# Series expansion for $L^{p}$ Hardy inequalities 

G. Barbatis ${ }^{1} \quad$ S. Filippas ${ }^{1}$ \& A. Tertikas ${ }^{2,3}$<br>Department of Applied Mathematics ${ }^{1}$ University of Crete, 71409 Heraklion, Greece gbarbati@tem.uoc.gr, filippas@tem.uoc.gr<br>Department of Mathematics ${ }^{2}$<br>University of Crete, 71409 Heraklion, Greece tertikas@tem.uoc.gr<br>Institute of Applied and Computational Mathematics ${ }^{3}$, FORTH, 71110 Heraklion, Greece


#### Abstract

We consider a general class of sharp $L^{p}$ Hardy inequalities in $\mathbb{R}^{N}$ involving distance from a surface of general codimension $1 \leq k \leq N$. We show that we can succesively improve them by adding to the right hand side a lower order term with optimal weight and best constant. This leads to an infinite series improvement of $L^{p}$ Hardy inequalities. AMS Subject Classification: 35J20 26D10 (46E35 35P) Keywords: Hardy inequalities, best constants, distance function, weighted norms


## 1 Introduction

Let $\Omega$ be a bounded domain in $\mathbb{R}^{N}$ containing the origin. Hardy inequality asserts that for any $p>1$

$$
\begin{equation*}
\int_{\Omega}|\nabla u|^{p} d x \geq\left|\frac{N-p}{p}\right|^{p} \int_{\Omega} \frac{|u|^{p}}{|x|^{p}} d x, \quad u \in C_{c}^{\infty}(\Omega \backslash\{0\}) \tag{1.1}
\end{equation*}
$$

with $\left|\frac{N-p}{p}\right|^{p}$ being the best constant, see for example $[\mathrm{HLP}],[\mathrm{OK}],[\mathrm{DH}]$. An analogous result asserts that for a convex domain $\Omega \subset \mathbb{R}^{N}$ with smooth boundary, and $d(x)=$ $\operatorname{dist}(x, \partial \Omega)$, there holds

$$
\begin{equation*}
\int_{\Omega}|\nabla u|^{p} d x \geq\left(\frac{p-1}{p}\right)^{p} \int_{\Omega} \frac{|u|^{p}}{d^{p}} d x, \quad u \in C_{c}^{\infty}(\Omega) \tag{1.2}
\end{equation*}
$$

with $\left(\frac{p-1}{p}\right)^{p}$ being the best constant, cf $[\mathrm{MS}]$, [MMP]. See [OK] for a comprehensive account of Hardy inequalities and [D] for a review of recent results.

In the last few years improved versions of the above inequalities have been obtained, in the sense that nonnegative terms are added in the right hand side of (1.1) or (1.2). Improved Hardy inequalities are useful in the study of critical phenomena in elliptic and parabolic PDE's; see, e.g., [BM, BV, MMP, VZ]. In this work we obtain an infinite series improvement for general Hardy inequalities, that include (1.1) or (1.2) as special cases.

Before stating our main theorems let us first introduce some notation. Let $\Omega$ be a domain in $\mathbb{R}^{N}, N \geq 2$, and $K$ a piecewise smooth surface of codimension $k, k=$ $1, \ldots, N$. In case $k=N$, we adopt the convention that $K$ is a point, say, the origin. We also set

$$
d(x)=\operatorname{dist}(x, K)
$$

and we assume that the following inequality holds in the weak sense:

$$
\begin{equation*}
p \neq k, \quad \quad \Delta_{p} d^{\frac{p-k}{p-1}} \leq 0, \quad \text { in } \Omega \backslash K \tag{C}
\end{equation*}
$$

Here $\Delta_{p}$ denotes the usual $p$-Laplace operator, $\Delta_{p} w=\operatorname{div}\left(|\nabla w|^{p-2} \nabla w\right)$. When $k=N$ (C) is satisfied as equality, since $d^{\frac{p-k}{p-1}}=|x|^{\frac{p-N}{p-1}}$ is the fundamental solution of the $p$-Laplacian. Also, if $k=1, \Omega$ is convex and $K=\partial \Omega$ condition (C) is satisfied. For a detailed analysis of this condition, as well as for examples in the intermediate cases $1<k<N$, we refer to [BFT].

We next define the function:

$$
\begin{equation*}
X_{1}(t)=(1-\log t)^{-1}, \quad t \in(0,1) \tag{1.3}
\end{equation*}
$$

and recursively

$$
X_{k}(t)=X_{1}\left(X_{k-1}(t)\right), \quad k=2,3, \ldots ;
$$

these are iterrated logarithmic functions suitably normalized. We also set

$$
\begin{equation*}
I_{m}[u]:=\int_{\Omega}|\nabla u|^{p} d x-|H|^{p} \int_{\Omega} \frac{|u|^{p}}{d^{p}} d x-\frac{p-1}{2 p}|H|^{p-2} \sum_{i=1}^{m} \int_{\Omega} \frac{|u|^{p}}{d^{p}} X_{1}^{2} X_{2}^{2} \ldots X_{i}^{2} d x \tag{1.4}
\end{equation*}
$$

where

$$
H=\frac{k-p}{p}
$$

Our main result reads
Theorem A Let $\Omega$ be a domain in $\mathbb{R}^{N}$ and $K$ a piecewise smooth surface of codimension $k, k=1, \ldots, N$. Suppose that $\sup _{x \in \Omega} d(x)<\infty$ and condition ( $C$ ) is satisfied. Then:
(1) There exists a positive constant $D_{0}=D_{0}(k, p) \geq \sup _{x \in \Omega} d(x)$ such that for any $D \geq D_{0}$ and all $u \in W_{0}^{1, p}(\Omega \backslash K)$ there holds

$$
\begin{align*}
& \int_{\Omega}|\nabla u|^{p} d x-|H|^{p} \int_{\Omega} \frac{|u|^{p}}{d^{p}} d x \geq \\
& \frac{p-1}{2 p}|H|^{p-2}\left(\sum_{i=1}^{\infty} \int_{\Omega} \frac{|u|^{p}}{d^{p}} X_{1}^{2}(d / D) \ldots X_{i}^{2}(d / D) d x\right) \tag{1.5}
\end{align*}
$$

If in addition $2 \leq p<k$, then we can take $D_{0}=\sup _{x \in \Omega} d(x)$.
(2) Moreover, for each $m=1,2, \ldots$ the constant $\frac{p-1}{2 p}|H|^{p-2}$ is the best constant for the corresponding m-Improved Hardy inequality, that is,

$$
\frac{p-1}{2 p}|H|^{p-2}=\inf _{u \in W_{0}^{1, p}(\Omega \backslash K)} \frac{I_{m-1}[u]}{\int_{\Omega} \frac{|u|^{p}}{d^{p}} X_{1}^{2} X_{2}^{2} \ldots X_{m}^{2} d x},
$$

in either of the following cases: (a) $k=N$ and $K=\{0\} \subset \Omega$, (b) $k=1$ and $K=\partial \Omega$, (c) $2 \leq k \leq N-1$ and $\Omega \cap K \neq \emptyset$.

