John’s theorem for an arbitrary pair of convex bodies

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Abstract

We provide a generalization of John’s representation of the identity for the maximal volume position of \( L \) inside \( K \), where \( K \) and \( L \) are arbitrary smooth convex bodies in \( \mathbb{R}^n \). From this representation we obtain Banach-Mazur distance and volume ratio estimates.

1 Introduction

The definition of the Banach-Mazur distance between symmetric convex bodies can be extended to the non-symmetric case as follows [Gr]: Let \( K \) and \( L \) be two convex bodies in \( \mathbb{R}^n \). Their geometric distance is defined by

\[
\hat{d}(K, L) = \inf \{ ab : (1/b)L \subseteq K \subseteq aL \}.
\]

If \( z_1, z_2 \in \mathbb{R}^n \), we consider the translates \( K - z_1 \) and \( L - z_2 \) of \( K \) and \( L \), and their distance with respect to \( z_1, z_2 \),

\[
d_{z_1, z_2}(K, L) = \inf \{ \hat{d}(T(K - z_1), L - z_2) \},
\]

where the inf is taken over all invertible linear transformations \( T \) of \( \mathbb{R}^n \). Finally, we let \( z_1, z_2 \) vary and define

\[
d(K, L) = \inf \{ d_{z_1, z_2}(K, L) : z_1, z_2 \in \mathbb{R}^n \}.
\]

John’s theorem [J] provides a first estimate for \( d(K, L) \). If \( K \) is any convex body in \( \mathbb{R}^n \) and \( E \) is its maximal or minimal volume ellipsoid, then \( d_{z, z}(K, E) \leq n \), where \( z \) is the center of \( E \). Actually, the distance between the simplex and the ball is equal to \( n \), and the simplex is the only body with this property [P]. It follows that the distance between any two convex bodies is at most \( n^2 \). Rudelson [R] has recently proved that \( d(K, L) \leq cn^{1/3} \log^{5} n \) for some absolute constants \( c, \beta > 0 \) (see also
recent work of Litvak and Tomczak-Jaegermann [LTJ]. A well-known theorem of Gluskin [GI] shows that \( d(K, L) \) can be of the order of \( n \) even for symmetric bodies \( K \) and \( L \).

In this paper we study the \textit{maximal volume position} of a body \( L \) inside \( K \): we say that \( L \) is of maximal volume in \( K \) if \( L \subseteq K \) and, for every \( w \in \mathbb{R}^n \) and every volume preserving linear transformation \( T \) of \( \mathbb{R}^n \), the affine image \( w + T(L) \) of \( L \) is not contained in the interior of \( K \). A simple compactness argument shows that for every pair of convex bodies \( K \) and \( L \) there exists an affine image \( \tilde{L} \) of \( L \) which is of maximal volume in \( K \).

Our main result is the following:

**Theorem.** Let \( L \) be of maximal volume in \( K \). If \( z \in \text{int}(L) \), we can find contact points \( v_1, \ldots, v_m \) of \( K - z \) and \( L - z \), contact points \( u_1, \ldots, u_m \) of the polar bodies \( (K - z)^0 \) and \( (L - z)^0 \), and positive reals \( \lambda_1, \ldots, \lambda_m \), such that: \( \sum \lambda_j u_j = o \), \( \langle u_j, v_j \rangle = 1 \), and

\[
Id = \sum_{j=1}^{m} \lambda_j u_j \otimes v_j.
\]

(4)

We shall prove the above fact under the assumption that both \( K \) and \( L \) are smooth enough. The theorem may be viewed as a generalization of John’s representation of the identity even in the case where \( L \) is the Euclidean unit ball. This generalization was observed by V.D. Milman in the case where \( K \) and \( L \) are \( o \)-symmetric and \( z = o \) (see [TJ], Theorem 14.5).

Using the theorem, we give a direct proof of the fact that \( d(K, L) \leq n \) when both \( K \) and \( L \) are symmetric, and we obtain the estimate \( d(K, L) \leq 2n - 1 \) when \( L \) is symmetric and \( K \) is any convex body (this was recently proved by Lassak [L]).

Note that the theorem holds true for any choice of \( z \in \text{int}(L) \). In Section 3 we prove an extension to the case \( z \in \text{bd}(L) \). Also, assuming that \( L \) is a polytope and \( K \) has \( C^2 \) boundary with strictly positive curvature, we show that the center \( z \) may be chosen so that \( \sum \lambda_j u_j = o = \sum \lambda_j v_j \).

Using the maximal volume position of \( L \) inside \( K \), one can naturally extend the notion of \textit{volume ratio} to an arbitrary pair of convex bodies. We define

\[
\text{vr}(K, L) = \left( \frac{|K|}{|L|} \right)^{\frac{1}{n}},
\]

(5)

where \( \tilde{L} \) is an affine image of \( L \) which is of maximal volume in \( K \) (by \( | \cdot | \) we denote \( n \)-dimensional volume). In Section 4, we prove the following general estimate:

**Theorem.** Let \( K \) and \( L \) be two convex bodies in \( \mathbb{R}^n \). Then,

\[
\text{vr}(K, L) \leq n.
\]

(6)
The same estimate can be given through K. Ball’s result on $v_r(K, D_n)$ and $v_r(D_n, K)$, where $D_n$ is the Euclidean unit ball. Ball [Ba] proved that both $v_r(K, D_n)$ and $v_r(D_n, K)$ are maximal when $K$ is the simplex $S_n$. It follows that

$$v_r(K, L) \leq v_r(K, D_n)v_r(D_n, L) \leq v_r(S_n, D_n)v_r(D_n, S_n) = n.$$

However, our proof is direct and might lead to a better estimate; it might be true that $v_r(K, L)$ is always bounded by $c \sqrt{n}$.

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2 The main theorem and distance estimates

We assume that $\mathbb{R}^n$ is equipped with a Euclidean structure $\langle \cdot, \cdot \rangle$, and denote the corresponding Euclidean norm by $| \cdot |$. We write $D_n$ for the Euclidean unit ball, and $S^{n-1}$ for the unit sphere.

