNL turbulence. For this discussion, we move away from the minimal channel simulations at $Re = 600$ that were used to

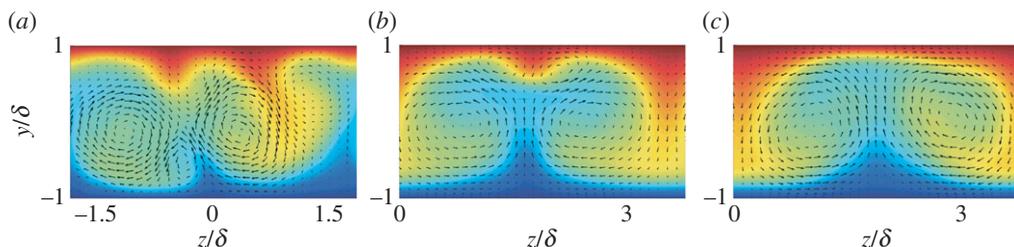


Figure 2. A y - z plane cross section of the flow (at $x = 0$) at a single snapshot in time for (a) an S3T simulation, (b) an RNL simulation and (c) DNS data. All panels show contours of the streamwise component of the mean flow U with the velocity vectors V, W superimposed. The RNL and S3T dynamics are self-sustaining for the time shown. (Online version in colour.)

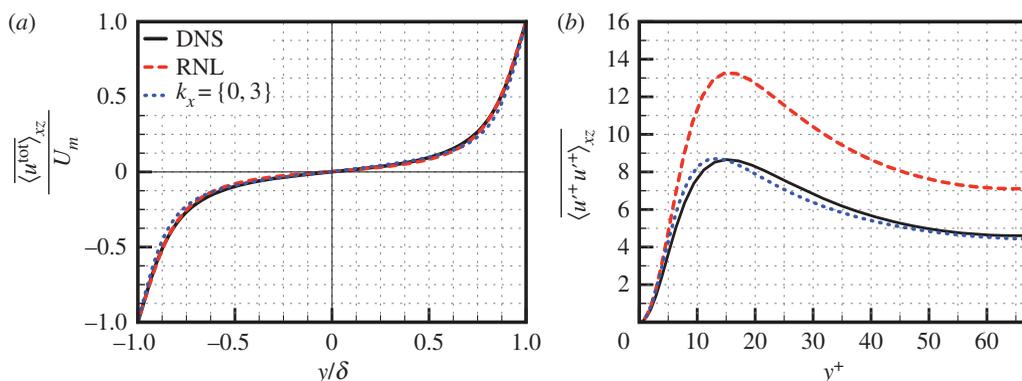


Figure 3. (a) Turbulent mean velocity profiles (based on streamwise, spanwise and time averages) in geometrical units obtained from the DNS (red solid line) and two RNL simulations; one with no band-limiting (black dashed line) and one where the streamwise wavenumber support is limited to $k_x = \{0, 3\}$ (blue dotted line). All at $Re = 1000$. (b) The corresponding Reynolds stresses $\langle u'^+u'^+ \rangle_{xz}$, where $u' = u^{\text{tot}} - \bar{u}^{\text{tot}}$ and $u^+ = u/u_\tau$. Adapted from [19]. (Online version in colour.)

facilitate comparison with the S3T equations and instead study plane Couette flow at $Re = 1000$ in a box with respective streamwise and spanwise extents of $L_x = 4\pi\delta$ and $L_z = 4\pi\delta$. The turbulent mean velocity profile obtained from a DNS and a RNL simulation under these conditions is shown in figure 3a, which illustrates good agreement between the two turbulent mean velocity profiles. Figure 3b shows the corresponding time-averaged Reynolds stress component, $\langle u'^+u'^+ \rangle_{xz}$, where the streamwise fluctuations, u' , are defined as $u' = u^{\text{tot}} - \bar{u}^{\text{tot}}$, $u^+ = u/u_\tau$ and $y^+ = (y + 1)u_\tau/\nu$ with friction velocity $u_\tau = \sqrt{\tau_w/\rho}$ (where τ_w is the shear stress at the wall), $Re_\tau = u_\tau\delta/\nu$ and $\nu = 1/Re$. The friction Reynolds numbers for the DNS data and the RNL simulation are, respectively, $Re_\tau = 66.2$ and $Re_\tau = 64.9$. Although they are not shown here, previous studies have also shown close agreement between the Reynolds shear stress $\langle u'v' \rangle_{xz}$ obtained from the RNL simulation and DNS [19], which is consistent with the fact that the turbulent flows supported by DNS and the RNL simulation exhibit nearly identical shear at the boundary, as seen in figure 3a. The close correspondence in the mean profiles in figure 3a, the $\langle u'v' \rangle_{xz}$ Reynolds stresses reported in [19], as well as in the close correspondence values of Re_τ in the RNL simulations and DNS indicate that the overall energy dissipation rates per unit mass $\mathcal{E} = \tau_w U/\delta$, where U/δ is a constant based on the velocity of the walls U and the half-height of the channel δ , also show close correspondence.

