

Stability estimates in H_0^1 for solutions of elliptic equations in varying domains

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We consider second-order uniformly elliptic operators subject to Dirichlet boundary conditions. Such operators are considered on a bounded domain Ω and on the domain $\phi(\Omega)$ resulting from Ω by means of a bi-Lipschitz map ϕ . We consider the solutions u and \tilde{u} of the corresponding elliptic equations with the same right-hand side $f \in L^2(\Omega \cup \phi(\Omega))$. Under certain assumptions, we estimate the difference $\|\nabla\tilde{u} - \nabla u\|_{L^2(\Omega \cup \phi(\Omega))}$ in terms of certain measure of vicinity of ϕ to the identity map. For domains within a certain class, this provides estimates in terms of the Lebesgue measure of the symmetric difference of $\phi(\Omega)$ and Ω , that is, $|\phi(\Omega) \Delta \Omega|$. We provide an example that shows that the estimates obtained are in a certain sense sharp. Copyright © 2013 John Wiley & Sons, Ltd.

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1. Introduction

Let Ω be a bounded domain in \mathbb{R}^N and let $A = \{A^{ij}(x)\}$ be a measurable positive-definite symmetric matrix-valued function on \mathbb{R}^N bounded away from zero and infinity. Let

$$Lu = - \sum_{i,j=1}^N \frac{\partial}{\partial x_i} \left\{ A^{ij}(x) \frac{\partial u}{\partial x_j} \right\}, \quad \text{on } \Omega,$$

subject to Dirichlet boundary conditions. Let $\phi : \Omega \rightarrow \phi(\Omega)$ be a bi-Lipschitz map and let \tilde{L} be the analogous operator on $L^2(\phi(\Omega))$. We fix $f \in L^2(\Omega \cup \phi(\Omega))$ and consider the functions $u \in H_0^1(\Omega)$ and $\tilde{u} \in H_0^1(\phi(\Omega))$ defined by

$$Lu = f, \quad \text{in } \Omega, \quad \tilde{L}\tilde{u} = f, \quad \text{in } \phi(\Omega).$$

Our aim in this article is to estimate $\|\nabla\tilde{u} - \nabla u\|_{L^2(\Omega \cup \phi(\Omega))}$ in terms of a certain measure of vicinity of ϕ to the identity map.

Domain perturbation problems are an important branch of the theory of PDEs. Within spectral theory, one is typically interested on the stability of the eigenvalues or eigenfunctions of differential operators. There are several recent results on this type of problems; we refer to the article [1] and references therein for more on recent progress on domain perturbation problems in spectral theory.

The problem we are interested in involves the stability of the solution u of the equation $Lu = f$ under perturbation of the domain Ω . In the article [2], Savaré and Schimperna obtain very detailed sharp estimates on the variation in H_0^1 of u for operators with Lipschitz continuous coefficients. In [3], estimates are obtained on the variation of u in L^2 for operators with measurable coefficients. See also the articles [4–6] where relevant results were obtained.

In the present article, we consider uniformly elliptic operators with measurable coefficients and we prove stability estimates in H_0^1 for the solution u of $Lu = f$. While Theorems 3.1 and 3.2 are set in the framework of well-known results involving Mosco convergence (see [7] for a recent survey), they are, to our knowledge, the first results of this type for operators with L^∞ coefficients where actual estimates are provided. A simple example shows that the estimates are in a certain sense sharp. Our theorem has essentially two assumptions: the first is that Ω is perturbed by a global bi-Lipschitz map ϕ and the second is an *a priori* estimate on $\|\nabla u\|_{L^q}$, for some $q > 2$, for the solution of both problems, perturbed and unperturbed. We note that if $f \in L^q$ and Ω has Lipschitz boundary in the sense that there

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exists a bi-Lipschitz transformation that maps Ω onto a domain with C^1 boundary, then $\nabla u \in L^q$ by a well-known result of Meyers [8], so our results are applicable. The proof relies on the so-called pull-back method. The operator \tilde{L} that acts on $\phi(\Omega)$ induces naturally an operator on Ω , and it is that operator that is then compared with H . Hence, in the first section, we prove a stability estimate for operators acting on the same space under variation of the coefficients. Some additional results are established there, which are of independent interest.