If $W$ is a convex body in $\mathbb{R}^n$ and $z \in \text{int}(W)$, we define the radial function $\rho_W(z, \cdot)$ of $W$ with respect to $z$ by

$$\rho_W(z, \theta) = \max \{ \lambda > 0 : z + \lambda \theta \in W \} \quad (1)$$

for $\theta \in S^{n-1}$, and extend this definition to $\mathbb{R}^n \backslash \{z\}$ by

$$\rho_W(z, x) = \frac{1}{t} \rho_W(z, \theta), \quad (2)$$

where $x = z + t\theta$, $t > 0$ and $\theta \in S^{n-1}$. If $\theta \in S^{n-1}$, we will write $\rho_W(z, \theta)$ instead of $\rho_W(z, z + \theta)$ (this will cause no confusion).

The polar body $W^\circ$ of $W$ with respect to $z \in \text{int}(W)$ is the body

$$W^\circ = (W - z)^\circ = \{ y \in \mathbb{R}^n : \langle y, x - z \rangle \leq 1 \text{ for all } x \in W \} \quad (3)$$

Let $o$ denote the origin. Since $\rho_W(z, x) = \rho_{W^\circ}(o, x - z)$, the support function $h_{W^\circ}$ of $W^\circ$ satisfies

$$h_{W^\circ}(x - z) = \frac{1}{\rho_W(z, x)} \quad (4)$$

for all $x \in \mathbb{R}^n \backslash \{z\}$. Note that the definition of the polar set $W^\circ$ makes sense for $z \in \text{bd}(W)$, but then $W^\circ$ may be unbounded in some directions.

Recall that, if $o \in \text{int}(W)$, $W$ is strictly convex and $h_W$ is continuously differentiable, then $\nabla h_W(\theta)$ is the unique point on the boundary of $W$ at which the outer unit normal to $W$ is $\theta$, and $\nabla h_W(\lambda \theta) = \nabla h_W(\theta)$ for all $\lambda > 0$.
With these definitions, we have the following description of the maximal volume position of $L$ in $K$:

**2.1. Lemma.** Let $K$ and $L$ be two convex bodies in $\mathbb{R}^n$, with $L \subseteq K$. Then, $L$ is of maximal volume in $K$ if and only if, for every $z \in L$, for every $w \in \mathbb{R}^n$ and every volume preserving $T$, there exists $\theta \in S^{n-1}$ such that

$$\rho_K(z, z + w + T(\rho_L(z, \theta)\theta)) \leq 1. \quad \square$$

We assume that $K$ is smooth enough: we ask that it is strictly convex and its support function $h_K$ is twice continuously differentiable. Under this assumption, we have that $h_{K^*}$ is twice continuously differentiable for every $z \in \text{int}(K)$.

**2.2. Lemma.** Let $L$ be of maximal volume in $K$, and $z \in L \cap \text{int}(K)$. Then, for every $w \in \mathbb{R}^n$ and every $S \in L(\mathbb{R}^n, \mathbb{R}^n)$ we can find $\theta \in S^{n-1}$ such that $\rho_L(z, \theta) = \rho_K(z, \theta)$ and

$$h_{K^*} \left( w + \rho_K(z, \theta)S(\theta) \right) \geq \frac{\text{tr}S}{n}.$$  

**Proof:** We follow the argument of [GM]. Let $w \in \mathbb{R}^n$ and $S \in L(\mathbb{R}^n, \mathbb{R}^n)$. If $\varepsilon > 0$ is small enough, then $T_{\varepsilon} = (I + \varepsilon S)/[\det(I + \varepsilon S)]^{1/n}$ is volume preserving, hence, using (4) and Lemma 2.1 for $T_{\varepsilon}$ and $\varepsilon w$, we find $\theta_{\varepsilon} \in S^{n-1}$ such that

$$h_{K^*} \left( \varepsilon w + T_{\varepsilon}(\rho_L(z, \theta_{\varepsilon})\theta_{\varepsilon}) \right) \geq 1.$$  

Since $[\det(I + \varepsilon S)]^{1/n} = 1 + \varepsilon \frac{\text{tr}S}{n} + O(\varepsilon^2)$, we get

$$h_{K^*} \left( \rho_L(z, \theta_{\varepsilon})\theta_{\varepsilon} + \varepsilon w + \varepsilon \rho_L(z, \theta_{\varepsilon})S(\theta_{\varepsilon}) \right) \geq 1 + \varepsilon \frac{\text{tr}S}{n} + O(\varepsilon^2).$$  

Since $L \subseteq K$, we have $h_{K^*}(\rho_L(z, \theta_{\varepsilon})\theta_{\varepsilon}) = \rho_L(z, \theta_{\varepsilon})/\rho_K(z, \theta_{\varepsilon}) \leq 1$, and the subadditivity of $h_{K^*}$ gives

$$h_{K^*} \left( w + \rho_L(z, \theta_{\varepsilon})S(\theta_{\varepsilon}) \right) \geq \frac{\text{tr}S}{n} + O(\varepsilon).$$  

By compactness, we can find $\varepsilon_m \to 0$ and $\theta \in S^{n-1}$ such that $\theta_{\varepsilon_m} \to \theta$. Then, taking limits in (9) we get

$$h_{K^*} \left( w + \rho_L(z, \theta)S(\theta) \right) \geq \frac{\text{tr}S}{n} + O(\varepsilon).$$

and taking limits in (7) we see that $h_{K^*}(\rho_L(z, \theta)\theta) \geq 1$, which forces $\rho_L(z, \theta) = \rho_K(z, \theta)$. \quad \square

Making one more step, we obtain the following condition:
2.3. **Lemma.** Let $L$ be of maximal volume in $K$, and $z \in L \cap \text{int}(K)$. Then, for every $w \in \mathbb{R}^n$ and every $T \in L(\mathbb{R}^n, \mathbb{R}^n)$ we can find $\theta \in S^{n-1}$ such that \( \rho_L(z, \theta) = \rho_K(z, \theta) \) and

\[
\langle \nabla h_{K^*}(\theta), w + \rho_K(z, \theta)T(\theta) \rangle \geq \frac{\text{tr}T}{n}.
\]