We also note that the exponent two of the logarithmic corrections in (1.5) are optimal; see Proposition 3.1 for the precise statement.
For $p=2, \Omega$ convex and $K=\partial \Omega$ the first term in the infinite series of (1.5) was obtained in $[\mathrm{BM}]$. In the more general framework of Theorem A, the first term in the above series was obtained in [BFT]. On the other hand, when $p=2$ and $K=\{0\}$ the full series was obtained in $[\mathrm{FT}]$ by a different method. For other types of improved Hardy inequalities we refer to [BV, GGM, M, VZ]; in all these works one correction term is added in the right hand side of the plain Hardy inequality.
We next consider the degenerate case $p=k$ for which we do not have the usual Hardy inequality. In $[\mathrm{BFT}]$ a substitute for Hardy inequality was given in that case. The analogue of condition ( C ) is now:

$$
p=k, \quad \Delta_{p}(-\ln d) \leq 0, \quad \text { in } \Omega \backslash K .
$$

If ( $C^{\prime}$ ) is satisfied then for any $D \geq \sup _{\Omega} d(x)$ there holds (cf [BFT], Theorems 4.2 and 5.4):

$$
\begin{equation*}
\int_{\Omega}|\nabla u|^{k} d x \geq\left(\frac{k-1}{k}\right)^{k} \int_{\Omega} \frac{|u|^{k}}{d^{k}} X_{1}^{k}(d / D) d x, \quad u \in W_{0}^{1, p}(\Omega \backslash K), \tag{1.6}
\end{equation*}
$$

with $\left(\frac{k-1}{k}\right)^{k}$ being the best constant. In our next result we obtain a series improvement for inequality (1.6). We set

$$
\begin{aligned}
\tilde{I}_{m}[u]=: & \int_{\Omega}|\nabla u|^{k} d x-\left(\frac{k-1}{k}\right)^{k} \int_{\Omega} \frac{|u|^{k}}{d^{k}} X_{1}^{k}(d / D) d x- \\
& -\frac{1}{2}\left(\frac{k-1}{k}\right)^{k-1} \sum_{i=2}^{m} \int_{\Omega} \frac{|u|^{k}}{d^{k}} X_{1}^{k}(d / D) X_{2}^{2}(d / D) \ldots X_{m}^{2}(d / D) d x .
\end{aligned}
$$

We then have
Theorem B Let $\Omega$ be a domain in $\mathbb{R}^{N}$ and $K$ a piecewise smooth surface of codimension $k, k=2, \ldots, N$. Suppose that $\sup _{x \in \Omega} d(x)<\infty$ and condition ( $C^{\prime}$ ) is satisfied. Then,
(1) for any $D \geq \sup _{\Omega} d(x)$ and all $u \in W_{0}^{1, k}(\Omega \backslash K)$ there holds

$$
\begin{align*}
& \int_{\Omega}|\nabla u|^{k} d x-\left(\frac{k-1}{k}\right)^{k} \int_{\Omega} \frac{|u|^{k}}{d^{k}} X_{1}^{k}(d / D) d x \geq \\
& \quad \frac{1}{2}\left(\frac{k-1}{k}\right)^{k-1} \sum_{i=2}^{\infty} \int_{\Omega} \frac{|u|^{k}}{d^{k}} X_{1}^{k}(d / D) X_{2}^{2}(d / D) \ldots X_{i}^{2}(d / D) d x . \tag{1.7}
\end{align*}
$$

(2) Moreover, for each $m=2,3, \ldots$ the constant $\frac{1}{2}\left(\frac{k-1}{k}\right)^{k-1}$ is the best constant for the corresponding m-Improved inequality. That is

$$
\frac{1}{2}\left(\frac{k-1}{k}\right)^{k-1}=\inf _{u \in W_{0}^{1, p}(\Omega \backslash K)} \frac{\tilde{I}_{m-1}[u]}{\int_{\Omega} \frac{|u|^{k} X_{1}^{k} X_{2}^{2} \ldots X_{m}^{2} d x}{d} . . . \text {. } . .}
$$

in either of the following cases: (a) $k=N$ and $K=\{0\} \subset \Omega$, (b) $2 \leq k \leq N-1$ and $\Omega \cap K \neq \emptyset$.
To prove parts (1) of the above Theorems, we make use of suitable vector fields and elementary inequalities; this is carried out in Section 2. To prove the second parts, we use a local argument and appropriate test functions; this is done in Section 3.

## 2 The series expansion

In this Section we will derive the series improvement that appear in part (1) of Theorems A and B. We shall repeatedly use the differentiation rule

$$
\begin{equation*}
\frac{d}{d t} X_{i}^{\beta}(t)=\frac{\beta}{t} X_{1}(t) X_{2}(t) \ldots X_{i-1}(t) X_{i}^{1+\beta}(t), \quad i=1,2, \ldots, \quad \beta \neq-1 \tag{2.1}
\end{equation*}
$$

which is proved by induction: for $i=1$ (2.1) follows immediately from the definition of $X_{1}(t)$, cf. (1.3):

$$
\frac{d}{d t} X_{1}^{\beta}(t)=\frac{\beta}{t}(1-\log t)^{-\beta-1}=\frac{\beta}{r} X_{1}^{\beta+1}(t)
$$

Moreover assuming (2.1) for a fixed $i \geq 1$ we have

$$
\begin{aligned}
\frac{d}{d t} X_{i+1}^{\beta}(t) & =\frac{d}{d t}\left[X_{1}^{\beta}\left(X_{i}(t)\right)\right] \\
& =\frac{\beta}{X_{i}(t)} X_{1}^{\beta+1}\left(X_{i}(t)\right) \frac{d X_{i}(t)}{d t} \\
& =\frac{\beta}{X_{i}(t)} X_{i+1}^{\beta+1}(t) \frac{1}{t} X_{1}(t) \ldots X_{i-1}(t) X_{i}^{2}(t) \\
& =\frac{\beta}{t} X_{1}(t) \ldots X_{i}(t) X_{i+1}^{\beta+1}(t)
\end{aligned}
$$

hence (2.1) is proved.
Proof of Theorem $A(1)$ : We will make use of a suitable vectot field as in [BFT]. If $T$ is a $C^{1}$ vector field in $\Omega$, then, for any $u \in C_{c}^{\infty}(\Omega \backslash K)$ we first integrate by parts and then use Hölder's inequality to obtain

$$
\begin{aligned}
\int_{\Omega} \operatorname{div} T|u|^{p} d x & =-p \int_{\Omega}(T \cdot \nabla u)|u|^{p-2} u d x \\
& \leq p\left(\int_{\Omega}|\nabla u|^{p} d x\right)^{\frac{1}{p}}\left(\int_{\Omega}|T|^{\frac{p}{p-1}}|u|^{p} d x\right)^{\frac{p-1}{p}} \\
& \leq \int_{\Omega}|\nabla u|^{p} d x+(p-1) \int_{\Omega}|T|^{\frac{p}{p-1}}|u|^{p} d x .
\end{aligned}
$$

We therefore arrive at

$$
\begin{equation*}
\int_{\Omega}|\nabla u|^{p} d x \geq \int_{\Omega}\left(\operatorname{div} T-(p-1)|T|^{\frac{p}{p-1}}\right)|u|^{p} d x . \tag{2.2}
\end{equation*}
$$

For $m \geq 1$ we introduce the notation

$$
\begin{aligned}
\eta(t) & =\sum_{i=1}^{m} X_{1}(t) \ldots X_{i}(t), \\
B(t) & =\sum_{i=1}^{m} X_{1}^{2}(t) \ldots X_{i}^{2}(t), \quad t \in(0,1) .
\end{aligned}
$$

In view of (2.2) in order to prove (1.5) it is enough to establish the following pointwise estimate:

$$
\begin{equation*}
\operatorname{div} T-(p-1)|T|^{\frac{p}{p-1}} \geq \frac{|H|^{p}}{d^{p}}\left(1+\frac{p-1}{2 p H^{2}} B(d(x) / D)\right) . \tag{2.3}
\end{equation*}
$$

