

Typical properties of contractions on ℓ_p spaces

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- ▶ A **Polish space** is a topological space which is separable and completely metrizable, i.e. its topology can be defined by a distance which turns it into a complete metric space.

Examples:

- any separable complete metric space;
 - $(0, 1)$ endowed with the topology induced by that of \mathbb{R} is a Polish space.
- ▶ In a Polish space, the Baire Category Theorem applies: if (U_n) is a sequence of open dense subsets of X , then $\bigcap_n U_n$ is dense in X .

A countable intersection of open sets is called a G_δ set. A set containing a dense G_δ set is called a **comeager** set.

- ▶ **Philosophy:** In a Polish space, the comeager sets (i.e. the sets containing an intersection of dense open sets) are **big sets** in the Baire category sense.

By the Baire Category Theorem, countable intersections of big sets in this sense are again big.

This motivates the following definition:

Definition. Let X be a Polish space, and let (P) be a certain property of elements of X . We say that property (P) is **typical**, or that **a typical $x \in X$ has property (P)** if the set

$$\{x \in X ; x \text{ has } (P)\}$$

is comeager in X .

- ▶ **Examples:**

- a typical $x \in (\mathbb{R}, | \cdot |)$ is irrational;
- a typical probability measure $\mu \in \mathcal{P}_1([0, 1], w^*)$ is continuous and purely singular with respect to Lebesgue measure.

Definition. Let X be a (complex) separable Banach space.

$$\mathcal{B}_1(X) := \{T \in \mathcal{B}(X) ; \|T\| \leq 1\}.$$

- ▶ **Aim:** put on $\mathcal{B}_1(X)$ a topology τ which turns it into a Polish space, and study whether some properties of elements of $(\mathcal{B}_1(X), \tau)$ are typical, or not.
- ▶ **Natural choices of topologies on $\mathcal{B}_1(X)$:**
 - the operator-norm topology: $(\mathcal{B}_1(X), \|\cdot\|)$ is usually not separable \rightarrow not Polish;
 - the WOT (Weak Operator Topology): $T_i \rightarrow T$ for the WOT if $T_i x \rightarrow T x$ weakly for every $x \in X$;
 - the SOT (Strong Operator Topology): $T_i \rightarrow T$ for the SOT if $T_i x \rightarrow T x$ in norm for every $x \in X$;
 - the SOT* (Strong* Operator Topology): $T_i \rightarrow T$ for the SOT* if $T_i \rightarrow T$ and $T_i^* \rightarrow T^*$ for the SOT.

- ▶ **ℓ_p -spaces:** They are sequence spaces defined for $1 \leq p < +\infty$ as

$$\ell_p(\mathbb{N}) := \{x = (x_j)_{j \geq 0} ; \sum_j |x_j|^p < +\infty\}$$

endowed with the norm

$$\|x\|_p = \left(\sum_j |x_j|^p \right)^{\frac{1}{p}}$$

which turns them into Banach spaces.

- ▶ **Canonical basis:** for $j \geq 0$,

$$e_j := (0, \dots, 0, 1, 0, \dots)$$

where 1 appears in the j -th place. Any $x \in \ell_p(\mathbb{N})$ can be written in a unique way as

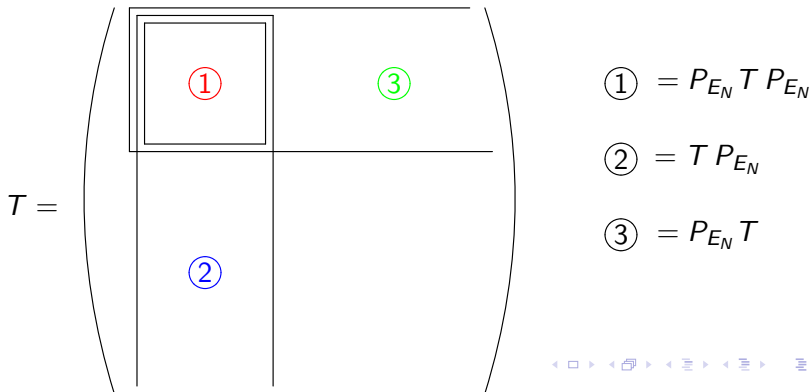
$$x = \sum_j x_j e_j$$

where the series converges in $\ell_p(\mathbb{N})$.

Example. Let $(e_j)_{j \geq 0}$ be the canonical basis of $\ell_p(\mathbb{N})$, and set $E_N = [e_0, \dots, e_N]$, $N \geq 0$. Let $T_0, T \in \mathcal{B}_1(\ell_p)$.