**Proof:** Let $T \in L(\mathbb{R}^n, \mathbb{R}^n)$, and define $S_\varepsilon = I + \varepsilon T$, $\varepsilon > 0$. By Lemma 2.2, we can find $\theta_\varepsilon \in S^{n-1}$ such that $\rho_K(z, \theta_\varepsilon) = \rho_L(z, \theta_\varepsilon)$ and

\[
\langle \nabla h_{K^*}(\theta_\varepsilon), w + \rho_K(z, \theta_\varepsilon)T(\theta_\varepsilon) \rangle \geq \frac{\text{tr}(I + \varepsilon T)}{n} = 1 + \varepsilon \frac{\text{tr}T}{n}.
\]

The left hand side is equal to

\[
\langle \nabla h_{K^*}(\theta_\varepsilon), w + \rho_K(z, \theta_\varepsilon)T(\theta_\varepsilon) \rangle \geq 1 + \varepsilon \langle \nabla h_{K^*}(\theta_\varepsilon), w + \rho_K(z, \theta_\varepsilon)T(\theta_\varepsilon) \rangle + O(\varepsilon^2).
\]

Therefore,

\[
\langle \nabla h_{K^*}(\theta_\varepsilon), w + \rho_K(z, \theta_\varepsilon)T(\theta_\varepsilon) \rangle \geq 1 + \varepsilon \frac{\text{tr}T}{n} + O(\varepsilon).
\]

Choosing again $\varepsilon_m \to 0$ such that $\theta_m \to \theta \in S^{n-1}$, we see that $\rho_K(z, \theta) = \rho_L(z, \theta)$ and $\theta$ satisfies (11). \( \square \)

**Lemma 2.3 and a separation argument give us a generalization of John's representation of the identity:**

2.4. **Theorem.** Let $K$ be smooth enough, $L$ be of maximal volume in $K$, and $z \in L \cap \text{int}(K)$. There exist $m \leq n^2 + n + 1$ vectors $\theta_1, \ldots, \theta_m \in S^{n-1}$ such that $\rho_K(z, \theta_j) = \rho_L(z, \theta_j)$ and $\lambda_1, \ldots, \lambda_m > 0$, such that:

(i) $\sum \lambda_j \nabla h_{K^*}(\theta_j) = 0$,

(ii) $Id = \sum \lambda_j [\nabla h_{K^*}(\theta_j)] \odot (\rho_K(z, \theta_j)\theta_j)$.

**Proof:** We identify the affine transformations of $\mathbb{R}^n$ with points in $\mathbb{R}^{n^2+n}$, and consider the set

\[
C = \text{co}\{ [\nabla h_{K^*}(\theta) \odot \rho_K(z, \theta)\theta] + \nabla h_{K^*}(\theta) : \theta \in S^{n-1}, \rho_K(z, \theta) = \rho_L(z, \theta) \}.
\]

Then, $C$ is a compact convex set with the Euclidean metric, and we claim that $Id/n \in C$. If not, there exist $w \in \mathbb{R}^n$ and $T \in L(\mathbb{R}^n, \mathbb{R}^n)$ such that

\[
\langle Id/n, T + w \rangle > \langle [\nabla h_{K^*}(\theta) \odot \rho_K(z, \theta)\theta] + \nabla h_{K^*}(\theta), T + w \rangle
\]

whenever $\rho_K(z, \theta) = \rho_L(z, \theta)$. But, (16) is equivalent to

\[
\frac{\text{tr}T}{n} > \langle \nabla h_{K^*}(\theta), w + \rho_K(z, \theta)T(\theta) \rangle.
\]

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and this contradicts Lemma 2.3.

Carathéodory’s theorem shows that we can find \( m \leq n^2 + n + 1 \) and positive reals \( \lambda_1, \ldots, \lambda_m \) such that

\[
    Id = \sum_{j=1}^{m} \lambda_j \left( [\nabla h_{K^z}(\theta_j)] \otimes \rho_{K}(z, \theta_j \theta_j) + \nabla h_{K^z}(\theta_j) \right),
\]

for \( \theta_1, \ldots, \theta_m \in S^{n-1} \) with \( \rho_{K}(z, \theta_j) = \rho_{L}(z, \theta_j) \). This completes the proof. \( \square \)

**Remark.** Assume that \( L \) is also smooth enough. Let \( \theta \in S^{n-1} \) be such that \( \rho_{K}(z, \theta) = \rho_{L}(z, \theta) \). Observe that

\[
    \langle \nabla h_{K^z}(\theta), \rho_{K}(z, \theta \theta) \rangle = \rho_{K}(z, \theta) h_{K^z}(\theta) = 1.
\]

Also, \( x = \nabla h_{L^z}(\theta) \) is the unique point of \( L^z \) for which \( \langle x, \theta \rangle = h_{L^z}(\theta) = h_{K^z}(\theta) \).

Since \( \langle \nabla h_{K^z}(\theta), \theta \rangle = h_{K^z}(\theta) \) and \( \nabla h_{K^z}(\theta) \in K^z \subseteq L^z \), we must have

\[
    \nabla h_{K^z}(\theta) = \nabla h_{L^z}(\theta).
\]

Hence, the theorem can be stated in the following form:

**2.5. Theorem.** Let \( K \) and \( L \) be smooth enough, and \( L \) be of maximal volume in \( K \). For every \( z \in \text{int}(L) \), we can find contact points \( v_1, \ldots, v_m \) of \( K - z \) and \( L - z \), contact points \( u_1, \ldots, u_m \) of \( K^z \) and \( L^z \), and positive reals \( \lambda_1, \ldots, \lambda_m \), such that:

\[
    \sum \lambda_j u_j = a, \quad \langle u_j, v_j \rangle = 1, \quad \text{and}
\]

\[
    Id = \sum_{j=1}^{m} \lambda_j u_j \otimes v_j. \quad \square
\]

**Remark.** The analogue of the Dvoretzky-Rogers lemma [DR] in the context of Theorem 2.5 is the following: If \( F \) is a \( k \)-dimensional subspace of \( \mathbb{R}^n \) and \( P_F \) denotes the orthogonal projection onto \( F \), then there exists \( j \in \{1, \ldots, m\} \) such that

\[
    \langle P_F(u_j), P_F(v_j) \rangle \geq \frac{k}{n}.
\]

This can be easily checked, since

\[
    k = \text{tr} P_F = \sum_{j=1}^{m} \lambda_j \langle P_F(u_j), P_F(v_j) \rangle,
\]

and \( \sum \lambda_j = n. \)

As an application of Theorem 2.4, we give a direct proof of the fact that the diameter of the Banach-Mazur compactum is bounded by \( n \):

**2.6. Proposition.** Let \( K \) and \( L \) be symmetric convex bodies in \( \mathbb{R}^n \). Then, \( d(K, L) \leq n. \)
Proof: We may assume that $K$ and $L$ satisfy our smoothness hypotheses, and that $K$ is symmetric about $o$. Let $L_1$ be an affine image of $L$ which is of maximal volume in $K$.