Figure 3b shows that the peak magnitude of the streamwise component of the time-averaged Reynolds stresses, $\langle u'^+u'^+ \rangle_{xz}$, is too high in the RNL simulation. Other second-order statistics, the premultiplied streamwise and spanwise spectra for this particular flow are presented in [19]. The discrepancies in both $\langle u'^+u'^+ \rangle_{xz}$ and the streamwise premultiplied spectra are a direct result of the dynamical restriction that leads to a reduced number of streamwise wave numbers that

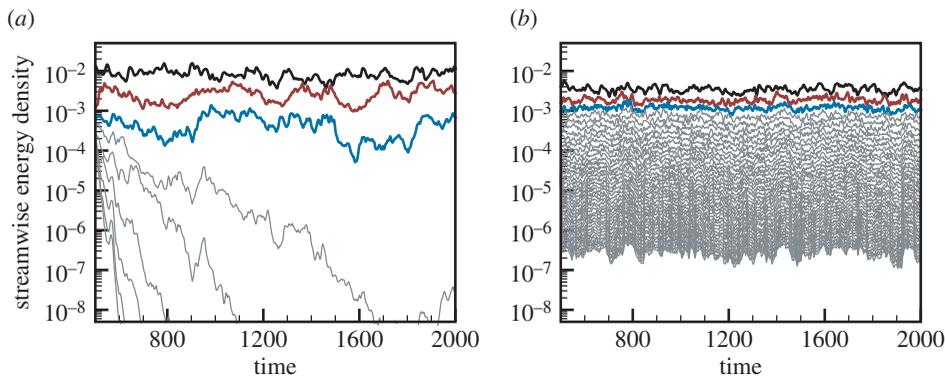


Figure 4. Streamwise energy densities for (a) a RNL simulation and (b) a DNS starting at $t = 500$, when the stochastic excitation was terminated. The energy densities of the streamwise varying perturbations that are supported in the RNL simulation are indicated in the following manner: $\lambda_1 = 4\pi\delta$ (black), $\lambda_2 = 2\pi\delta$ (red), $\lambda_3 = 4\pi\delta/3$ (blue). The modes that decay when the RNL is in a self-sustaining state are shown in grey in both panels. (Online version in colour.)

support RNL turbulence, which we discuss next. In particular, we demonstrate that when \mathbf{f} in equation (2.14b) is set to 0, the RNL model reduces to a minimal representation in which only a finite number of streamwise varying perturbations are maintained, whereas energy in the other streamwise varying perturbations decays exponentially. This resulting limited streamwise wavenumber support cannot and is not expected to accurately reproduce the entire streamwise spectra but instead captures the spectral components associated with the turbulent structures that are responsible for the SSP, i.e. those corresponding to the spanwise roll/streak structure.

In order to frame our discussion of the streamwise wavenumber support of RNL turbulence, we define a streamwise energy density associated with each perturbation wavenumber k_n ($n \neq 0$) based on the perturbation energy contained in structures at the associated streamwise wavelength λ_n as

$$E_{\lambda_n}(t) = \int_{-1}^1 \frac{1}{4} \langle \|\mathbf{u}_{\lambda_n}(y, z, t)\|^2 \rangle_z dy. \quad (4.1)$$

Here, \mathbf{u}_{λ_n} is the perturbation, $\mathbf{u} = (u, v, w)$, associated with Fourier components with streamwise wavelength λ_n .

Figure 4a,b shows the time evolution of the streamwise energy densities E_{λ_n} for a DNS and a RNL simulation, respectively. The simulations were both initiated with a stochastic excitation containing a full range of streamwise and spanwise Fourier components that was applied until $t = 500$. Figure 4a illustrates that the streamwise energy density of most of the modes in the RNL simulation decay once the stochastic excitation is removed. The decay of these modes is a result of the dynamical restriction not an externally imposed modal truncation. As a result, the self-sustaining turbulent behaviour illustrated in figure 3 is supported by only three streamwise varying modes. In contrast, all of the perturbation components remain supported in the DNS. This behaviour highlights an appealing reduction in model order in a RNL₁ simulation, which is consistent with the order reduction obtained when $N \rightarrow \infty$ [22].