To proceed we now make a specific choice of $T$. We take

$$
T(x)=H|H|^{p-2} \frac{\nabla d(x)}{d^{p-1}(x)}\left(1+\frac{p-1}{p H} \eta(d(x) / D)+a \eta^{2}(d(x) / D)\right) .
$$

where $a$ is a free parameter to be chosen later. In any case $a$ will be such that the quantity $1+\frac{p-1}{p H} \eta(d / D)+a \eta^{2}(d / D)$ is positive on $\Omega$. Note that $T(x)$ is singular at $x \in K$, but since $u \in C_{c}^{\infty}(\Omega \backslash K)$ all previous calculations are legitimate.
When computing $\operatorname{div} T$ we need to differentiate $\eta(d(x) / D)$. Recalling (2.1) a straightforward calculation gives

$$
\eta^{\prime}(t)=\frac{1}{t}\left(X_{1}^{2}+\left(X_{1}^{2} X_{2}+X_{1}^{2} X_{2}^{2}\right)+\cdots+\left(X_{1}^{2} X_{2} \ldots X_{m}+\cdots+X_{1}^{2} \ldots X_{m}^{2}\right)\right),
$$

from which follows that

$$
\begin{equation*}
t \eta^{\prime}(t)=\frac{1}{2} B(t)+\frac{1}{2} \eta^{2}(t) . \tag{2.4}
\end{equation*}
$$

On the other hand, observing that

$$
\Delta_{p} d^{\frac{p-k}{p-1}}=\frac{p-k}{p-1}\left|\frac{p-k}{p-1}\right|^{p-2} d^{-k}\left(d \Delta d+(1-k)|\nabla d|^{2}\right),
$$

condition (C) implies

$$
\begin{equation*}
(p-k)(d \Delta d+1-k) \leq 0 . \tag{2.5}
\end{equation*}
$$

For the sake of simplicity we henceforth omit the argument $d(x) / D$ from $\eta(d(x) / D)$ and $B(d(x) / D)$. Using (2.4) and (2.5) a straightforward calculation shows that

$$
\begin{equation*}
\operatorname{div} T \geq \frac{|H|^{p}}{d^{p}}\left(p+\frac{p-1}{H} \eta+p a \eta^{2}+\frac{p-1}{2 p H^{2}}\left(B+\eta^{2}\right)+\frac{a}{H}\left(B+\eta^{2}\right) \eta\right) . \tag{2.6}
\end{equation*}
$$

It then follows that (2.3) will be established once we prove the following inequality $(p-1)+\frac{p-1}{H} \eta+\left(p a+\frac{p-1}{2 p H^{2}}\right) \eta^{2}+\frac{a}{H} B \eta+\frac{a}{H} \eta^{3}-(p-1)\left(1+\frac{p-1}{p H} \eta+a \eta^{2}\right)^{\frac{p}{p-1}} \geq 0$,
for all $x \in \Omega$. We set for convenience

$$
\begin{aligned}
f(B, \eta) & =(p-1)+\frac{p-1}{H} \eta+\left(p a+\frac{p-1}{2 p H^{2}}\right) \eta^{2}+\frac{a}{H} B \eta+\frac{a}{H} \eta^{3}, \\
g(\eta) & =\left(1+\frac{p-1}{p H} \eta+a \eta^{2}\right)^{\frac{p}{p-1}},
\end{aligned}
$$

and the required inequality is written as

$$
\begin{equation*}
f(B, \eta)-(p-1) g(\eta) \geq 0 . \tag{2.7}
\end{equation*}
$$

When $\eta=\eta(d(x) / D)>0$ is small, the Taylor expansion of $g(\eta)$ about $\eta=0$, gives

$$
\begin{equation*}
g(\eta)=1+\frac{1}{H} \eta+\frac{1}{2}\left(\frac{2 a p}{p-1}+\frac{1}{p H^{2}}\right) \eta^{2}+\frac{1}{6}\left(\frac{6 a}{(p-1) H}+\frac{2-p}{p^{2} H^{3}}\right) \eta^{3}+O\left(\eta^{4}\right) . \tag{2.8}
\end{equation*}
$$

Let us also note, that in the special case $a=0$, there holds

$$
\begin{equation*}
g(\eta)=1+\frac{1}{H} \eta+\frac{1}{2 p H^{2}} \eta^{2}+\frac{2-p}{6 p^{2} H^{3}}\left(1+\frac{p-1}{p H} \xi_{\eta}\right)^{\frac{3-2 p}{p-1}} \eta^{3}, \quad(a=0), \tag{2.9}
\end{equation*}
$$

for some $\xi_{\eta} \in(0, \eta)$, without any smallness assumption on $\eta$.
In view of (2.8), if $\eta$ is small, inequality (2.7) will be proved once we show:

$$
\begin{equation*}
\frac{a}{H} \geq\left(\frac{(2-p)(p-1)}{6 p^{2} H^{3}}+O(\eta)\right) \frac{\eta^{2}}{B} . \tag{2.10}
\end{equation*}
$$

From the definition of $\eta$ and $B$ it follows easily that

$$
\begin{equation*}
m \geq \frac{\eta^{2}}{B} \geq 1 \tag{2.11}
\end{equation*}
$$

We will show that for any choice of $H$ and $p>1$, there exists an $a \in \mathbb{R}$, such that (2.7) holds true. We distinguish various cases:
(a) $H>0,1<p<2$. We assume that $\eta$ is small, which amounts to taking $D$ big. It is enough to show that we can choose $a$ such that (2.10) holds. In view of (2.11) we see that for (2.10) to be valid, it is enough to take $a$ to be big and positive.
(b) $H>0, p \geq 2$. In this case we choose $a=0$ and we use (2.9). Notice that under our current assumptions on $H, p$ the last term in (2.9) is negative and therefore

$$
\begin{equation*}
g(\eta) \leq 1+\frac{1}{H} \eta+\frac{1}{2 p H^{2}} \eta^{2}, \quad(a=0) \tag{2.12}
\end{equation*}
$$

On the other hand

$$
f(B, \eta)=(p-1)+\frac{p-1}{H} \eta+\frac{p-1}{2 p H^{2}} \eta^{2}, \quad(a=0)
$$

and therefore (2.7) is satisfied, without any smallness assumption on $\eta$. In particular, we can take $D_{0}=\sup _{x \in \Omega} d(x)$ in this case.
(c) $H<0,1<p<2$. We assume that $\eta$ is small. In this case, the right hand side of (2.10) is negative. Hence, we can choose $a=0$ and (2.10) holds true.
(d) $H<0, p \geq 2$. Arguing as in case (a) we take $a$ to be big and negative, and (2.10) holds true.
We next consider the degenerate case $p=k$.
Proof of Theorem B(1): We assume that $p=k \geq 2$ and that condition ( $\mathrm{C}^{\prime}$ ) is satisfied. The proof is quite similar to the previous one.
An easy calculation shows that condition ( $C^{\prime}$ ) implies that

$$
\begin{equation*}
d \Delta d+1-k \geq 0 \tag{2.13}
\end{equation*}
$$

We now choose the vector field

$$
\begin{equation*}
T(x)=\left(\frac{k-1}{k}\right)^{k-1} \frac{\nabla d}{d^{k-1}}\left(X_{1}^{k-1}+\sum_{i=2}^{m} X_{1}^{k-1} X_{2} \ldots X_{i}\right) \tag{2.14}
\end{equation*}
$$

where, here and below, $X_{j}=X_{j}(d(x) / D)$. Taking into account (2.13) a straightforward calculation yields that

$$
\begin{align*}
& \operatorname{div} T-(p-1)|T|^{\frac{p}{p-1}} \geq \frac{(k-1)^{k}}{k^{k-1}} \frac{X_{1}^{k}}{d^{k}}\left(1+\sum_{i=2}^{m} X_{2} \ldots X_{i}\right. \\
& \left.\quad+\frac{1}{k-1} \sum_{i=2}^{m} \sum_{j=2}^{i} X_{2}^{2} \ldots X_{j}^{2} X_{j+1} \ldots X_{i}-\frac{k-1}{k}\left(1+\sum_{i=2}^{m} X_{2} \ldots X_{i}\right)^{\frac{k}{k-1}}\right) \tag{2.15}
\end{align*}
$$