The method of proof easily generalizes to other kinds of differential operators, such as higher-order operators, operators subject to Neumann boundary conditions or operators acting on Riemannian manifolds. For the sake of simplicity and brevity, we restrict our attention to second-order Dirichlet operators on bounded Euclidean domains.

2. A general stability theorem

In this section, we prove an auxiliary result, which we believe is of independent interest. Let Ω be a bounded domain in \mathbb{R}^N and for $\epsilon \geq 0$ let $A_\epsilon = (A_\epsilon^{ij})$ be a family of real, symmetric, matrix-valued measurable functions on Ω satisfying

$$\frac{1}{c}|\xi|^2 \leq \sum_{ij} A_\epsilon^{ij}(x)\xi_i\xi_j \leq c|\xi|^2, \quad \epsilon \geq 0, \quad x \in \Omega, \quad \xi \in \mathbb{R}^n. \quad (2.1)$$

For $\epsilon \geq 0$, we define the self-adjoint operator

$$H_\epsilon = - \sum_{ij} \frac{\partial}{\partial x_j} \left(A_\epsilon^{ij}(x) \frac{\partial}{\partial x_i} \right), \quad \text{on } L^2(\Omega),$$

subject to Dirichlet boundary conditions on $\partial\Omega$. We now fix $f \in L^2(\Omega)$, and we denote by u_ϵ the solution of $H_\epsilon u_\epsilon = f$, $\epsilon \geq 0$. Using a standard argument, we obtain from (2.1) that $\|u_\epsilon\|_{H^1(\Omega)} \leq c$ for all $\epsilon > 0$; hence, up to a subsequence, (u_ϵ) converges weakly in $H_0^1(\Omega)$.

We now assume that $\|A_\epsilon - A_0\|_{L^p(\Omega)} \equiv \sup_{ij} \{ \|A_\epsilon^{ij} - A_0^{ij}\|_{L^p(\Omega)} \} \rightarrow 0$ for some (equivalently, for all) $1 \leq p < \infty$. We then easily deduce that the weak H^1 -limit of (u_ϵ) is precisely u_0 . This implies in particular that the full sequence (u_ϵ) converges to u_0 weakly in $H_0^1(\Omega)$. It is a natural question to seek conditions under which the convergence $u_\epsilon \rightarrow u_0$ is strong in $H_0^1(\Omega)$. To our knowledge, this problem has not been studied. In the next theorem, we provide four conditions, each one of which guarantees strong convergence in $H_0^1(\Omega)$. The first of these conditions also provides an estimate for the rate of convergence $u_\epsilon \rightarrow u_0$ in $H_0^1(\Omega)$ and is the one that will be used for the domain perturbation problem in the next section.

Given a real symmetric matrix A , the matrix A_+ is defined by means of the spectral theorem: if $A = \sum \lambda_n (e_n \otimes e_n)$ is the spectral representation of A , then $A_+ := \sum (\lambda_n)_+ (e_n \otimes e_n)$.

Theorem 2.1

Assume that any one of the following four conditions is satisfied:

- (1) $\nabla u_0 \in L^q(\Omega)$ for some $q > 2$.
- (2) The eigenfunctions $\{\phi_n\}$ of H_0 satisfy $\|\nabla \phi_n\|_{L^q(\Omega)} \leq c\lambda_n^\gamma$ for some $q > 2, \gamma > 0$ and all $n \in \mathbb{N}$.
- (3) There exists a compact set $K \subset \Omega$ such that $A_\epsilon \rightarrow A_0$ in $L^\infty(\Omega \setminus K)$.
- (4) $(A_0 - A_\epsilon)_+ \rightarrow 0$ in $L^\infty(\Omega)$.

Then $u_\epsilon \rightarrow u_0$ in $H_0^1(\Omega)$ as $\epsilon \rightarrow 0$. Moreover, in case (1), we have the estimate

$$\|\nabla u_\epsilon - \nabla u_0\|_{L^2(\Omega)} \leq c\|\nabla u_0\|_{L^q(\Omega)} \|A_\epsilon - A_0\|_{L^{2q/(q-2)}(\Omega)}, \quad \epsilon > 0. \quad (2.2)$$

Proof of Theorem 2.1.