We now demonstrate that RNL turbulence can be supported even when the perturbation dynamics (2.14b) is further restricted to a single streamwise Fourier component. This restriction to a particular wavenumber or set of wavenumbers is accomplished by slowly damping the other streamwise varying modes as described in [24]. We refer to a RNL₁ system that is truncated to a particular set of streamwise Fourier components as a band-limited RNL model and those with no such restriction as baseline RNL systems.

Thomas *et al.* [24] showed that band-limited RNL systems produce mean profiles and other structural features that are consistent with the baseline RNL system. Here we discuss only a subset of those results focusing on the particular case in which we keep only the $k_x = 3$ mode

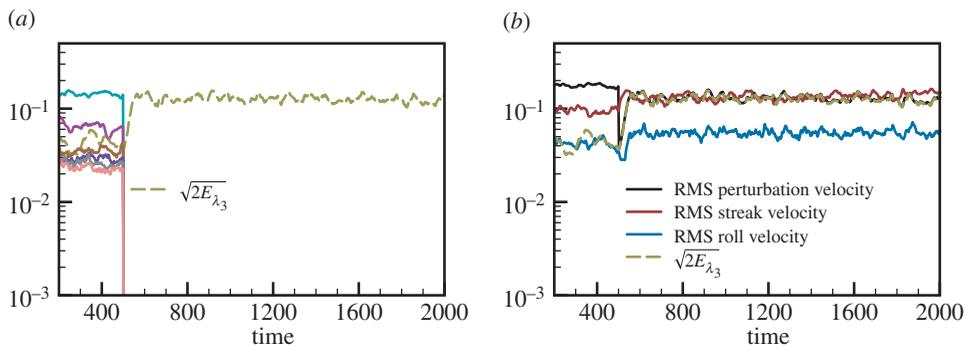


Figure 5. Sustaining turbulence with a single streamwise varying mode. (a) The RMS velocity associated with the streamwise energy density, $\sqrt{2E_{\lambda_n}}$, contained in each of the streamwise varying modes versus time before and after broad spectrum forcing is removed at $t = 500$. The remaining mode $k_x = 3$ ($\lambda_3 = 4\pi\delta/3$) is shown in gold. After the forcing is removed, the remaining mode increases its energy to compensate for the loss of the other modes. (b) $\sqrt{2E_{\lambda_n}}$ for the undamped wavelength along with the RMS perturbation velocity, U_{pert} , the RMS streak velocity, U_{streak} , and the RMS roll velocity, U_{roll} , for the same data as in (a). (Online version in colour.)

corresponding to $\lambda_x = 4\pi/3\delta$. Figure 5a shows the time evolution of the RMS velocity associated with the streamwise energy density, $\sqrt{2E_{\lambda_3}}$. Figure 5a begins just prior to the removal of the full spectrum stochastic forcing used to initialize the turbulence. At $t = 500$, all but the perturbations associated with streamwise wavenumber $k_x = 3$ are removed. It is interesting to note that once these streamwise wavenumbers are removed the energy density of the remaining mode increases to maintain the turbulent state. This behaviour can be further examined in the evolution of the RMS velocities of the streak, roll and perturbation energies over the same time period, which are respectively defined as $U_{\text{streak}} = \sqrt{2E_s}$, $U_{\text{roll}} = \sqrt{2E_r}$ and $U_{\text{pert}} = \sqrt{2E_p}$, where E_s , E_r and E_p are respectively defined in equations (2.4)–(2.6), shown in figure 5. Here, it is clear that after a small transient phase the roll and streak structures supported through the $k_x = 3$ perturbation field increase to the levels maintained by the larger number of perturbation components present prior to the band-limiting.

Figure 3b also shows that the streamwise component of the normal Reynolds stress obtained in this band-limited system shows better agreement with the DNS than does the baseline RNL system. This behaviour can be explained by looking at figure 5b, which shows that once the forcing is removed the total perturbation energy (as seen through U_{pert}) falls only slightly. This small drop is likely due to the removal of the forcing. This behaviour is consistent with observations that baseline and band-limited RNL simulations have approximately the same perturbation energy. The lower turbulent kinetic energy in figure 3b for the band-limited system can be attributed to the increase in dissipation that results from forcing the flow to operate with only the shorter wavelength (higher wavenumber) structures.