Claim: $L_1$ is also symmetric about $o$.

Let $z$ be the center of $L_1$. Then $L_1 = 2z - L_1 \subseteq K$ and the symmetry of $K$ shows that $L_1 - 2z \subseteq K$. It follows that

$$\tilde{L} = L_1 - z = \frac{L_1 + (L_1 - 2z)}{2} \subseteq K,$$

and $L_1 - z$ is $o$-symmetric. If $z \neq o$, we obtain a contradiction as follows: we define a linear map $T$ which leaves $z^\perp$ unchanged and sends $z$ to $(1 + \alpha)z$, where $0 < \alpha < |z|^2/h_{L_1 - z}(z)$. One can easily check that $T(L_1 - z) \subseteq \text{co}(L_1, L_1 - 2z) \subseteq K$ and $|T(L_1 - z)| = (1 + \alpha)|L_1| > |L_1|.$

We write $L$ for $L_1$. Let $x \in \mathbb{R}^n$ and choose $z = w = o$ and $T(y) = \langle \nabla h_{L^*}(x), y \rangle x$ in Lemma 2.3. Then there exists $\theta \in S^{n-1}$ such that $\rho_K(o, \theta) = \rho_L(o, \theta)$ and

$$\langle \nabla h_{K^*}(\theta), \nabla h_{L^*}(x), \rho_L(o, \theta) \theta \rangle x \geq \frac{h_{L^*}(x)}{n}.$$ 

But, $\nabla h_{L^*}(x) \in L^*$ and $\rho_L(o, \theta) \theta \in L$. Since $L$ is $o$-symmetric, we have

$$|\langle \nabla h_{L^*}(x), \rho_L(o, \theta) \theta \rangle| \leq 1.$$ 

Using now the $o$-symmetry of $K$ and the fact that $\nabla h_{K^*}(\theta) \in K^*$, from (23) and (24) we get

$$h_{K^*}(x) \geq \frac{h_{L^*}(x)}{n}.$$ 

Therefore, $L^* \subseteq nK^*$, and this shows that $K \subseteq nL$. \hfill \Box

We now assume that $L$ is symmetric and $K$ is any convex body.

2.7. Proposition. Let $L$ be a symmetric convex body and $K$ be any convex body in $\mathbb{R}^n$. Then, $d(K,L) \leq 2n - 1$.

Proof: We may assume that $L$ is of maximal volume in $K$ and $L$ is symmetric about $o$.

Let $d > 0$ be the smallest positive real for which $h_{L^*}(y) \leq dh_{K^*}(y)$ for all $y \in \mathbb{R}^n$. Then, duality, the symmetry of $L$ and the fact that $L \subseteq K$ show that $h_K(-x) \leq dh_L(-x) = dh_L(x) \leq dh_K(x)$ for every $x \in \mathbb{R}^n$.

We define $T(y) = \langle n\nabla h_{L^*}(x), y \rangle x$ and $w = \gamma x$, where $\gamma \in [0,n)$ is to be determined. From Lemma 2.3, there exists $\theta \in S^{n-1}$ such that $\rho_K(o, \theta) = \rho_L(o, \theta)$ and

$$\langle \nabla h_{K^*}(\theta), \gamma x + n\langle \nabla h_{L^*}(x), \rho_L(o, \theta) \theta \rangle x \rangle \geq \frac{n\langle \nabla h_{L^*}(x), x \rangle}{n} = h_{L^*}(x).$$

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Since \( \nabla h_{L^*}(x) \in L^\circ, \rho_L(o, \theta) \theta \in L \) and \( L \) is \( o \)-symmetric, we have
\[ |(\nabla h_{L^*}(x), \rho_L(o, \theta) \theta)| \leq 1, \]
therefore
\[ (27) \quad \gamma - n \leq \gamma + n(\nabla h_{L^*}(x), \rho_L(o, \theta) \theta) \leq \gamma + n. \]
Let \( s = (\nabla h_{L^*}(x), \rho_L(o, \theta) \theta) \). Since \( \nabla h_{K^*}(x) \in K^\circ \), from (26) and (27) we get
\[ (28) \quad h_{L^*}(x) \leq (\gamma + n)h_{K^*}(x), \]
if \( \gamma + ns \geq 0 \), and
\[ (29) \quad h_{L^*}(x) \leq (n - \gamma)dh_{K^*}(x), \]
if \( \gamma + ns < 0 \). It follows that
\[ (30) \quad h_{L^*}(x) \leq \max\{\gamma + n, (n - \gamma)d\}h_{K^*}(x). \]
This shows that \( d \leq \max\{\gamma + n, (n - \gamma)d\} \), and choosing \( \gamma = n(d - 1)/(d + 1) \) we get \( d \leq 2n - 1 \). Hence, \( L^\circ \subseteq (2n - 1)K^\circ \) and the result follows. \( \square \)

3 Choice of the center

In this section we study the case where \( L \) is a polytope with vertices \( v_1, \ldots, v_N \), and \( K \) has \( C^2 \) boundary with strictly positive curvature \( (K \in C^2_{\pm}) \). Then, we can strengthen Theorem 2.5 in the following sense:

3.1. Theorem. Let \( L \) be of maximal volume in \( K \). Then, there exists \( z \in L \setminus \{v_1, \ldots, v_N\} \) for which we can find \( \lambda_1, \ldots, \lambda_N \geq 0 \), and \( u_1, \ldots, u_N \in \text{bd}(K^z) \) so that:

1. \( \sum \lambda_j u_j = o, \quad \sum \frac{\lambda_j}{n} v_j = z. \)
2. \( (u_j, v_j - z) = 1 \) for all \( j = 1, \ldots, N. \)
3. \( Id = \sum_{j=1}^{N} \lambda_j u_j \otimes v_j. \)