Part (1). Using the standard notation of repeated indices, we have

$$\begin{aligned} \int_{\Omega} A_\epsilon^{ij} \frac{\partial u_\epsilon}{\partial x_j} \cdot \left(\frac{\partial u_\epsilon}{\partial x_j} - \frac{\partial u_0}{\partial x_j} \right) dx &= \int_{\Omega} f(u_\epsilon - u_0) dx, \\ \int_{\Omega} A_0^{ij} \frac{\partial u_0}{\partial x_j} \cdot \left(\frac{\partial u_\epsilon}{\partial x_j} - \frac{\partial u_0}{\partial x_j} \right) dx &= \int_{\Omega} f(u_\epsilon - u_0) dx. \end{aligned}$$

Subtracting yields

$$\int_{\Omega} A_{\epsilon}^{ij} \left(\frac{\partial u_{\epsilon}}{\partial x_i} - \frac{\partial u_0}{\partial x_i} \right) \left(\frac{\partial u_{\epsilon}}{\partial x_j} - \frac{\partial u_0}{\partial x_j} \right) dx = \int_{\Omega} \left(A_0^{ij} - A_{\epsilon}^{ij} \right) \frac{\partial u_0}{\partial x_i} \left(\frac{\partial u_{\epsilon}}{\partial x_j} - \frac{\partial u_0}{\partial x_j} \right) dx, \tag{2.3}$$

hence, by (2.1) and Hölder's inequality, we obtain

$$\|\nabla u_{\epsilon} - \nabla u_0\|_{L^2(\Omega)} \leq c \|\nabla u_0\|_{L^q(\Omega)} \|A_{\epsilon} - A_0\|_{L^{2q/(q-2)}(\Omega)}.$$

Part (2). Let us denote by ∇ the gradient operator, from $H_0^1(\Omega)$ to $L^2(\Omega)$. By [9, Lemma 3], we have

$$u_{\epsilon} - u_0 = \nabla^* A_{\epsilon}^{1/2} \left(A_{\epsilon}^{1/2} \nabla \nabla^* A_{\epsilon}^{1/2} + 1 \right)^{-1} A_{\epsilon}^{-1/2} (A_0 - A_{\epsilon}) A_0^{-1/2} \left(A_0^{1/2} \nabla \nabla^* A_0^{1/2} + 1 \right)^{-1} A_0^{1/2} \nabla f,$$

therefore,

$$\begin{aligned} \|\nabla u_{\epsilon} - \nabla u_0\|_{L^2(\Omega)} &\leq \|A_{\epsilon}^{-1/2}\| \cdot \|A_{\epsilon}^{1/2} \nabla \nabla^* A_{\epsilon}^{1/2} \left(A_{\epsilon}^{1/2} \nabla \nabla^* A_{\epsilon}^{1/2} + 1 \right)^{-1}\| \times \\ &\quad \|A_{\epsilon}^{-1/2} (A_0 - A_{\epsilon}) A_0^{-1/2} \left(A_0^{1/2} \nabla \nabla^* A_0^{1/2} + 1 \right)^{-1} A_0^{1/2} \nabla\| \cdot \|f\|_{L^2(\Omega)} \\ &\leq c \| (A_0 - A_{\epsilon}) A_0^{-1/2} \left(A_0^{1/2} \nabla \nabla^* A_0^{1/2} + 1 \right)^{-1} A_0^{1/2} \nabla \|, \end{aligned}$$

where non-indexed norms are operator norms on $L^2(\Omega)$. By [9, Lemma 4], we conclude that

$$\|\nabla u_{\epsilon} - \nabla u_0\|_{L^2(\Omega)} \leq c \|A_{\epsilon} - A_0\|_{L^r(\Omega)}, \text{ all } r > \frac{2q}{q-2} \left(\frac{N}{2} + 2\gamma - 1 \right), \tag{2.4}$$

and the result follows.

Part (3). Going back to (2.3), applying (2.1) to the left-hand side and decomposing the integral in the right-hand side by integrating in K and in $\Omega \setminus K$, we obtain by Hölder inequality for any $q > 2$,

$$\frac{1}{c} \|\nabla u_{\epsilon} - \nabla u_0\|_{L^2(\Omega)}^2 \leq C \|A_{\epsilon} - A_0\|_{L^{\infty}(\Omega \setminus K)} \|\nabla u_{\epsilon} - \nabla u_0\|_{L^2(\Omega)} + C \|A_{\epsilon} - A_0\|_{L^{2q/(q-2)}(K)} \|\nabla u_0\|_{L^q(K)} \|\nabla u_{\epsilon} - \nabla u_0\|_{L^2(\Omega)}$$

which implies,

$$\|\nabla u_{\epsilon} - \nabla u_0\|_{L^2(\Omega)} \leq \tilde{C} \left(\|A_{\epsilon} - A_0\|_{L^{\infty}(\Omega \setminus K)} + \|A_{\epsilon} - A_0\|_{L^{2q/(q-2)}(K)} \|\nabla u_0\|_{L^q(K)} \right)$$