To estimate the last term in the right hand side of (2.15) we use Taylor's expansion to obtain the inequality

$$
\left(1+\sum_{i=2}^{m} X_{2} \ldots X_{i}\right)^{\frac{k}{k-1}} \leq 1+\frac{k}{k-1} \sum_{i=2}^{m} X_{2} \ldots X_{i}+\frac{k}{2(k-1)^{2}}\left(\sum_{i=2}^{m} X_{2} \ldots X_{i}\right)^{2}
$$

It then follows that

$$
\begin{align*}
& \quad \operatorname{div} T-(p-1)|T|^{\frac{p}{p-1}} \geq \\
& \frac{(k-1)^{k-1}}{k^{k-1}} \frac{X_{1}^{k}}{d^{k}}\left(\frac{k-1}{k}+\sum_{i=2}^{m} \sum_{j=2}^{i} X_{2}^{2} \ldots X_{j}^{2} X_{j+1} \ldots X_{i}-\frac{1}{2}\left(\sum_{i=2}^{m} X_{2} \ldots X_{i}\right)^{2}\right) \tag{2.16}
\end{align*}
$$

Expanding the square in the last term in (2.16) we conclude that

$$
\operatorname{div} T-(p-1)|T|^{\frac{p}{p-1}} \geq\left(\frac{k-1}{k}\right)^{k-1} \frac{X_{1}^{k}}{d^{k}}\left(\frac{k-1}{k}+\frac{1}{2} \sum_{i=2}^{m} X_{2}^{2} \ldots X_{i}^{2}\right)
$$

and the result follows.

## 3 Best constants

In this section we are going to prove the optimality of the Improved Hardy Inequality of Section 2. More precisely, for any $m \geq 1$ let us recall that

$$
\begin{aligned}
I_{m}[u]= & \int_{\Omega}|\nabla u|^{p} d x-|H|^{p} \int_{\Omega} \frac{|u|^{p}}{d^{p}} d x- \\
& -\frac{p-1}{2 p}|H|^{p-2} \int_{\Omega} \frac{|u|^{p}}{d^{p}}\left(X_{1}^{2}+X_{1}^{2} X_{2}^{2}+\cdots+X_{1}^{2} \ldots X_{m}^{2}\right) d x
\end{aligned}
$$

where $X_{i}=X_{i}(d(x) / D)$. We have the following

Proposition 3.1 Let $\Omega$ be a domain in $\mathbb{R}^{N}$. (i) If $2 \leq k \leq N-1$ then we take $K$ to be a piecewise smooth surface of codimension $k$ and assume $K \cap \Omega \neq \emptyset$; (ii) if $k=N$ then we take $K=\{0\} \subset \Omega$; (iii) if $k=1$ then we assume $K=\partial \Omega$. Let $D \geq \sup _{\Omega} d(x)$ be fixed and suppose that for some constants $B>0$ and $\gamma \in \mathbb{R}$ the following inequality holds true for all $u \in W_{0}^{1, p}(\Omega \backslash K)$

$$
\begin{equation*}
I_{m-1}[u] \geq B \int_{\Omega} \frac{|u|^{p}}{d^{p}} X_{1}^{2}(d / D) \ldots X_{m-1}^{2}(d / D) X_{m}^{\gamma}(d / D) d x \tag{3.1}
\end{equation*}
$$

Then
(i) $\gamma \geq 2$
(ii) If $\gamma=2$ then $B \leq \frac{p-1}{2 p}|H|^{p-2}$.

Proof. All our analysis will be local, say, in a fixed ball of radius $\delta$ (denoted by $\left.B_{\delta}\right)$ centered at the origin, for some fixed small $\delta$. The proof we present works for any $k=1,2, \ldots, N$. We note however that for $k=N$ (distance from a point) the subsequent calculations are substantially simplified, whereas for $k=1$ (distance from the boundary) one should replace $B_{\delta}$ by $B_{\delta} \cap \Omega$. This last change entails some minor modifications, the arguments otherwise being the same. Without any loss of generality we may assume that $0 \in K \cap \Omega(k \neq 1)$, or $0 \in \partial \Omega$ if $k=1$. We divide the proof into several steps.

Step 1. Let $\phi \in C_{c}^{\infty}\left(B_{\delta}\right)$ be such that $0 \leq \phi \leq 1$ in $B_{\delta}$ and $\phi=1$ in $B_{\delta / 2}$. We fix small parameters $\alpha_{0}, \alpha_{1}, \ldots, \alpha_{m}>0$ and define the functions

$$
w(x)=d^{-H+\frac{\alpha_{0}}{p}} X_{1}^{\frac{-1+\alpha_{1}}{p}}(d / D) \ldots X_{m}^{\frac{-1+\alpha_{m}}{p}}(d / D)
$$

and

$$
u(x)=\phi(x) w(x)
$$

It is an immediate consequence of (3.17) below that $u \in W^{1, p}(\Omega)$. Moreover, if $k<p$ then $H<0$ and therefore $\left.u\right|_{K}=0$. On the other hand, if $k>p$ then a standard approximation argument - using cut-off functions - shows that $W_{0}^{1, p}(\Omega \backslash K)=$ $W^{1, p}(\Omega \backslash K)$. Hence $u \in W_{0}^{1, p}(\Omega \backslash K)$. To prove the proposition we shall estimate the corresponding Rayleigh quotient of $u$ in the limit $\alpha_{0} \rightarrow 0, \alpha_{1} \rightarrow 0, \ldots, \alpha_{m} \rightarrow 0$ in this order.

It is easily seen that

$$
\begin{equation*}
\nabla w=-d^{\frac{-k+\alpha_{0}}{p}} X_{1}^{\frac{-1+\alpha_{1}}{p}} \ldots X_{m}^{\frac{-1+\alpha_{m}}{p}}\left(H+\frac{\zeta(x)}{p}\right) \nabla d \tag{3.2}
\end{equation*}
$$

where

$$
\begin{equation*}
\zeta(x)=-\alpha_{0}+\left(1-\alpha_{1}\right) X_{1}+\ldots+\left(1-\alpha_{m}\right) X_{1} X_{2} \ldots X_{m} \tag{3.3}
\end{equation*}
$$

where, here and below, we omit the argument $d(x) / D$ from $X_{i}(d / D)$. Since $\delta$ is small the $X_{i}$ 's are also small. Hence $\zeta(x)$ can be thought as a small parameter in the rest of the proof.
Now $\nabla u=\phi \nabla w+\nabla \phi w$ and hence, using the elementary inequality

$$
\begin{equation*}
|a+b|^{p} \leq|a|^{p}+c_{p}\left(|a|^{p-1}|b|+|b|^{p}\right), \quad a, b \in \mathbb{R}^{N}, \quad p>1 \tag{3.4}
\end{equation*}
$$

we obtain

$$
\begin{align*}
\int_{\Omega}|\nabla u|^{p} d x \leq & \int_{B_{\delta}} \phi^{p}|\nabla w|^{p} d x+c_{p} \int_{B_{\delta}}|\nabla \phi||\phi|^{p-1}|\nabla w|^{p-1}|w| d x+ \\
& +c_{p} \int_{B_{\delta}}|\nabla \phi|^{p}|w|^{p} d x \\
= & I_{1}+I_{2}+I_{3} . \tag{3.5}
\end{align*}
$$

We claim that

$$
\begin{equation*}
I_{2}, I_{3}=O(1) \quad \text { uniformly as } \alpha_{0}, \alpha_{1}, \ldots, \alpha_{m} \text { tend to zero. } \tag{3.6}
\end{equation*}
$$

Let us give the proof for $I_{2}$. Using the definition of $w(x)$ and the regularity of $\phi$ we obtain

$$
I_{2} \leq c \int_{B_{\delta}} d^{1-k+\alpha_{0}} X_{1}^{-1+\alpha_{1}} \ldots X_{m}^{-1+\alpha_{m}}\left|H+\frac{\zeta(x)}{p}\right|^{p-1} d x .
$$