Proof: We may assume that \( o \in \text{int}(L) \). By Theorem 2.4 and our hypotheses about \( K \), for every \( z \in L_0 := L \setminus \{v_1, \ldots, v_N\} \) there exist representations of the form
\[ Id = \sum_{j=1}^{N} \lambda_j u_j \otimes v_j, \]
where \( \lambda_j \geq 0, u_j \in \text{bd}(K^z) \) with \( (u_j, v_j - z) = 1 \), and \( \sum_{j=1}^{N} \lambda_j u_j = o \). Note that the representation of the identity follows from Theorem 2.4 because of the condition \( \sum_{j=1}^{N} \lambda_j u_j = o \).
We define a set-function $\phi$ on $L_0$, setting $\phi(z)$ to be the set of all points 
$(1/n) \sum_{j=1}^{N} \lambda_j v_j \in L$ which come from such representations (with respect to $z$).

The set $\phi(z)$ is clearly non-empty, convex and closed.

Let $s \in (0, 1)$. We define $\phi_s$ on $L_0$ with $\phi_s(z) = s\phi(z)$, and $g_s : L_0 \to \mathbb{R}^+$ with

$$(1) \quad g_s(z) = d(z, \phi_s(z)) = \inf\{|z - w| : w \in \phi_s(z)|. $$

It is easily checked that $\phi_s$ is upper semi-continuous and $g_s$ is lower semi-continuous.

3.2. Lemma. For every $s \in (0, 1)$, there exists $z \in sL$ such that $z \in \phi_s(z)$. 

Proof: Assume otherwise. Since $\phi_s(z) \subseteq sL$ for all $z \in L_0$, this means that $g_s(z) > 0$

on $L_0$. We set $r = (1 + s)/2$, and consider the restriction of $\phi_s$ onto $rL$. Since $g_s$

is lower-semicontinuous, there exists $q = q(r, s) > 0$ such that $g_s(z) \geq q$ for all $z \in rL$.

On the other hand, $\phi_s$ is upper-semicontinuous, convex-valued with bounded range. Therefore, $\phi_s$

admits approximate continuous selections: By a result of Beer [Be] (see also [RW], pp. 195), for every $\varepsilon > 0$ there exists a continuous function $h_\varepsilon : rL \to \mathbb{R}^n$ so that

$$(2) \quad d(h_\varepsilon(z), s\phi(z)) < \varepsilon. $$

Let $c = c(r, s) > 0$ be such that $sL + cD_n \subseteq rL$. Letting $\varepsilon = (1/2) \min\{q, c\}$ we find continuous $h : rL \to rL$ satisfying (2). Brower’s theorem shows that $h$ has a

fixed point $z \in rL$. But then,

$$q \leq d(z, s\phi(z)) = d(h(z), s\phi(z)) < \varepsilon,$$

which is a contradiction. This completes the proof. \hfill \Box

We apply Lemma 3.2 for a sequence $s_k \in (0, 1)$ with $s_k \to 1$. For each $k$ we find $z_k \in s_k L$ and $\lambda_j^{(k)} \geq 0$ such that

$$(3) \quad Id = \sum_{j=1}^{N} \lambda_j^{(k)} u_j^{(k)} \otimes v_j,$$

where $u_j^{(k)} \in \bd(K^{z_k})$ is uniquely determined by $\langle u_j^{(k)}, v_j - z_k \rangle = 1$, and

$$(4) \quad z_k = s_k \sum_{j=1}^{N} \frac{\lambda_j^{(k)}}{n} v_j + \sum_{j=1}^{N} \lambda_j^{(k)} u_j^{(k)} = o. $$

Passing to a subsequence, we may assume that $z_k \to z \in L$. If $z$ is not one of the

vertices of $L$, then $u_j^{(k)} \to u_j$, where $u_j \in \bd(K^z)$ and $\langle u_j, v_j - z \rangle = 1$. Passing to

further subsequences we may assume that $\lambda_j^{(k)} \to \lambda_j \geq 0$. Since $s_k \to 1$, (3) and

(4) imply

$$(5) \quad Id = \sum_{j=1}^{N} \lambda_j u_j \otimes v_j,$$

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and

\[(6) \quad z = \sum_{j=1}^{N} \frac{\lambda_j}{n} v_j, \quad \sum_{j=1}^{N} \lambda_j u_j = o.\]

This is exactly the assertion of the Theorem, provided that we have proved the following

**3.3. Claim.** Let \( s_k \in (0,1) \) with \( s_k \to 1 \), and \( z_k \in s_k \phi(z_k) \). If \( z_k \to z \), then \( z \notin \{v_1, \ldots, v_N \} \).

**Proof:** We assume that \( z_k \) satisfy (3) and (4) and \( z_k \to v_1 \). Our assumptions about \( K \) imply that \( K^{v_1} \) is unbounded only in the direction of \( N(v_1) \), where \( N(v_1) \) is the unit normal vector to \( K \) at \( v_1 \). For large \( k \), \( z_k \) is away from \( v_2, \ldots, v_N \), therefore \( u_j^{(k)} \to u_j, j = 2, \ldots, N \), where \( u_j \) is the unique point in \( \text{bd}(K^{v_1}) \) for which \( \langle u_j, v_j - z \rangle = 1 \).

Since \( (u_j^{(k)}) \), \( j \geq 2 \) is bounded and \( \sum_{j=1}^{N} \lambda_j = n \), (4) shows that

\[ |\lambda_j^{(k)} u_j^{(k)}| = \left| \sum_{j=2}^{N} \lambda_j^{(k)} u_j^{(k)} \right| \]

remains bounded. Hence, passing to a subsequence we may assume that \( \lambda_1^{(k)} u_1^{(k)} \to w_1 \), and \( \lambda_j^{(k)} \to \lambda_j \) for all \( j = 1, \ldots, N \). This means that

\[(7) \quad Id = w_1 \otimes v_1 + \sum_{j=2}^{N} \lambda_j u_j \otimes v_j,\]

and

\[(8) \quad v_1 = \sum_{j=1}^{N} \frac{\lambda_j}{n} v_j, \quad \lambda_1 u_1 = o.\]