But interior estimates for the limit problem imply, see [8, Theorem 2], that there exists a $q > 2$ such that $\|\nabla u_0\|_{L^q(K)} \leq C$. Hence, we obtain the stated result.

Part (4). Let us start noticing that in general, because $u_{\epsilon} \rightarrow u_0$ weakly in $H^1(\Omega)$ and in particular in $L^2(\Omega)$, we obtain

$$\int_{\Omega} A_{\epsilon}^{ij} \frac{\partial u_{\epsilon}}{\partial x_i} \frac{\partial u_{\epsilon}}{\partial x_j} = \int_{\Omega} f u_{\epsilon} \rightarrow \int_{\Omega} f u_0 = \int_{\Omega} A_0^{ij} \frac{\partial u_0}{\partial x_i} \frac{\partial u_0}{\partial x_j} \tag{2.5}$$

Hence, we have

$$\begin{aligned} \int_{\Omega} A_0^{ij} \frac{\partial u_{\epsilon}}{\partial x_i} \frac{\partial u_{\epsilon}}{\partial x_j} dx &\leq \int_{\Omega} (A_0 - A_{\epsilon})^{ij} \frac{\partial u_{\epsilon}}{\partial x_i} \frac{\partial u_{\epsilon}}{\partial x_j} dx + \int_{\Omega} A_{\epsilon}^{ij} \frac{\partial u_{\epsilon}}{\partial x_i} \frac{\partial u_{\epsilon}}{\partial x_j} dx \\ &\rightarrow \int_{\Omega} A_0^{ij} \frac{\partial u_0}{\partial x_i} \frac{\partial u_0}{\partial x_j} dx \quad \text{as } \epsilon \rightarrow 0 \end{aligned}$$

where we have used the hypothesis and (2.5). Hence,

$$\limsup_{\epsilon \rightarrow 0} \int_{\Omega} \left(A_0^{ij} \frac{\partial u_{\epsilon}}{\partial x_i} \frac{\partial u_{\epsilon}}{\partial x_j} + |u_{\epsilon}|^2 \right) dx \leq \int_{\Omega} \left(A_0^{ij} \frac{\partial u_0}{\partial x_i} \frac{\partial u_0}{\partial x_j} + |u_0|^2 \right) dx.$$

Let us now consider the space $H^1(\Omega)$ with the Hilbert norm

$$\|u\|^2 = \int_{\Omega} \left(A_0^{ij} \frac{\partial u}{\partial x_i} \frac{\partial u}{\partial x_j} + |u|^2 \right) dx.$$

We have thus proved that $\limsup \|u_{\epsilon}\| \leq \|u_0\|$. Moreover, the weak convergence in $H_0^1(\Omega)$ with respect to the standard norm implies the weak convergence with respect to the equivalent norm $\|\cdot\|$; hence, $\liminf \|u_{\epsilon}\| \geq \|u_0\|$. We thus conclude that $\|u_{\epsilon}\| \rightarrow \|u_0\|$, and therefore, $u_{\epsilon} \rightarrow u_0$ strongly in $H_0^1(\Omega)$, as required. \square

Remark 1

If Ω has a Lipschitz boundary, in the sense that there exists a bi-Lipschitz transformation that maps Ω onto a domain with C^1 boundary, then condition (2) is satisfied. This follows easily from [8, Theorem 1].

Remark 2

It is an interesting problem to prove or disprove that $u_\epsilon \rightarrow u_0$ in $H_0^1(\Omega)$ without any assumptions other than those stated before Theorem 2.1.

We now present an example that shows that estimate (2.2) is sharp. We note that the same family of domains was used in [1] in order to prove the sharpness of certain stability estimates of the eigenvalues. Analogous domains have also been used in [10] in dimension $N \geq 3$.