- ▶ T is WOT-close to T_0 if $\|P_{E_N}(T - T_0)P_{E_N}\| < \varepsilon$.
- ▶ T is SOT-close to T_0 if $\|(T - T_0)P_{E_N}\| < \varepsilon$.
- ▶ T is SOT*-close to T_0 if

$$\|(T - T_0)P_{E_N}\| < \varepsilon \quad \text{and} \quad \|P_{E_N}(T - T_0)\| < \varepsilon.$$



Proposition.

- If X is separable, $(\mathcal{B}_1(X), \text{SOT})$ is a Polish space.
- If X^* is separable, $(\mathcal{B}_1(X), \text{SOT}^*)$ is a Polish space.
- If X is reflexive, $(\mathcal{B}_1(X), \text{WOT})$ is a Polish space.

* * *

Let (x_n) be dense in the unit sphere of X . The distance d on $\mathcal{B}_1(X)$ defined by

$$T, S \in \mathcal{B}_1(X); d(S, T) = \sum_n 2^{-n} \| (T - S)x_n \|^2$$

is an equivalent distance for the SOT on $\mathcal{B}_1(X)$ which turns it into a complete metric space.

* * *

If $X = \ell_p(\mathbb{N})$, $1 \leq p < +\infty$, or $X = c_0(\mathbb{N})$,

- $(\mathcal{B}_1(X), \text{SOT})$ is a Polish space;
- if $p > 1$, $(\mathcal{B}_1(X), \text{SOT}^*)$ and $(\mathcal{B}_1(X), \text{WOT})$ are Polish spaces.

Question. Find some interesting typical properties of operators $T \in \mathcal{B}_1(\ell_p)$ or $T \in \mathcal{B}_1(c_0)$ for one of these Polish topologies.

For instance, one may ask: is it true

- that a typical contraction on ℓ_p or c_0 for one of these topologies has an eigenvector?
- that it has a non-trivial invariant subspace, i.e. a closed subspace M of X with $M \neq \{0\}$ and $M \neq X$ such that $T(M) \subseteq M$?

Recall that saying for instance that a typical $T \in (\mathcal{B}_1(\ell_p), \text{SOT})$ has a non-trivial invariant subspace means that the set

$$\{T \in \mathcal{B}_1(\ell_p) ; T \text{ has a non-trivial invariant subspace}\}$$

contains a comeager subset of $(\mathcal{B}_1(\ell_p), \text{SOT})$.

The Invariant Subspace Problem. Given a bounded operator T on a separable (infinite-dimensional) Banach space X , does there exist a closed subspace M of X which is *non-trivial* ($M \neq \{0\}$ and $M \neq X$), and *T -invariant* (i.e. $T(M) \subseteq M$)?

- ▶ ENFLO, '70: No. Counterexamples on some strange Banach spaces.
- ▶ READ, '80: more counterexamples, much simpler, on some classical Banach spaces like ℓ_1 , c_0 , $\bigoplus_{\ell_2} J$.
Examples of operators on ℓ_1 without non-trivial invariant closed *subset*.
- ▶ GRIVAUX-ROGINSKAYA: unification of Read's type constructions on *non-reflexive* Banach spaces.

- ▶ ARGYROS-HAYDON '11: there exist Banach spaces X such that every $T \in \mathcal{B}(X)$ has a non-trivial invariant subspace.

The Invariant Subspace Problem is widely open for reflexive spaces and, most importantly, for Hilbert spaces.

ℓ_p -spaces: very interesting class of Banach spaces in this context.

This motivates the question we asked a few slides ago:

Question. Given a “natural” Polish topology on $\mathcal{B}_1(\ell_p)$, is it true that a typical contraction T for this topology has a non-trivial invariant subspace?

- ▶ **The Hilbertian case:** typical properties of contractions on ℓ_2 for the WOT and the SOT were studied by EISNER and EISNER-MÁTRAI.

Theorem. *A typical $T \in (\mathcal{B}_1(\ell_2), \text{WOT})$ is unitary.*

Theorem. *A typical $T \in (\mathcal{B}_1(\ell_2), \text{SOT})$ is unitarily similar to the backward shift of infinite multiplicity B_∞ on $\bigoplus_{\ell_2} \ell_2$:*

$$B_\infty : \bigoplus_{\ell_2} \ell_2 \longrightarrow \bigoplus_{\ell_2} \ell_2, \quad (x_0, x_1, x_2, \dots) \longmapsto (x_1, x_2, x_3, \dots)$$

- ▶ **Consequences:**

A typical $T \in (\mathcal{B}_1(\ell_2), \text{WOT})$ has a non-trivial invariant subspace.