The appearance of $d^{-k+1}$ together with the fact that $\zeta$ is small compared to $H$ implies that $I_{2}$ is uniformly bounded (see step 2). The integral $I_{3}$ is treated similarly.
Step 2. We shall repeatedly deal with integrals of the form

$$
\begin{equation*}
Q=\int_{\Omega} \phi^{p} d^{-k+\beta_{0}} X_{1}^{1+\beta_{1}}(d / D) \ldots X_{m}^{1+\beta_{m}}(d / D) d x, \quad \beta_{i} \in \mathbb{R} \tag{3.7}
\end{equation*}
$$

we therefore provide precise conditions under which $Q<\infty$. From our assumptions on $\phi$ we have

$$
\int_{B_{\delta / 2}} d^{-k+\beta_{0}} X_{1}^{1+\beta_{1}} \ldots X_{m}^{1+\beta_{m}} d x \leq Q \leq \int_{B_{\delta}} d^{-k+\beta_{0}} X_{1}^{1+\beta_{1}} \ldots X_{m}^{1+\beta_{m}} d x
$$

Using the coarea formula and the fact that

$$
c_{1} r^{k-1} \leq \int_{\{d=r\} \cap B_{\delta}} d S<c_{2} r^{k-1}
$$

we conclude that

$$
c_{1} \int_{0}^{\delta / 2} r^{-1+\beta_{0}} X_{1}^{1+\beta_{1}} \ldots X_{m}^{1+\beta_{m}} d r \leq Q \leq c_{2} \int_{0}^{\delta} r^{-1+\beta_{0}} X_{1}^{1+\beta_{1}} \ldots X_{m}^{1+\beta_{m}} d r .
$$

where $X_{i}=X_{i}(r / D)$. Hence, recalling (2.1) we conclude that

$$
Q<\infty \Longleftrightarrow \begin{cases} & \beta_{0}>0  \tag{3.8}\\ \text { or } & \beta_{0}=0 \text { and } \beta_{1}>0 \\ \text { or } & \beta_{0}=\beta_{1}=0 \text { and } \beta_{2}>0 \\ & \ldots \\ \text { or } & \beta_{0}=\beta_{1}=\ldots=\beta_{m-1}=0 \text { and } \beta_{m}>0\end{cases}
$$

Step 3. We introduce some auxiliary quantities and prove some simple relations about them. For $0 \leq i \leq j \leq m$ we define

$$
\begin{aligned}
& A_{0}=\int_{\Omega} \phi^{p} d^{-k+\alpha_{0}} X_{1}^{-1+\alpha_{1}} \ldots X_{m}^{-1+\alpha_{m}} d x \\
& A_{i}=\int_{\Omega} \phi^{p} d^{-k+\alpha_{0}} X_{1}^{1+\alpha_{1}} \ldots X_{i}^{1+\alpha_{i}} X_{i+1}^{-1+\alpha_{i+1}} \ldots X_{m}^{-1+\alpha_{m}} d x \\
& \Gamma_{0 j}=\int_{\Omega} \phi^{p} d^{-k+\alpha_{0}} X_{1}^{\alpha_{1}} \ldots X_{i}^{\alpha_{i}} X_{i+1}^{-1+\alpha_{i+1}} \ldots X_{m}^{-1+\alpha_{m}} d x \\
& \Gamma_{i j}=\int_{\Omega} \phi^{p} d^{-k+\alpha_{0}} X_{1}^{1+\alpha_{1}} \ldots X_{i}^{1+\alpha_{i}} X_{i+1}^{\alpha_{i+1} \ldots X_{j}^{\alpha_{j}} X_{j+1}^{-1+\alpha_{j+1}} \ldots X_{m}^{-1+\alpha_{m}} d x,}
\end{aligned}
$$

with $\Gamma_{i i}=A_{i}$. We have the following
Two identities: Let $0 \leq i \leq m-1$ be given and assume that $\alpha_{0}=\alpha_{1}=\ldots=\alpha_{i-1}=0$. Then

$$
\begin{align*}
& \alpha_{i} A_{i}=\sum_{j=i+1}^{m}\left(1-\alpha_{j}\right) \Gamma_{i j}+O(1)  \tag{3.9}\\
& \alpha_{i} \Gamma_{i j}=-\sum_{k=i+1}^{j} \alpha_{k} \Gamma_{k j}+\sum_{k=j+1}^{m}\left(1-\alpha_{k}\right) \Gamma_{j k}+O(1) \tag{3.10}
\end{align*}
$$

where the $O(1)$ is uniform as the $\alpha_{i}$ 's tend to zero. Let us give the proof for (3.9). We assume that $i>0$, the case $i=0$ being a straight-forward adaptation. A direct computation gives

$$
\begin{equation*}
\alpha_{i} d^{-k} X_{1} \ldots X_{i-1} X_{i}^{1+\alpha_{i}}=\operatorname{div}\left(d^{-k+1} X_{i}^{\alpha_{i}} \nabla d\right)-d^{-k}(d \Delta d+1-k) X_{i}^{\alpha_{i}} . \tag{3.11}
\end{equation*}
$$

hence

$$
\begin{aligned}
\alpha_{i} A_{i}= & \int_{\Omega} \phi^{p} \operatorname{div}\left(d^{-k+1} X_{i}^{\alpha_{i}} \nabla d\right) X_{i+1}^{-1+\alpha_{i+1}} \ldots X_{m}^{-1+\alpha_{m}} d x- \\
& -\int_{\Omega} \phi^{p} d^{-k}(d \Delta d+1-k) X_{i}^{\alpha_{i}} X_{i+1}^{-1+\alpha_{i+1}} \ldots X_{m}^{-1+\alpha_{m}} d x \\
= & E_{1}-E_{2} .
\end{aligned}
$$

It is a direct consequence of [AS, Theorem 3.2] that

$$
\begin{equation*}
d \Delta d+1-k=O(d), \quad \text { as } d \rightarrow 0, \tag{3.12}
\end{equation*}
$$

hence $E_{2}$ is estimated by a constant times $\int_{\Omega} \phi^{p} d^{-k+1} X_{i}^{\alpha_{i}} X_{i+1}^{-1+\alpha_{i+1}} \ldots X_{m}^{-1+\alpha_{m}} d x$ and therefore is bounded uniformly in $\alpha_{0}, \alpha_{1}, \ldots, \alpha_{m}$. To handle $E_{1}$ we integrate by parts obtaining

$$
\begin{aligned}
E_{1}= & -\int_{\Omega} \nabla \phi^{p} \cdot \nabla d d^{-k+1} X_{i}^{\alpha_{i}} X_{i+1}^{-1+\alpha_{i+1}} \ldots X_{m}^{-1+\alpha_{m}} d x \\
& -\int_{\Omega} \phi^{p} d^{-k+1} X_{i}^{\alpha_{i}} \nabla d \cdot \nabla\left(X_{1}^{-1+\alpha_{1}} \ldots X_{m}^{-1+\alpha_{m}}\right) d x
\end{aligned}
$$

The first integral is of order $O(1)$ (similarly to $I_{2}, I_{3}$ above) while the second is equal to $\sum_{j=i+1}^{m}\left(1-\alpha_{j}\right) \Gamma_{i j}$. Hence (3.9) has been proved. To prove (3.10) we use (3.11) once more and proceed similarly; we omit the details.