We fix an angle $\pi < \beta < 2\pi$ and denote by Ω_β the circular sector of radius one and angle β ,

$$\Omega_\beta = \{(r, \theta) : 0 < r < 1, 0 < \theta < \beta\}.$$

Let u_0 be the solution of the problem,

$$\begin{cases} -\Delta u_0 = \frac{4\beta^2 - \pi^2}{\beta^2} \sin\left(\frac{\pi\theta}{\beta}\right), & \text{in } \Omega_\beta, \\ u_0 = 0, & \text{on } \partial\Omega_\beta. \end{cases} \tag{2.6}$$

(The factor $(4\beta^2 - \pi^2) / \beta^2$ is introduced to simplify subsequent calculations.) Simple computations give

$$u_0(x) = \left(r^{\frac{\pi}{\beta}} - r^2\right) \sin\left(\frac{\pi\theta}{\beta}\right), \quad 0 < r < 1, \quad 0 < \theta < \beta. \tag{2.7}$$

This implies in particular that $\nabla u_0 \in L^q(\Omega_\beta)$ if and only if $q < 2\beta / (\beta - \pi)$. We now fix $\alpha > 0$, and for $0 < \epsilon < 1$, we set

$$a_\epsilon(x) = \begin{cases} \alpha, & 0 < |x| < \epsilon, \\ 1, & \epsilon < |x| < 1. \end{cases}$$

We note that $a_\epsilon \rightarrow 1$ in $L^p(\Omega_\beta)$, $1 \leq p < \infty$, but not in $L^\infty(\Omega_\beta)$. Let us denote by u_ϵ the solution of the perturbed boundary-value problem

$$\begin{cases} -\operatorname{div}(a_\epsilon \nabla u_\epsilon) = \frac{4\beta^2 - \pi^2}{\beta^2} \sin\left(\frac{\pi\theta}{\beta}\right), & \text{in } \Omega_\beta, \\ u_\epsilon = 0, & \text{on } \partial\Omega_\beta. \end{cases} \tag{2.8}$$

From part (2) of Theorem 2.1, it follows that

$$\|\nabla u_\epsilon - \nabla u_0\|_{L^2(\Omega_\beta)} \leq c \|a_\epsilon - a_0\|_{L^p(\Omega_\beta)} = c \epsilon^{\frac{2}{p}}, \quad \text{all } p > \frac{2\beta}{\pi}.$$

Now, simple computations give that $u_\epsilon(x) = v_\epsilon(r) \sin(\pi\theta/\beta)$, where

$$v_\epsilon(r) = \begin{cases} \frac{\left(\frac{1}{\alpha} - 1\right) \left(\epsilon^2 + \epsilon^{2 - \frac{2\pi}{\beta}}\right) + 2\epsilon^{-\frac{\pi}{\beta}}}{(1 - \alpha)\epsilon^{\frac{\pi}{\beta}} + (1 + \alpha)\epsilon^{-\frac{\pi}{\beta}}} r^{\frac{\pi}{\beta}} - \frac{1}{\alpha} r^2, & 0 < r < \epsilon, \\ \frac{(1 - \alpha)\epsilon^2 + (1 + \alpha)\epsilon^{-\frac{\pi}{\beta}}}{(1 - \alpha)\epsilon^{\frac{\pi}{\beta}} + (1 + \alpha)\epsilon^{-\frac{\pi}{\beta}}} r^{\frac{\pi}{\beta}} + \frac{(1 - \alpha) \left(\epsilon^{\frac{\pi}{\beta}} - \epsilon^2\right)}{(1 - \alpha)\epsilon^{\frac{\pi}{\beta}} + (1 + \alpha)\epsilon^{-\frac{\pi}{\beta}}} r^{-\frac{\pi}{\beta}} - r^2, & \epsilon < r < 1. \end{cases}$$

Let us denote $u_0(x) = v_0(r) \sin(\pi\theta/\beta)$ (cf. (2.7)). We then have

$$\begin{aligned} \|\nabla u_\epsilon - \nabla u_0\|_{L^2(\Omega_\beta)}^2 &\geq c \int_0^\epsilon (v'_\epsilon - v'_0)^2 r \, dr \\ &= \frac{\pi(1 - \alpha)^2}{2\beta(1 + \alpha)^2} \epsilon^{\frac{2\pi}{\beta}} (1 + o(1)), \quad \text{as } \epsilon \rightarrow 0. \end{aligned}$$

We conclude that the index $2q/(q - 2)$ in (2.2) cannot be replaced by any smaller index.