5. Restricted nonlinear turbulence at moderate Reynolds numbers

Section 4 demonstrates that the low-order statistics obtained from RNL₁ simulations of low Reynolds number plane Couette flow show good agreement with DNS data. We now discuss how the insight gained at low Reynolds numbers can be applied to simulations of half-channel flows at moderate Reynolds numbers. The half-channel flow NS equations are given by equation (2.1) with a constant pressure gradient $\partial_x p_\infty$, a characteristic velocity U_m equal to velocity at the top of the half-channel for the laminar flow, and the characteristic length δ equal to the full half-channel height. No-slip and stress-free boundary conditions are imposed at the respective bottom and top walls. As in the previous configurations periodic boundary conditions are imposed in the

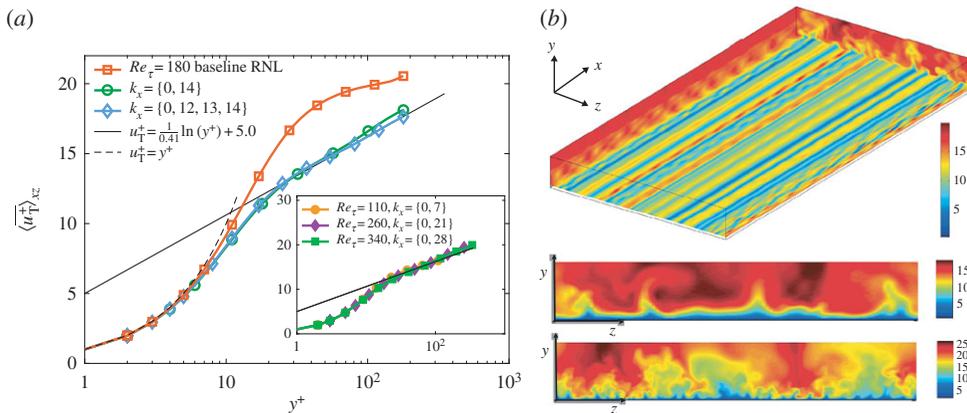


Figure 6. (a) Mean velocity profiles for baseline and band-limited RNL simulations at $Re_\tau = 180$ in the forefront, and band-limited simulations at $Re_\tau = 110, 260$ and 340 in the inset. (b) (Top) Snapshot of the streamwise velocity at a horizontal plane of $y^+ = 15$ for a band-limited RNL flow at $Re_\tau = 180$ with only $k_x = \{0, 12, 13, 14\}$. Cross-stream snapshots at $Re_\tau = 110$ (centre) and $Re_\tau = 340$ (bottom) with respective streamwise wavenumbers support sets of $k_x = \{0, 7\}$ and $k_x = \{0, 28\}$. This figure is adapted from [25], where the wavenumbers reported there have been rescaled so that $k_x = 1$ corresponds to $\lambda_x = 4\pi\delta$ in order to be consistent with the previous section. (Online version in colour.)

streamwise and spanwise directions. Further details regarding the half-channel simulations are provided in [25]. All results reported in this section are for $f = 0$.

Previous studies of RNL simulations in Pouseuille flow (a full channel) with $f = 0$ in (2.14b) have demonstrated that the accuracy of the mean velocity profile degrades as the Reynolds number is increased [23,26]. This deviation from the DNS mean velocity profile is also seen in simulations of a half-channel flow at $Re_\tau = 180$, as shown in figure 6a. However, the previously observed ability to modify the flow properties through band-limiting the perturbation field can be exploited to improve the accuracy of the RNL predictions. Mean velocity profiles from a series of band-limited RNL simulations at Reynolds numbers ranging from $Re_\tau = 180$ to $Re_\tau = 340$ in which the improved accuracy over baseline RNL simulations is clear are shown in figure 6a. In particular, the mean profiles over this Reynolds number range exhibit a logarithmic region with standard values of $\kappa = 0.41$ and $B = 5.0$. It should also be noted that many of these band-limited RNL simulations have perturbation fields that are supported by a single streamwise varying wavenumber, although figure 6 demonstrates that increasing the support to include a set of three adjacent $k_x \neq 0$ wavenumbers results in slightly improved statistics at $Re_\tau = 180$. Similar improvements are seen in the second-order statistics as reported in [25]. The specific wavenumbers to be retained in the model in order to produce the results shown here were determined empirically by comparing the skin friction coefficient of the band-limited RNL profiles and those obtained from a well-validated DNS [58]. That work demonstrated that the wavelength producing the best fit over the range of Reynolds numbers shown scales with Reynolds number and asymptotes to a value of approximately $\lambda_x = 150$ wall units. Preliminary work at higher Reynolds numbers has shown that this trend appears to continue to higher Reynolds numbers, although multiple wavenumbers (of the same approximate wavelength) may be needed. Developing the theory underlying this behaviour is a direction of continuing work.