A typical $T \in (\mathcal{B}_1(\ell_2), \text{SOT})$ has eigenvectors (and hence invariant subspaces), and is such that T^* is an isometry.

Why should such results be true?

- ▶ the case of WOT-typical contractions: given $x \in \ell_2(\mathbb{N})$, the maps

$$T \mapsto \|Tx\| \quad \text{and} \quad T \mapsto \|T^*x\|$$

are **not** continuous. A WOT-typical T is such that T and T^* are isometries.

- ▶ the case of SOT-typical contractions: given $x \in \ell_2(\mathbb{N})$, the maps

$$T \mapsto \|Tx\|$$

are indeed continuous, but the maps

$$T \mapsto \|T^*x\|$$

are **not** continuous. An SOT-typical T is such that T^* is an isometry.

Typical properties of contractions for the the SOT^* topology are not so well understood. For instance a typical $T \in (\mathcal{B}_1(\ell_2), SOT^*)$ has no eigenvalue [GRIVAUX-MATHERON-MENET].

It is still true that a typical $T \in (\mathcal{B}_1(\ell_2), SOT^*)$ has non-trivial invariant subspaces, but for much less “trivial” reasons than for the SOT and the WOT.

► **Brown-Chevreau-Pearcy Theorem:**

If $T \in \mathcal{B}_1(\ell_2)$ is such that its spectrum contains the whole unit circle \mathbb{T} , then T has a non-trivial invariant subspace.

One can show without too much trouble that a typical $T \in \mathcal{B}_1(\ell_p)$ or $\mathcal{B}_1(c_0)$ for one of the topologies SOT or SOT^* is such that $\sigma(T) = \overline{\mathbb{D}(0, 1)} \supseteq \mathbb{T}$.

- ▶ What happens for SOT-typical contractions on $X \equiv \ell_p$, $1 \leq p \neq 2 < +\infty$?

For $p = 1$, the situation is surprisingly similar to the Hilbertian one:

Theorem. *A typical $T \in (\mathcal{B}_1(\ell_1), \text{SOT})$ is such that any $\lambda \in \mathbb{D}(0, 1)$ is an eigenvalue of T of infinite multiplicity, and T^* is an isometry.*

Consequently, a typical $T \in (\mathcal{B}_1(\ell_1), \text{SOT})$ has a non-trivial invariant subspace.

- ▶ What happens for SOT-typical contractions on $X = \ell_p$, $1 < p \neq 2 < +\infty$?

We do not know really. . .

Theorem. *Let $p > 2$. A typical $T \in (\mathcal{B}_1(\ell_p), \text{SOT})$ has no eigenvalue.*

Recall that it follows from the Eisner-Mátrai result that a typical $T \in (\mathcal{B}_1(\ell_2), \text{SOT})$ is such that any $\lambda \in \mathbb{D}$ is an eigenvalue of T .

We can actually prove the following stronger result:

Theorem. Let $p > 2$. A typical $T \in (\mathcal{B}_1(\ell_p), \text{SOT})$ is such that $2T^*$ is a hypercyclic operator.

Definition. An operator $S \in \mathcal{B}(X)$ is **hypercyclic** if there exists $x \in X$ whose orbit $\{S^n x; n \geq 0\}$ is dense in X .

If S is hypercyclic, S^* has no eigenvalue:

$$Sx^* = \lambda x^* \Rightarrow \forall x \in X, \forall n \geq 0, \quad \langle x^*, S^n x \rangle = \lambda^n \langle x^*, x \rangle.$$

If x is a hypercyclic vector and if $x^* \neq 0$, the set $\{\langle x^*, S^n x \rangle; n \geq 0\}$ is dense in $\mathbb{C} \Rightarrow$ contradiction.

Recall again: a typical $T \in (\mathcal{B}_1(\ell_2), \text{SOT})$ is such that T^* is an isometry.

Theorem. Let $p > 2$. A typical $T \in (\mathcal{B}_1(\ell_p), \text{SOT})$ has no eigenvalue.

A key step in the proof of this theorem is given by the following rather intriguing result:

Theorem. Let $p > 2$, and let G be a subset of $\mathcal{B}_1(\ell_p)$. If G is comeager in $(\mathcal{B}_1(\ell_p), \text{SOT}^*)$, then G is comeager in $(\mathcal{B}_1(\ell_p), \text{SOT})$.

This statement is non-trivial: $\text{SOT}^* - G_\delta \not\Rightarrow \text{SOT} - G_\delta$.

Proposition. Let $p > 1$. A typical $T \in (\mathcal{B}_1(\ell_p), \text{SOT}^*)$ has no eigenvalue.