3. Stability estimates in H_0^1 under domain perturbation

Let Ω be a bounded domain in \mathbb{R}^N . We fix $M > 0$. Let $\phi : \Omega \rightarrow \tilde{\Omega} =: \tilde{\Omega}$ be a bi-Lipschitz transformation such that

$$\|D\phi\|_{L^\infty(\Omega)} \leq M, \quad \|(D\phi)^{-1}\|_{L^\infty(\tilde{\Omega})} \leq M. \tag{3.1}$$

We set $E = \{x \in \Omega : \phi(x) \neq x\}$ and we note that

$$\|F \circ \phi - F\|_{L^2(\Omega)} \leq \|F\|_{L^q(\Omega)} |E|^{\frac{q-2}{2q}}, \quad \|(D\phi)^{\pm 1} - I\|_{L^q(\Omega)} \leq c|E|^{\frac{q-2}{2q}}. \quad (3.2)$$

Let $A = \{A^{ij}(x)\}$ be measurable and symmetric on $\Omega \cup \tilde{\Omega}$ satisfying

$$\frac{1}{M} |\xi|^2 \leq \sum_{ij} A^{ij}(x) \xi_i \xi_j \leq M |\xi|^2, \quad x \in \Omega \cup \tilde{\Omega}, \quad \xi \in \mathbb{R}^N.$$

Let L (resp. \tilde{L}) denote the operator $-\sum_{ij} \partial_{x_j} \{A^{ij} \partial_{x_i}\}$ on $L^2(\Omega)$ (resp. $L^2(\tilde{\Omega})$) subject to Dirichlet boundary conditions. We fix $f \in L^2(\Omega \cup \tilde{\Omega})$ and we denote by u (resp. \tilde{u}) the solution of $Lu = f$ (resp. $\tilde{L}\tilde{u} = f$). We extend ∇u and $\nabla \tilde{u}$ to be zero outside their respective domains. We then have the following.

Theorem 3.1

Assume that there exists $q > 2$ such that $\|f\|_{L^q(\Omega \cup \tilde{\Omega})} \leq M$, $\|\nabla u\|_{L^q(\Omega)} \leq M$ and $\|\nabla \tilde{u}\|_{L^q(\tilde{\Omega})} \leq M$. Then there exists a constant c depending only on M such that

$$\|\nabla \tilde{u} - \nabla u\|_{L^2(\Omega \cup \tilde{\Omega})} \leq c|E|^{\frac{q-2}{2q}}. \quad (3.3)$$

Proof

We set $g(x) = |\det D\phi(x)|$, $x \in \Omega$. We note that given $v \in H_0^1(\tilde{\Omega})$ and letting $u = v \circ \phi$, we have

$$\int_{\tilde{\Omega}} |v|^2 dy = \int_{\Omega} |u|^2 g dx$$

and

$$\int_{\tilde{\Omega}} \sum_{ij=1}^N A^{ij} \frac{\partial v}{\partial y_i} \frac{\partial \tilde{v}}{\partial y_j} dy = \int_{\Omega} \sum_{ij=1}^N a^{ij} \frac{\partial u}{\partial x_i} \frac{\partial \tilde{u}}{\partial x_j} g dx,$$

where $a = (a^{ij})_{i,j=1,\dots,N}$ is defined on Ω by

$$a^{ij} = \sum_{r,s=1}^N \left(A^{rs} \frac{\partial \phi_i^{(-1)}}{\partial y_r} \frac{\partial \phi_j^{(-1)}}{\partial y_s} \right) \circ \phi = \left((D\phi)^{-1} (A \circ \phi) (D\phi)^{-t} \right)_{ij}. \quad (3.4)$$

This leads to the notion of the *pull-back*: the pull-back of \tilde{L} to Ω is the self-adjoint operator \tilde{H} on $L^2(\Omega, g dx)$ associated with the sesquilinear form \tilde{Q} with $\text{Dom}(\tilde{Q}) = H_0^1(\Omega)$ and

$$\tilde{Q}(u_1, u_2) = \int_{\Omega} \sum_{ij=1}^N a^{ij} \frac{\partial u_1}{\partial x_i} \frac{\partial \tilde{u}_2}{\partial x_j} g dx, \quad u_1, u_2 \in H_0^1(\Omega).$$

So formally, $\tilde{H}U = -g^{-1} \sum_{ij} (ga^{ij} U_{x_i})_{x_j}$. Equivalently, \tilde{H} can be defined as $\tilde{H} = C_\phi \tilde{L} C_\phi^{-1}$, where $C_\phi : L^2(\tilde{\Omega}) \rightarrow L^2(\Omega, g dx)$ denotes composition by ϕ (a unitary operator).