Step 4. We proceed to estimate $I_{1}$. It follows from (3.2) that

$$
I_{1}=\int_{\Omega} \phi^{p} d^{-k+\alpha_{0}} X_{1}^{-1+\alpha_{1}} \ldots X_{m}^{-1+\alpha_{m}}\left|H+\frac{\zeta}{p}\right|^{p} d x
$$

Since $\zeta$ is small compared to $H$ we may use Taylor's expansion to obtain

$$
\begin{equation*}
\left|H+\frac{\zeta}{p}\right|^{p} \leq|H|^{p}+|H|^{p-2} H \zeta+\frac{p-1}{2 p}|H|^{p-2} \zeta^{2}+c|\zeta|^{3} . \tag{3.13}
\end{equation*}
$$

Using this inequality we can bound $I_{1}$ by

$$
\begin{equation*}
I_{1} \leq I_{10}+I_{11}+I_{12}+I_{13}, \tag{3.14}
\end{equation*}
$$

where

$$
\begin{align*}
I_{10} & =|H|^{p} \int_{B_{\delta}} \phi^{p} d^{-k+\alpha_{0}} X_{1}^{-1+\alpha_{1}} \ldots X_{m}^{-1+\alpha_{m}} d x=|H|^{p} \int_{\Omega} \frac{|u|^{p}}{d^{p}} d x  \tag{3.15}\\
I_{11} & =|H|^{p-2} H \int_{B_{\delta}} \phi^{p} d^{-k+\alpha_{0}} X_{1}^{-1+\alpha_{1}} \ldots X_{m}^{-1+\alpha_{m}} \zeta(x) d x \\
I_{12} & =\frac{p-1}{2 p}|H|^{p-2} \int_{B_{\delta}} \phi^{p} d^{-k+\alpha_{0}} X_{1}^{-1+\alpha_{1}} \ldots X_{m}^{-1+\alpha_{m}} \zeta^{2}(x) d x \\
I_{13} & =c \int_{B_{\delta}} \phi^{p} d^{-k+\alpha_{0}} X_{1}^{-1+\alpha_{1}} \ldots X_{m}^{-1+\alpha_{m}}|\zeta(x)|^{3} d x
\end{align*}
$$

Step 5. We shall prove that

$$
\begin{equation*}
I_{11}, I_{13}=O(1) \quad \text { uniformly in } \alpha_{0}, \alpha_{1}, \ldots, \alpha_{m} \tag{3.16}
\end{equation*}
$$

Indeed, substituting for $\zeta$ in $I_{11}$ we see by a direct application of (3.9) (for $i=0$ ) that $I_{11}=O(1)$. To estimate $I_{13}$ we observe that $X_{1} \ldots X_{i} \leq c X_{1}$ for some $c>0$ and thus obtain

$$
\begin{aligned}
I_{13} \leq & c_{1} \alpha_{0}^{3} \int_{\Omega} \phi^{p} d^{-k+\alpha_{0}} X_{1}^{-1+\alpha_{1}} \ldots X_{m}^{-1+\alpha_{m}} d x+ \\
& +c_{2} \int_{\Omega} \phi^{p} d^{-k+\alpha_{0}} X_{1}^{2+\alpha_{1}} X_{2}^{-1+\alpha_{2}} \ldots X_{m}^{-1+\alpha_{m}} d x
\end{aligned}
$$

The second integral is bounded uniformly in the $\alpha_{i}$ 's due to the factor $X_{1}^{2}$. Moreover, using the fact $0 \leq \phi \leq 1$ and $\int_{\{d=r\} \cap B_{\delta}} d S<c r^{k-1}$ we obtain

$$
\begin{aligned}
& \alpha_{0}^{3} \int_{\Omega} \phi^{p} d^{-k+\alpha_{0}} X_{1}^{-1+\alpha_{1}} \ldots X_{m}^{-1+\alpha_{m}} d x \\
& \leq c \alpha_{0}^{3} \int_{0}^{\delta} r^{-1+\alpha_{0}} X_{1}^{-1+\alpha_{1}}(r / D) \ldots X_{m}^{-1+\alpha_{m}}(r / D) d r \\
& \leq c \alpha_{0}^{3} \int_{0}^{\delta} r^{-1+\alpha_{0}} X_{1}^{-2}(r / D) d r \\
&\left(r=D s^{1 / \alpha_{0}}\right)=c D^{\alpha_{0}} \alpha_{0}^{2} \int_{0}^{(\delta / D)^{\alpha_{0}}}\left(1-\frac{1}{\alpha_{0}} \log s\right)^{2} d s \\
&=O(1)
\end{aligned}
$$

as $\alpha_{0} \rightarrow 0$, uniformly in $\alpha_{1}, \ldots \alpha_{m}$. Hence (3.16) has been proved. Combining (3.5), (3.6), (3.14), (3.15) and (3.16) we conclude that

$$
\begin{equation*}
\int_{\Omega}|\nabla u|^{p} d x-|H|^{p} \int_{\Omega} \frac{|u|^{p}}{d^{p}} d x \leq I_{12}+O(1) \tag{3.17}
\end{equation*}
$$

uniformly in the $\alpha_{i}$ 's.
Step 6. Recalling the definition of $I_{m-1}[\cdot]$ we obtain from (3.17)

$$
\begin{align*}
I_{m-1}[u] \leq & \frac{p-1}{2 p}|H|^{p-2} \int_{\Omega} \phi^{p} d^{-k+\alpha_{0}} X_{1}^{-1+\alpha_{1}} \ldots X_{m}^{-1+\alpha_{m}} \times \\
& \times\left(\zeta^{2}(x)-\sum_{i=1}^{m-1} X_{1}^{2} \ldots X_{i}^{2}\right) d x+O(1) \\
= & \frac{p-1}{2 p}|H|^{p-2} J+O(1) \tag{3.18}
\end{align*}
$$

Expanding $\zeta^{2}(x)(c f(3.3))$ and collecting similar terms we obtain

$$
\begin{gather*}
J=\int_{\Omega} \phi^{p} d^{-k+\alpha_{0}} X_{1}^{-1+\alpha_{1}} \ldots X_{m}^{-1+\alpha_{m}}\left\{\alpha_{0}^{2}+\sum_{i=1}^{m}\left(1-\alpha_{i}\right)^{2} X_{1}^{2} \ldots X_{i}^{2}-\right. \\
-\sum_{i=1}^{m-1} X_{1}^{2} \ldots X_{i}^{2}-2 \alpha_{0} \sum_{j=1}^{m}\left(1-\alpha_{j}\right) X_{1} \ldots X_{j}+ \\
\left.+2 \sum_{i=1}^{m-1} \sum_{j=i+1}^{m}\left(1-\alpha_{i}\right)\left(1-\alpha_{j}\right) X_{1}^{2} \ldots X_{i}^{2} X_{i+1} \ldots X_{j}\right\} d x \\
=\alpha_{0}^{2} A_{0}+A_{m}+\sum_{i=1}^{m}\left(\alpha_{i}^{2}-2 \alpha_{i}\right) A_{i}-2 \alpha_{0} \sum_{j=1}^{m}\left(1-\alpha_{j}\right) \Gamma_{0 j}+ \\
+\sum_{i=1}^{m-1} \sum_{j=i+1}^{m} 2\left(1-\alpha_{i}\right)\left(1-\alpha_{j}\right) \Gamma_{i j} . \tag{3.19}
\end{gather*}
$$

Step 7. We intend to take the limit $\alpha_{0} \rightarrow 0$ in (3.19). All terms have finite limits except those containing $A_{0}$ and $\Gamma_{0 j}$ which, when viewed separately, diverge. When combined however, they give

$$
\begin{gathered}
\alpha_{0}^{2} A_{0}-2 \alpha_{0} \sum_{j=1}^{m}\left(1-\alpha_{j}\right) \Gamma_{0 j} \\
(\text { by }(3.9))=-\alpha_{0} \sum_{j=1}^{m}\left(1-\alpha_{j}\right) \Gamma_{0 j}+O(1) \\
(\text { by }(3.10))=-\sum_{j=1}^{m}\left(1-\alpha_{j}\right)\left(-\sum_{i=1}^{j} \alpha_{i} \Gamma_{i j}+\sum_{i=j+1}^{m}\left(1-\alpha_{i}\right) \Gamma_{j i}\right)+O(1) \\
=\sum_{i=1}^{m}\left(\alpha_{i}-\alpha_{i}^{2}\right) A_{i}+\sum_{i=1}^{m-1} \sum_{j=i+1}^{m}\left(2 \alpha_{i}-1\right)\left(1-\alpha_{j}\right) \Gamma_{i j}+O(1) .
\end{gathered}
$$