Since \( v_1 \) is a vertex of \( L \), we must have \( \lambda_2 = \ldots = \lambda_N = 0 \). Then, \( w_1 = o \), and (7) takes the form \( Id = 0 \), which is a contradiction. \( \square \)

Actually, the argument we used for the proof of Claim 3.3 shows the following extension of Theorem 2.4:

**3.4. Proposition.** Let \( K, L \) be smooth enough and assume that \( L \) is of maximal volume inside \( K \). For every \( z \in \text{bd}(K) \cap \text{bd}(L) \), there exist \( m_0 \leq m \leq n^2 + n + 1 \), contact points \( v_1, \ldots, v_m \) of \( K \) and \( L \), contact points \( u_1, \ldots, u_m \) of \( K^z \) and \( L^z \), and non-negative numbers \( \lambda_1, \ldots, \lambda_m, \alpha_{m+1}, \ldots, \alpha_m \) so that:

1. \( \langle u_j, v_j - z \rangle = 1 \) for all \( j = 1, 2, \ldots, m_0 \),
2. \( \langle v_j N(z), v_j - z \rangle = 0 \) for all \( j = m_0 + 1, \ldots, m \),
3. \( Id = \sum_{j=1}^{m_0} \lambda_j u_j \odot v_j + N(z) \odot \left( \sum_{j=m_0+1}^m \alpha_j v_j \right), \)

where \( N(z) \) is the unit normal vector of \( K \) at \( z \).

**Sketch of the proof:** Let \( z \in \text{bd}(K) \cap \text{bd}(L) \), and consider a sequence \( z_k \in \text{int}(L) \) with \( z_k \to z \). Applying Theorem 2.4, for each \( k \) we find \( \lambda_j^{(k)} \geq 0 \), contact points \( v_j^{(k)} \) of \( K \) and \( L \), and contact points \( u_j^{(k)} \) of \( K^* \) and \( L^* \) so that \( \sum_{j=1}^n \lambda_j^{(k)} u_j^{(k)} = o \), \( \langle u_j^{(k)}, v_j^{(k)} - z_k \rangle = 1 \) and \( Id = \sum_{j=1}^N \lambda_j^{(k)} (u_j^{(k)} \odot v_j^{(k)}) \). We may assume that \( N = n^2 + n + 1 \) for all \( k \).

Passing to subsequences we may assume that \( \lambda_j^{(k)} \to \lambda_j \) and \( v_j^{(k)} \to v_j \) as \( k \to \infty \), where \( \lambda_j \geq 0 \) and \( v_j \) are contact points of \( K \) and \( L \). We may also assume that there exists \( m_0 \leq N \) such that \( u_j^{(k)} \to u_j \) if \( j \leq m_0 \), and \( |u_j^{(k)}| \to \infty \) if \( j > m_0 \).

Let \( N(z) \) be the unit normal vector to \( K \) at \( z \). It is not hard to see that for all \( j > m_0 \), the angle between \( u_j^{(k)} \) and \( N(z) \) tends to zero as \( k \to \infty \). Using the fact that \( \sum_{j=1}^N \lambda_j^{(k)} u_j^{(k)} = o \), we then see that for large \( k \)

\[
\max_{j > m_0} |\lambda_j^{(k)} u_j^{(k)}| \leq \sum_{j > m_0} |\lambda_j^{(k)} u_j^{(k)}| = \sum_{j \leq m_0} |\lambda_j^{(k)} u_j^{(k)}|,
\]

and this quantity remains bounded, since all \( \lambda_j^{(k)} \) and \( u_j^{(k)} \) \((j \leq m_0)\) converge. Therefore, we may also assume that \( \lambda_j^{(k)} u_j^{(k)} \to \alpha_j N(z), j > m_0 \).

Passing to the limit we check that \( \langle u_j, v_j - z \rangle = 1, j \leq m_0 \), and

\[
Id = \sum_{j=1}^{m_0} \lambda_j u_j \odot v_j + N(z) \odot \left( \sum_{j=m_0+1}^N \alpha_j v_j \right).
\]

Finally, \( \langle \alpha_j N(z), v_j - z \rangle \lim_k \lambda_j^{(k)} (u_j^{(k)}, v_j^{(k)} - z_k) = \lim_k \lambda_j^{(k)} = 0 \) for all \( j > m_0 \), and \( \sum_{j=1}^{m_0} \lambda_j u_j + \left( \sum_{j=m_0+1}^N \alpha_j \right) N(z) = o \). Ignoring all \( j \)'s for which \( \alpha_j = 0 \), we conclude the proof. \( \square \)

4 **Volume ratio**

In this Section we give an estimate for the volume ratio of two convex bodies:

4.1 **Theorem.** Let \( L \) be of maximal volume in \( K \). Then, \( (|K|/|L|)^{1/n} \leq n \).

**Proof:** Without loss of generality we may assume \( L \) is a polytope and \( K \in C^2_\mathbb{R} \), and using Theorem 3.1 we may assume that \( o \in L \cap \text{int}(K) \), and

\[
Id = \sum_{j=1}^m \lambda_j u_j \odot v_j.
\]
where \( \lambda_j > 0, u_1, \ldots, u_m \in \text{bd}(K), v_1, \ldots, v_m \) are contact points of \( K \) and \( L \), 
\[ \langle u_j, v_j \rangle = 1, \text{ and } \sum_{j=1}^{m} \lambda_j u_j = o = \sum_{j=1}^{m} \lambda_j v_j. \] 
This last condition shows that \( m \geq n + 1 \).