It then follows that $\tilde{H} = g^{-1} \hat{H}$, where \hat{H} is the self-adjoint operator on $L^2(\Omega)$ associated to the form \tilde{Q} defined previously on $H_0^1(\Omega)$. Now, let $\hat{u} \in L^2(\Omega)$ be defined by $\hat{H}\hat{u} = f$. Using (1) of Theorem 2.1 and also (3.2), we obtain

$$\|\nabla \hat{u} - \nabla u\|_{L^2(\Omega)} \leq c \|a - A\|_{L^{\frac{2q}{q-2}}(\Omega)} \leq c|E|^{\frac{q-2}{2q}}.$$

Moreover, we have

$$\begin{cases} \tilde{H}(\tilde{u} \circ \phi) = f \circ \phi, \\ \hat{H}\hat{u} = gf. \end{cases} \quad (3.5)$$

Hence, by (3.2),

$$\|\nabla(\tilde{u} \circ \phi) - \nabla \hat{u}\|_{L^2(\Omega)} \leq c \|f \circ \phi - gf\|_{L^2(\Omega)} \leq c|E|^{\frac{q-2}{2q}}. \quad (3.6)$$

Finally by (3.2), we also have

$$\|\nabla(\tilde{u} \circ \phi) - \nabla \tilde{u}\|_{L^2(\Omega)} \leq c|E|^{\frac{q-2}{2q}}. \tag{3.7}$$

Combining (3.5), (3.6) and (3.7), we obtain that $\|\nabla \tilde{u} - \nabla u\|_{L^2(\Omega)} \leq c|E|^{\frac{q-2}{2q}}$. We also have

$$|\tilde{\Omega} \setminus \Omega| \leq c|\phi^{-1}(\tilde{\Omega} \setminus \Omega)| \leq c|E|,$$

hence, $\|\nabla \tilde{u} - \nabla u\|_{L^2(\tilde{\Omega})} \leq c|E|^{\frac{q-2}{2q}}$ by Hölder inequality. This concludes the proof. \square

Using Theorem 3.1, we can now prove stability estimates in H_0^1 for localized perturbations in terms of the Lebesgue measure. We consider the following class of domains (see also [11]):

Definition 1

Let V be a bounded open cylinder; that is, there exists a rotation R such that $R(V) = W \times]a, b[$, where W is a bounded convex open set in \mathbb{R}^{N-1} . Let $M, \rho > 0$. We say that a bounded open set $\Omega \subset \mathbb{R}^N$ belongs to $C_M^{0,1}(V, R)$ if Ω is of class $C^{0,1}$ (i.e., Ω is locally a subgraph of $C^{0,1}$ functions) and there exists a function $h \in C^{0,1}(\bar{W})$ such that $a + (b - a)/10 \leq h \leq b$, $\text{Lip}(h) \leq M$ and

$$R(\Omega \cap V) = \{(\bar{x}, x_N) : \bar{x} \in W, a < x_N < h(\bar{x})\}. \tag{3.8}$$

In the following theorem, again, ∇u and $\nabla \tilde{u}$ are extended to be zero outside Ω and $\tilde{\Omega}$, respectively.

Theorem 3.2

Let $\Omega, \tilde{\Omega}$ be domains of class $C_M^{0,1}(V, R)$ with $\Omega \setminus V = \tilde{\Omega} \setminus V$. Let $f \in L^2(\Omega \cup \tilde{\Omega})$ and let $u \in H_0^1(\Omega)$ and $\tilde{u} \in H_0^1(\tilde{\Omega})$ solve $Lu = f$ and $\tilde{L}\tilde{u} = f$, respectively. Assume that there exists $q > 2$ such that $\|f\|_{L^q(\Omega \cup \tilde{\Omega})} \leq M$, $\|\nabla u\|_{L^q(\Omega)} \leq M$ and $\|\nabla \tilde{u}\|_{L^q(\tilde{\Omega})} \leq M$. Then there exists a constant c depending only on M such that

$$\|\nabla \tilde{u} - \nabla u\|_{L^2(\Omega \cup \tilde{\Omega})} \leq c|\tilde{\Omega} \Delta \Omega|^{\frac{q-2}{2q}}. \tag{3.9}$$