Figure 6b shows snapshots of the streamwise velocity fields for three of the band-limited RNL flows shown in figure 6a. The top image in figure 6b shows a horizontal ($x - z$) plane snapshot of the streamwise velocity, u^{tot} , at $y^+ = 15$ at $Re_\tau = 180$, whereas the middle and bottom images depict cross plane ($y - z$) snapshots of the flow fields at $Re_\tau = 110$ and $Re_\tau = 340$, respectively. These images demonstrate realistic vortical structures in the cross-stream, whereas the band-limited nature of the streamwise-varying perturbations and the associated restriction to a particular set of streamwise wavelengths is clearly visible in the horizontal plane. The agreement

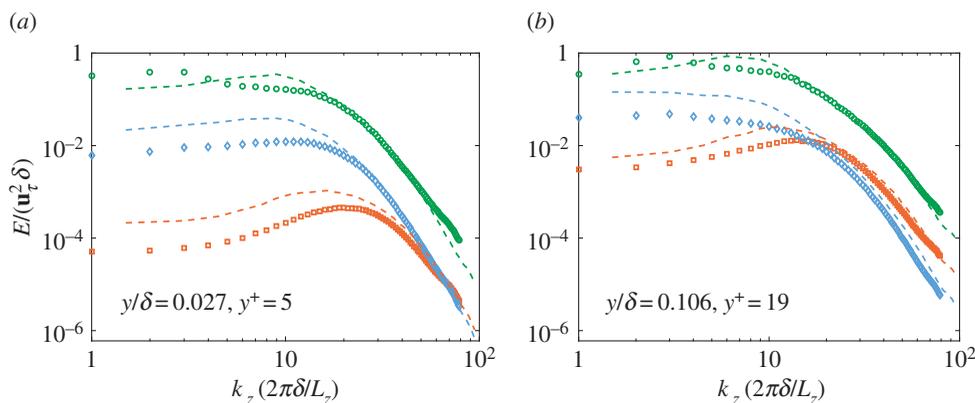


Figure 7. Spanwise energy spectra, E_{uu} (green circles), E_{vv} (red squares) and E_{ww} (blue diamonds), obtained from the band-limited RNL model at $Re_\tau = 180$, at two wall-normal locations. The RNL system is constrained to a single perturbation wavenumber of $k_x = 14$. Dashed lines are channel flow DNS data from Moser *et al.* [58]. Symbols are RNL data. Adapted from [25]. (Online version in colour.)

of the transverse spatial structure of the fluctuations can be quantified through the comparisons of the spanwise spectra with DNS shown in figure 7. Here we report results at two distances from the wall for the $Re_\tau = 180$ data for the band-limited RNL simulation supported by a perturbation field limited to $k_x = 14$ and a DNS at the same Reynolds number [58]. Although there are some differences in the magnitudes of the spectra, especially at low wavenumbers, the qualitative agreement is very good considering the simplicity of the RNL model compared with the NS equations. The benefit of the RNL approach is that these results are obtained at a significantly reduced computational cost.

6. Conclusion

Adopting the perspective of SSD provides not only new concepts and new methods for studying the dynamics underlying wall turbulence, but also provides new reduced-order models for simulating wall turbulence. The conceptual advance arising from SSD that we have reviewed here is the existence of analytical structures underlying turbulence dynamics that lack expression in the dynamics of realizations. The example we provided is that of the analytical unstable eigenmode and associated bifurcation structure associated with instability of the roll/streak structure in plane Couette flow, which has no analytical expression in the dynamics of realizations. The modelling advance that we reviewed is the naturally occurring reduction in order of RNL turbulence that allows construction of low-dimensional models for simulating turbulence. A RNL system with an infinite number of realizations, referred to as S3T, provides the conceptual advance, whereas the RNL approximation provides an efficient computational tool. The computational simplicity and the ability to band-limit the streamwise wavenumber support to improve simulation accuracy means that RNL simulations promise to provide a computationally tractable tool for probing the dynamics of high Reynolds number flows. In summary, the SSD perspective provides a new set of tools as well as new insights into wall turbulence.

Authors' contributions. The author order is alphabetical. Sections 1–3 were primarily written by B.F.F. and P.J.I. with input from D.F.G. Sections 4 and 5 were written by D.F.G. with input from B.F.F. and P.J.I.

Competing interests. We declare we have no competing interests.

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