All the terms in the last expression remain bounded as $\alpha_{0} \rightarrow 0$; hence taking the limit in (3.19) we obtain

$$
\begin{equation*}
J=A_{m}-\sum_{i=1}^{m} \alpha_{i} A_{i}+\sum_{i=1}^{m-1} \sum_{j=i+1}^{m}\left(1-\alpha_{j}\right) \Gamma_{i j}+O(1) \quad\left(\alpha_{0}=0\right) \tag{3.20}
\end{equation*}
$$

where the $O(1)$ is uniform with respect to $\alpha_{1}, \ldots, \alpha_{m}$.
Step 8. We next let $\alpha_{1} \rightarrow 0$ in (3.20). All terms have finite limits except those involving $A_{1}$ and $\Gamma_{1 j}$ which diverge. Using (3.9) once more - this time for $i=1$ - we see that when combined these terms stay bounded in the limit $\alpha_{1} \rightarrow 0$. Hence

$$
\begin{equation*}
J=A_{m}-\sum_{i=2}^{m} \alpha_{i} A_{i}+\sum_{i=2}^{m-1} \sum_{j=i+1}^{m}\left(1-\alpha_{j}\right) \Gamma_{i j}+O(1) \quad\left(\alpha_{0}=\alpha_{1}=0\right) \tag{3.21}
\end{equation*}
$$

We proceed in this way and after letting $\alpha_{m-1} \rightarrow 0$ we are left with

$$
\begin{equation*}
J=\left(1-\alpha_{m}\right) A_{m}+O(1), \quad\left(\alpha_{0}=\alpha_{1}=\ldots \alpha_{m-1}=0\right) \tag{3.22}
\end{equation*}
$$

uniformly in $\alpha_{m}$.
Combining (3.1), (3.18) and (3.22) we conclude that

$$
\begin{equation*}
B \leq \frac{p-1}{2 p}|H|^{p-2} \frac{\left(1-\alpha_{m}\right) A_{m}+O(1)}{\int_{\Omega} \phi^{p} d^{-k} X_{1} \ldots X_{m-1} X_{m}^{\gamma-1+\alpha_{m}} d x} . \tag{3.23}
\end{equation*}
$$

Suppose now that $\gamma<2$. Then letting $\alpha_{m} \rightarrow 2-\gamma>0$ we observe that the denominator in (3.23) tends to infinity while the numerator stays bounded. This implies $B=0$ proving part (i) of the Proposition.
Now, if $\gamma=2$ then the denominator in (3.23) is equal to $A_{m}$. Hence letting $\alpha_{m} \rightarrow 0$ we have $A_{m} \rightarrow \infty$ (by (3.8)) and hence $B \leq \frac{p-1}{2 p}|H|^{p-2}$. This concludes the proof. // We next consider the degenerate case $p=k$. We have the following

Proposition 3.2 Let $\Omega$ be a domain in $\mathbb{R}^{N}$. (i) If $2 \leq k \leq N-1$ then we take $K$ to be a piecewise smooth surface of codimension $k$ and assume $K \cap \Omega \neq \emptyset$; (ii) if $k=N$ then we take $K=\{0\} \subset \Omega$. Let $D \geq \sup _{x \in \Omega} d(x)$ be fixed and suppose that for some constants $B>0$ and $\gamma \in \mathbb{R}$ the following inequality holds true for all $u \in C_{c}^{\infty}(\Omega \backslash K)$

$$
\begin{equation*}
\tilde{I}_{m-1}[u] \geq B \int_{\Omega} \frac{|u|^{k}}{d^{k}} X_{1}^{k}(d / D) X_{2}^{2}(d / D) \ldots X_{m}^{\gamma}(d / D) d x \tag{3.24}
\end{equation*}
$$

Then:
(i) $\gamma \geq 2$
(ii) If $\gamma=2$ then $B \leq \frac{1}{2}\left(\frac{k-1}{k}\right)^{k-1}$.

Proof. The proof is similar to that of Proposition 3.1. Without any loss of generality we assume that $0 \in K \cap \Omega$. As in the previous theorem we let $\phi$ be a non-negative, smooth cut-off function supported in $B_{\delta}=\{|x|<\delta\}$, equal to one on $B_{\delta / 2}$ and taking values in $[0,1]$.
Given small parameters $\alpha_{1}, \ldots, \alpha_{m}>0$ we define

$$
w(x)=X_{1}^{\frac{-k+1+\alpha_{1}}{k}}(d / D) X_{2}^{\frac{-1+\alpha_{2}}{k}}(d / D) \ldots X_{m}^{\frac{-1+\alpha_{m}}{k}}(d / D) .
$$

and

$$
u(x)=\phi(x) w(x) .
$$

Subsequent calculations will establish that $u \in W^{1, k}(\Omega)$ (see (3.29)). We will prove that $u \in W_{0}^{1, k}(\Omega \backslash K)$ by showing that

$$
\begin{equation*}
d^{\frac{\alpha_{0}}{k}} u \rightarrow u \quad \text { in } W^{1, k}(\Omega) \text { as } \alpha_{0} \rightarrow 0 \tag{3.25}
\end{equation*}
$$

We have

$$
\begin{equation*}
\int_{\Omega}\left|\nabla\left(d^{\frac{\alpha_{0}}{k}} u\right)-\nabla u\right|^{k} d x \leq c \alpha_{0}^{k} \int_{\Omega} d^{-k+\alpha_{0}} u^{k} d x+\int_{\Omega}\left|d^{\frac{\alpha_{0}}{k}}-1\right|^{k}|\nabla u|^{k} d x \tag{3.26}
\end{equation*}
$$

The second term in the right hand side of (3.26) tends to zero as $\alpha_{0} \rightarrow 0$ by the dominated convergence theorem. Moreover, there exists a constant $c_{\alpha_{1}}$ such that
$X_{1}^{\alpha_{1} / 2} X_{2}^{-1} \ldots X_{m}^{-1} \leq c_{\alpha_{1}}$. Hence the first term in the right hand side of (3.26) is estimated by

$$
c_{\alpha_{1}} \alpha_{0}^{k} \int_{\Omega} d^{-k+\alpha_{0}} X_{1}^{-k+1+\frac{\alpha_{1}}{2}} d x .
$$

A direct application of [BFT, Lemma 5.2] shows that this tends to zero as $\alpha_{0} \rightarrow 0$. Hence $u \in W_{0}^{1, p}(\Omega \backslash K)$.
To proceed we use (3.4) obtaining

$$
\begin{align*}
\int_{\Omega}|\nabla u|^{k} d x \leq & \int_{\Omega} \phi^{k}|\nabla w|^{k} d x+c_{k} \int_{\Omega}|\nabla \phi||\phi|^{k-1}|\nabla w|^{k-1}|w| d x+ \\
& +c_{k} \int_{\Omega}|\nabla \phi|^{k}|w|^{k} d x \\
=: & I_{1}+I_{2}+I_{3} . \tag{3.27}
\end{align*}
$$

Arguing as in the proof of the previous proposition (cf step 1) we see that $I_{2}$ and $I_{3}$ are bounded uniformly with respect to the $\alpha_{i}$ 's. Hence

$$
\begin{equation*}
\int_{\Omega}|\nabla u|^{k} d x \leq \int_{\Omega} \phi^{k}|\nabla w|^{k} d x+O(1) \tag{3.28}
\end{equation*}
$$

uniformly as $\alpha_{1}, \ldots, \alpha_{m} \rightarrow 0$.
Now, a direct computation yields

$$
\nabla w=-d^{-1} X_{1}^{\frac{1+\alpha_{1}}{k}} X_{2}^{\frac{-1+\alpha_{2}}{k}} \ldots X_{m}^{\frac{-1+\alpha_{m}}{k}}\left(\frac{k-1}{k}+\frac{\zeta(x)}{k}\right) \nabla d
$$

where

$$
\zeta(x)=-\alpha_{1}+\sum_{i=2}^{m}\left(1-\alpha_{i}\right) X_{2}(d / D) \ldots X_{i}(d / D) .
$$