Proof

It has been proved in [3], following earlier work of Burenkov and Lamberti [11], that if Ω and $\tilde{\Omega}$ are in $C_M^{0,1}(V, R)$, then there exists a bi-Lipschitz diffeomorphism $\phi : \Omega \rightarrow \tilde{\Omega}$ whose Lipschitz constants are estimated in terms of M only and such that $|E| \leq c|\tilde{\Omega} \Delta \Omega|$, where c also depends only on M . Hence, (3.9) follows from Theorem 3.1. \square

We now present an example that shows that estimate (2.2) is sharp. We fix $\pi < \beta < 2\pi$ and $0 \leq \epsilon < 1$ and denote by $\Omega_{\epsilon, \beta}$ the planar domain

$$\Omega_{\epsilon, \beta} = \{(r, \theta) : \epsilon < r < 1, 0 < \theta < \beta\}.$$

We denote by u_ϵ be the solution of the problem

$$\begin{cases} -\Delta u_\epsilon = \frac{4\beta^2 - \pi^2}{\beta^2} \sin\left(\frac{\pi\theta}{\beta}\right), & \text{in } \Omega_{\epsilon, \beta}, \\ u_\epsilon = 0, & \text{on } \partial\Omega_{\epsilon, \beta}. \end{cases} \tag{3.10}$$

The function u_0 has been computed in (2.7). For $\epsilon > 0$, a direct computation gives that $u_\epsilon(x) = v_\epsilon(r) \sin(\pi\theta/\beta)$, where

$$v_\epsilon(r) = \frac{\epsilon^{-\pi/\beta} - \epsilon^2}{\epsilon^{-\pi/\beta} - \epsilon^{\pi/\beta}} r^{\frac{\pi}{\beta}} + \frac{\epsilon^2 - \epsilon^{\pi/\beta}}{\epsilon^{-\pi/\beta} - \epsilon^{\pi/\beta}} r^{-\frac{\pi}{\beta}} - r^2, \quad \epsilon < r < 1.$$

We then easily obtain the asymptotic formula

$$\|\nabla u_\epsilon - \nabla u_0\|_{L^2(\Omega_0)} = A\epsilon^{\pi/\beta} (1 + o(1)), \tag{3.11}$$

for some $A > 0$.

Let us now see what our theorem gives. We note that the domains are not of some class $C_M^{0,1}(V, R)$ uniformly in ϵ , so we cannot directly apply Theorem 3.2. Instead, let $s_\epsilon : (0, 1) \rightarrow (\epsilon, 1)$,

$$s_\epsilon(r) = \begin{cases} \frac{r}{2} + \epsilon, & 0 < r < 2\epsilon, \\ r, & 2\epsilon < r < 1. \end{cases}$$

We define the bi-Lipschitz map $\phi_\epsilon : \Omega_0 \rightarrow \Omega_{\epsilon, \beta}$, given in polar coordinates by

$$\phi_\epsilon(r, \theta) = (s_\epsilon(r), \theta), \quad 0 < r < 1, \quad 0 < \theta < \beta.$$

Using the explicit computation of u_0 and u_ϵ , we easily see that the assumptions of Theorem 3.1 are satisfied for any (fixed) $q < 2\beta/(\beta - \pi)$. Hence, Theorem 3.1 gives

$$\|\nabla u_\epsilon - \nabla u_0\|_{L^2(\Omega_0 \cup \Omega_\epsilon)} \leq c_q |E_\epsilon|^{\frac{q-2}{2q}} = c_q \epsilon^{\frac{q-2}{q}} = c_\delta \epsilon^{\frac{\pi}{\beta} - \delta},$$

for any $\delta > 0$. Because of (3.11), this shows that the exponent of $|E|$ in (3.3) cannot be replaced by a smaller one.

Remark 3

It is worth pointing out that the eigenvalue stability estimates obtained in [1, 11] have the term $|\tilde{\Omega} \Delta \Omega|^{\frac{q-2}{q}}$ in the RHS; the exponent $(q - 2)/q$ is twice the one in (3.9) and is also sharp.

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