Since \( u_j \in K, j = 1, \ldots, m \), we have the inclusion
\[
(2) \quad K \subseteq U := \{ x : \langle x, u_j \rangle \leq 1, j = 1, \ldots, m \}.
\]

Observe that \( U \) is a convex body, because \( \sum \lambda_j u_j = o \). On the other hand, \( v_j \in L \),
\( j = 1, \ldots, m \). Therefore,
\[
(3) \quad L \supseteq V := \text{co}\{v_1, \ldots, v_m\}.
\]

It follows that
\[
(4) \quad \frac{|K|}{|L|} \leq \frac{|U|}{|V|}.
\]

We define \( \hat{v}_j \in \mathbb{R}^{n+1} \) by
\[
(5) \quad \hat{v}_j = \frac{n}{n+1}(-v_j, 1), \quad j = 1, \ldots, m.
\]

Then, we can estimate \( |V| \) using the reverse form of the Brascamp-Lieb inequality (see [Bar]):

4.2. Lemma. Let
\[
D_\hat{v} = \inf \left\{ \frac{\det \left( \sum_{j=1}^{m} \lambda_j \alpha_j v_j \otimes v_j \right)}{\prod_{j=1}^{m} \alpha_j^{\lambda_j}} : \alpha_j > 0, \ j = 1, 2, \ldots, m \right\}.
\]

Then, the volume of \( V \) satisfies the inequality
\[
(6) \quad |V| \geq \left( \frac{n+1}{n} \right)^{n+1} \frac{\sqrt{D_\hat{v}}}{n!}.
\]

Proof: Let
\[
N_V(x) = \begin{cases} 
\inf \left\{ \sum_{i=1}^{m} \alpha_i : \alpha_i \geq 0 \text{ and } x = \sum_{i=1}^{m} \alpha_i \hat{v}_i \right\}, & \text{if such } \alpha_i \text{ exist} \\
+\infty, & \text{otherwise.}
\end{cases}
\]

Let also \( C = \text{co}\{-v_1, -v_2, \ldots, -v_m\} \).

Claim: If \( x = (y, r) \) for some \( y \in \mathbb{R}^n \) and \( r \in \mathbb{R} \), then
\[
(7) \quad e^{-N_V(x)} \leq \chi_{\{y \in C\}} \chi_{\{r \geq 0\}} e^{-\frac{n}{n+1} r}.
\]
[If \( r < 0 \) then \( N_V(x) = +\infty \) and the inequality is true. Otherwise, let \( \alpha_i \geq 0 \) be such that \( x = \sum_{i=1}^{m} \alpha_i \tilde{v}_i \) and \( \sum_{i=1}^{m} \alpha_i = N_V(x) \). Then, it is immediate that \( N_V(x) = \frac{n+1}{n} r \geq 0 \) and \( y = \frac{n+1}{n} \sum_{i=1}^{m} \alpha_i (-\tilde{v}_i) \in r\mathcal{C} \). From this (7) follows.]

Integrating the inequality (7) we get

\[
\int_{\mathbb{R}^{n+1}} e^{-N_V(x)} \, dx \leq n! \left( \frac{n}{n+1} \right)^{n+1} |V|.
\]

We now set \( d_j = \frac{n+1}{n} \lambda_j \) and apply the reverse form of the Brascamp-Lieb inequality to the left hand side integral:

\[
\int_{\mathbb{R}^{n+1}} e^{-N_V(x)} \, dx = \int_{\mathbb{R}^{n+1}} \sup_{x = \sum_{j=1}^{m} \alpha_j \tilde{v}_j} \prod_{j=1}^{m} e^{-\alpha_j} \, dx
\]
\[
= \int_{\mathbb{R}^{n+1}} \sup_{x = \sum_{j=1}^{m} \alpha_j \tilde{v}_j} \prod_{j=1}^{m} \left( e^{-\alpha_j/d_j} \chi_{\{\alpha_j > 0\}} \right)^{d_j}
\]
\[
\geq \sqrt{D_\mathcal{V}} \prod_{j=1}^{m} \left( \int_{0}^{\infty} e^{-t} \, dt \right)^{d_j} = \sqrt{D_\mathcal{V}}.
\]

From this (6) follows. \( \square \)

We now turn to find an upper bound for \( |U| \): as above, let \( d_j = \frac{n+1}{n} \lambda_j \) and set \( \hat{u}_j = (-u_j, \frac{1}{n}) \) for \( j = 1, \ldots, m \).

**4.3. Lemma.** The volume of \( U \) satisfies the inequality

\[
|U| \leq \frac{1}{\sqrt{D_\mathcal{U}}} \frac{(n+1)^{n+1}}{n!},
\]

where

\[
D_\mathcal{U} = \inf \left\{ \frac{\det (\sum_{j=1}^{m} \alpha_j \hat{u}_j \otimes \hat{u}_j)}{\prod \alpha_j^{d_j}} ; \alpha_j > 0 \right\}.
\]

**Proof:** We apply the Brascamp-Lieb inequality [BL] (see also [Bar]) in the spirit of K. Ball’s proof of the fact that among all convex bodies having the Euclidean unit ball as their ellipsoid of maximal volume, the regular simplex has maximal volume [Ba].

For each \( j = 1, \ldots, m \), define \( f_j : \mathbb{R} \to [0, \infty) \) by \( f_j(t) = e^{-t} \chi_{[0,\infty)}(t) \), and set

\[
F(x) = \prod_{j=1}^{m} f_j(\langle \hat{u}_j, x \rangle)^{d_j}, \quad x \in \mathbb{R}^{n+1}.
\]
The Brascamp-Lieb inequality gives

\[
\int_{\mathbb{R}^{n+1}} F(x) dx = \frac{1}{\sqrt{D_a}} \prod_{j=1}^{m} \left( \int_{\mathbb{R}} f_j \right)^{d_j} = \frac{1}{\sqrt{D_a}}
\]

As in [Ba], writing \( x = (y, r) \in \mathbb{R}^n \times \mathbb{R} \), we see that \( F(x) = 0 \) if \( r < 0 \). When \( r \geq 0 \), we have \( F(x) \neq 0 \) precisely when \( y \in (r/n) U \), and then, taking into account the facts that \( \sum \lambda_j u_j = o \) and \( \sum d_j = n + 1 \), we see that \( F \) is independent of \( y \) and equal to

\[
F(x) = \exp(-r(n+1)/n).
\]

It follows from (11) that

\[
\frac{1}{\sqrt{D_a}} \geq \int_0^\infty \exp(-r(n+1)/n) \left( \frac{r}{n} \right)^n |U| dr = |U| \frac{n/n}{(n+1)^{n+1}}.
\]

Combining the two lemmata, we get

\[
\frac{|K|}{|F|} \leq \frac{n^n}{\sqrt{D_a D_b}}.
\]

Observe that \( \tilde{u}_j, \tilde{v}_j \) and \( d_j \) satisfy \( \langle \tilde{u}_j, \tilde{v}_j \rangle = 1 \), \( j = 1, \ldots, m \). Using the fact that \( \sum_{j=1}^{m} \lambda_j u_j = o = \sum_{j=1}^{m} \lambda_j v_j \), we check that

\[
Id = \sum_{j=1}^{m} d_j \tilde{u}_j \otimes \tilde{v}_j.
\]

Thus, in order to finish the proof of Theorem 4.1 it suffices to prove the following proposition.