From (3.28) and recalling (3.13) we have

$$
\begin{align*}
\int_{\Omega}|\nabla u|^{k} d x & \leq \int_{\Omega} \phi^{k} d^{-k} X_{1}^{1+\alpha_{1}} X_{2}^{-1+\alpha_{2}} \ldots X_{m}^{-1+\alpha_{m}} \times  \tag{3.29}\\
& \times\left\{\left(\frac{k-1}{k}\right)^{k}+\left(\frac{k-1}{k}\right)^{k-1} \zeta+\frac{1}{2}\left(\frac{k-1}{k}\right)^{k-1} \zeta^{2}+c|\zeta|^{3}\right\} d x .
\end{align*}
$$

The term containing $|\zeta|^{3}$ is bounded uniformly with respect to $\alpha_{1}, \ldots, \alpha_{m}$ (cf Step 4 in the previous proposition). Moreover it is immediately seen that

$$
\begin{equation*}
\phi^{k} d^{-k} X_{1}^{1+\alpha_{1}} X_{2}^{-1+\alpha_{2}} . X_{m}^{-1+\alpha_{m}}=\frac{|u|^{k}}{d^{k}} X_{1}^{k} \tag{3.30}
\end{equation*}
$$

Hence

$$
\begin{align*}
& \tilde{I}_{m-1}[u] \leq \int_{\Omega} \phi^{k} d^{-k} X_{1}^{1+\alpha_{1}} X_{2}^{-1+\alpha_{2}} \ldots X_{m}^{-1+\alpha_{m}} \times \\
&\left\{\left(\frac{k-1}{k}\right)^{k-1}\left(-\alpha_{1}+\sum_{i=2}^{m}\left(1-\alpha_{i}\right) X_{2} \ldots X_{i}\right)+\right. \\
&+\frac{1}{2}\left(\frac{k-1}{k}\right)^{k-1}\left(-\alpha_{1}+\sum_{i=2}^{m}\left(1-\alpha_{i}\right) X_{2} \ldots X_{i}\right)^{2}- \\
&\left.-\frac{1}{2}\left(\frac{k-1}{k}\right)^{k-1} \sum_{i=2}^{m-1} X_{2}^{2} \ldots X_{i}^{2}\right\} d x+O(1) \tag{3.31}
\end{align*}
$$

where the $O(1)$ is uniform with respect to all the $\alpha_{i}$ 's. Expanding the square and collecting similar terms we conclude that

$$
\begin{equation*}
\tilde{I}_{m-1}[u] \leq \frac{1}{2}\left(\frac{k-1}{k}\right)^{k-1} \tilde{J}+O(1), \quad \text { uniformly in } \alpha_{1}, \ldots, \alpha_{m} \tag{3.32}
\end{equation*}
$$

where

$$
\begin{equation*}
\tilde{J}=A_{m}+\sum_{i=1}^{m}\left(\alpha_{i}^{2}-2 \alpha_{i}\right) A_{i}+2 \sum_{i=1}^{m-1} \sum_{j=i+1}^{m}\left(1-\alpha_{i}\right)\left(1-\alpha_{j}\right) \Gamma_{i j} \tag{3.33}
\end{equation*}
$$

We intend to take the limit $\alpha_{1} \rightarrow 0$ in (3.33). All terms have a finite limit except $A_{1}$ and $\Gamma_{1 j}$ which do not contain the factor $X_{2}^{1+\alpha_{2}}$. When combined they give

$$
\begin{aligned}
& \quad\left(\alpha_{1}^{2}-2 \alpha_{1}\right) A_{1}+2 \sum_{j=2}^{m}\left(1-\alpha_{1}\right)\left(1-\alpha_{j}\right) \Gamma_{1 j} \\
& (\text { by }(3.9))=\alpha_{1}^{2} A_{1}-2 \alpha_{1} \sum_{j=2}^{m}\left(1-\alpha_{j}\right) \Gamma_{1 j}+O(1) \\
& (\text { by }(3.9))=-\sum_{j=2}^{m}\left(1-\alpha_{j}\right) \alpha_{1} \Gamma_{1 j}+O(1) \\
& (\text { by }(3.10))=\sum_{j=2}^{m}\left(1-\alpha_{j}\right)\left(\sum_{i=2}^{j} \alpha_{i} \Gamma_{i j}-\sum_{i=j+1}^{m}\left(1-\alpha_{i}\right) \Gamma_{j i}\right)+O(1) \\
& =\sum_{i=2}^{m}\left(\alpha_{i}-\alpha_{i}^{2}\right) A_{i}+\sum_{i=2}^{m-1} \sum_{j=i+1}^{m}\left(2 \alpha_{i}-1\right)\left(1-\alpha_{j}\right) \Gamma_{i j}+O(1)
\end{aligned}
$$

In this expression we can let $\alpha_{1} \rightarrow 0$. Hence (3.33) becomes

$$
\begin{equation*}
\tilde{J}=A_{m}-\sum_{i=2}^{m} \alpha_{i} A_{i}+\sum_{i=2}^{m-1} \sum_{j=i+1}^{m}\left(1-\alpha_{j}\right) \Gamma_{i j}+O(1), \quad\left(\alpha_{1}=0\right) \tag{3.34}
\end{equation*}
$$

This relation is completely analogous to (3.20). For the rest of the proof we argue as in the proof of Proposition 3.1; we omit the details.

## References

[AS] Ambrosio L. and Soner H.M. Level set approach to mean curvature flow in arbitrary codimension. J. Diff. Geometry 43 (1996) 693-737.
[BFT] Barbatis G., Filippas S., and Tertikas A. A unified approach to improved $L^{p}$ Hardy inequalities with best constants. submitted.
[BM] Brezis H. and Marcus M. Hardy's inequalities revisited. Ann. Scuola Norm. Pisa 25 (1997) 217-237.
[BV] Brezis H. and Vázquez J.-L. Blow-up solutions of some nonlinear elliptic problems. Rev. Mat. Univ. Comp. Madrid 10 (1997) 443-469.
[D] Davies E.B. A review of Hardy inequalities. Oper. Theory Adv. Appl. 110 (1998) 55-67.
[DH] Davies E.B. and Hinz A.M. Explicit constants for Rellich inequalities in $L_{p}(\Omega)$. Math. Z. 227 (1998) 511-523.
[FT] Filippas S. and Tertikas A. Optimizing Improved Hardy inequalities. J. Funct. Anal., to appear.
[GGM] Gazzola F., Grunau H.-Ch. and Mitidieri E. Hardy inequalities with optimal constants and remainder terms. Trans. Amer. Math. Soc., to appear.
[HLP] Hardy G., Pólya G. and Littlewood J.E. Inequalities. 2nd edition, Cambridge University Press 1952.
[MMP] Marcus M., Mizel V.J. and Pinchover Y. On the best constant for Hardy's inequality in $\mathbb{R}^{n}$. Trans. Amer. Math. Soc. 350 (1998) 3237-3255.
[MS] Matskewich T. and Sobolevskii P.E. The best possible constant in generalized Hardy's inequality for convex domain in $\mathbb{R}^{n}$. Nonlinear Anal., Theory, Methods \& Appl., 28 (1997) 1601-1610.
[M] Maz'ja V.G. Sobolev spaces. Springer 1985.
[OK] Opic B. and Kufner A. Hardy-type inequalities. Pitman Research Notes in Math., vol.219, Longman 1990.
[VZ] Vazquez J.L. and Zuazua E., The Hardy inequality and the asymptotic behavior of the heat equation with an inverse-square potential. J. Funct. Anal. 173 (2000) 103-153.