**4.4. Proposition.** Let \( \lambda_1, \ldots, \lambda_m > 0, u_1, \ldots, u_m \) and \( v_1, \ldots, v_m \) be vectors satisfying \( \langle u_j, v_j \rangle = 1 \) for all \( j = 1, \ldots, m \) and

\[
Id = \sum_{j=1}^{m} \lambda_j u_j \otimes v_j.
\]

Then \( D_a D_b \geq 1 \).

**Proof:** For \( I \subseteq \{1, 2, \ldots, m\} \) we use the notation \( \lambda_I = \prod_{i \in I} \lambda_i, \alpha_I = \prod_{i \in I} \alpha_i \), and for \( I \)’s with cardinality \( n \), we write \( U_I = \det (u_i : i \in I) \) and \( V_I = \det (v_i : i \in I) \). Moreover, we write \( (\lambda U)_I \) for \( \det (\lambda_i u_i : i \in I) \). Applying the Cauchy-Binet formula we have

\[
\det \left( \sum_{j=1}^{m} \lambda_j \alpha_j u_j \otimes v_j \right) = \sum_{I \subseteq \{1, 2, \ldots, m\}} \alpha_I (\sqrt{\lambda} U)_I (\sqrt{\lambda} V)_I.
\]
But \( \sum (\sqrt[\lambda]{U})_I (\sqrt[\lambda]{V})_I = \det \left( \sum_{j=1}^{m} \lambda_j u_j \otimes v_j \right) = \det (I d) = 1 \). Hence, applying the arithmetic-geometric means inequality to the right side of (16) we deduce that

\[
\sum_{I \subseteq \{1, \ldots, m\}} \alpha_I (\sqrt[\lambda]{U})_I (\sqrt[\lambda]{V})_I \geq \prod_{I \subseteq \{1, \ldots, m\}} \alpha_I (\sqrt[\lambda]{U})_I (\sqrt[\lambda]{V})_I
\]

\[
= \prod_{j=1}^{m} \alpha_j \sum_{I \subseteq \{1, \ldots, m\}} (\sqrt[\lambda]{U})_I (\sqrt[\lambda]{V})_I
\]

Observe now that the exponent of \( \alpha_j \) in the above product equals \( \lambda_j \):

\[
\sum_{j \in I, |I|=n} (\sqrt[\lambda]{U})_I (\sqrt[\lambda]{V})_I = \sum_{|I|=n} (\sqrt[\lambda]{U})_I (\sqrt[\lambda]{V})_I - \sum_{j \notin I, |I|=n} (\sqrt[\lambda]{U})_I (\sqrt[\lambda]{V})_I
\]

\[
= \det \left( \sum_{j=1}^{m} \lambda_j u_j \otimes v_j \right) - \det (I - \lambda_j u_j \otimes v_j)
\]

\[
= \lambda_j,
\]

since \( \langle u_j, v_j \rangle = 1 \). Thus, we have shown that

(17) \[
\det \left( \sum_{j=1}^{m} \lambda_j u_j \otimes v_j \right) \geq \prod_{j=1}^{m} \alpha_j^{\lambda_j}.
\]

Now, for any \( \gamma_j, \delta_j \geq 0 \) we have

\[
\det \left( \sum_{j=1}^{m} \lambda_j \gamma_j u_j \otimes u_j \right) \det \left( \sum_{j=1}^{m} \lambda_j \delta_j v_j \otimes v_j \right)
\]

\[
= \sum_{|I|=n} \gamma_I \sqrt[\lambda_I]{U_I} \sum_{|I|=n} \delta_I \sqrt[\lambda_I]{V_I}
\]

By the Cauchy-Schwarz inequality this is greater than

\[
\left( \sum_{|I|=n} \lambda_I \sqrt[\lambda_I]{U_I} \right)^2.
\]

Apply now (17) to get

\[
\frac{\det \left( \sum_{j=1}^{m} \lambda_j \gamma_j u_j \otimes u_j \right) \det \left( \sum_{j=1}^{m} \lambda_j \delta_j v_j \otimes v_j \right)}{\prod_{j=1}^{m} \gamma_j^{\lambda_j} \delta_j^{\lambda_j}} \geq 1,
\]

completing the proof. \( \square \)
**Remark.** A different argument shows that \( \varrho(K, S_n) \leq c \sqrt{n} \) for every convex body \( K \) in \( \mathbb{R}^n \), where \( c > 0 \) is an absolute constant.

Without loss of generality we may assume that \( K \) is of maximal volume in \( D_n \). Then, John’s theorem gives us \( \lambda_1, \ldots, \lambda_m > 0 \) and contact points \( u_1, \ldots, u_m \) of \( K \) and \( D_n \), such that

\[
Id = \sum_{j=1}^{m} \lambda_j u_j \otimes u_j.
\]

The Dvoretzky-Rogers lemma [DR] shows that we can choose \( u_1, \ldots, u_n \) among the \( u_j \)'s so that

\[
|P_{\text{span}\{u_i, i < t\}} \setminus u_i| \geq \left( \frac{n - i + 1}{n} \right)^{1/2}, \quad i = 2, \ldots, n.
\]

Therefore, the simplex \( S = \text{co}\{o, u_1, \ldots, u_n\} \) has volume

\[
|S| \geq \frac{1}{n!} \prod_{i=2}^{n} \left( \frac{n - i + 1}{n} \right)^{1/2} \geq \frac{1}{n! (n^n)^{1/2}},
\]

and \( S \subseteq K \subseteq D_n \). It follows that

\[
\varrho(K, S_n) \leq \left( \frac{|D_n|}{|S|} \right)^{1/n} \leq \left( \frac{n!}{(n^n)^{1/2}} \right)^{1/n} \leq c \sqrt{n}.
\]

This supports the question if \( \varrho(K, L) \) is always bounded by \( c \sqrt{n} \).

**References**


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