Theorem. Let $p > 2$ and let G be a subset of $\mathcal{B}_1(\ell_p)$. If G is comeager in $(\mathcal{B}_1(\ell_p), \text{SOT}^*)$, then G is comeager in $(\mathcal{B}_1(\ell_p), \text{SOT})$.

Idea of proof: *Banach-Mazur game*.

Let \mathcal{E} be a Polish space, $\mathcal{A} \subseteq \mathcal{E}$. Two players I and II play alternatively non-empty open sets $\mathcal{U}_0 \supseteq \mathcal{U}_1 \supseteq \dots$. Player II wins the run if $\bigcap_n \mathcal{U}_n \subseteq \mathcal{A}$.

The set \mathcal{A} is comeager in \mathcal{E} if and only if player II has a winning strategy in this game.

WLOG, the sets \mathcal{U}_n can be required to be picked from a given basis of the topology of \mathcal{E} .

In our context, let $\mathcal{E} = (\mathcal{B}_1(\ell_p), \text{SOT})$. Let $(e_j)_{j \geq 0}$ be the canonical basis of ℓ_p , and let $E_N = [e_0, \dots, e_N]$ for $N \geq 0$.

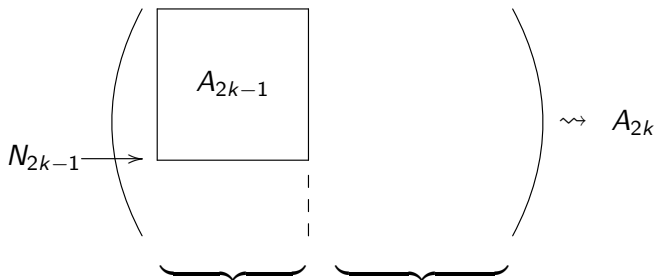
The open sets played in the game will be of the form

$$\mathcal{U}(N, A, \varepsilon) = \{T \in \mathcal{B}_1(\ell_p) ; \|Te_j - Ae_j\| < \varepsilon \text{ for } j = 0 \dots N\}$$

where $N \geq 0$, $A \in \mathcal{B}_1(E_N)$, and $0 < \varepsilon \leq 1$.

Player I plays $\mathcal{U}_{2k} = \mathcal{U}(N_{2k}, A_{2k}, \varepsilon_{2k})$,

Player II plays $\mathcal{U}_{2k+1} = \mathcal{U}(N_{2k+1}, A_{2k+1}, \varepsilon_{2k+1})$.



At step $2k$:

Small variation

Anything, provided that the operator remains a contraction

“Anything, provided that the operator remains a contraction”: It is here that the condition that $p > 2$ appears, through the following elementary inequality (to be found for instance in a paper by C. H. KAN):

Lemma. *Let $u, v \in \mathbb{C}^*$. If $2 < p < +\infty$,*

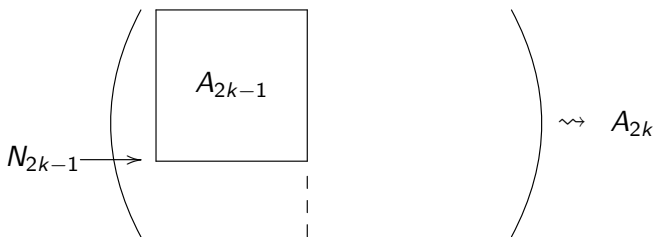
$$|u + v|^p + |u - v|^p > 2|u|^p + p|u|^{p-2}|v|.$$

Corollary. Let $T \in \mathcal{B}_1(\ell_p)$, $p > 2$. If $f \in S_{\ell_p}$ is such that $\|Tf\| = 1$, then $\forall g \in \ell_p$,

$$\text{supp}(f) \cap \text{supp}(g) = \emptyset \implies \text{supp}(Tf) \cap \text{supp}(Tg) = \emptyset.$$

Corollary. Let $T \in \mathcal{B}_1(\ell_p)$, $p > 2$. If $f \in S_{\ell_p}$ is such that $\|Tf\| = 1$, then $\forall g \in \ell_p$,

$$\text{supp}(f) \cap \text{supp}(g) = \emptyset \implies \text{supp}(Tf) \cap \text{supp}(Tg) = \emptyset.$$



If A_{2k-1} has norm 1 and attains its norm on $E_{N_{2k-1}}$ at f such that

$$\text{supp}(f) = \text{supp}(A_{2k-1}f) = [0, N_{2k-1}],$$

then in order for A_{2k} to remain a contraction one must have

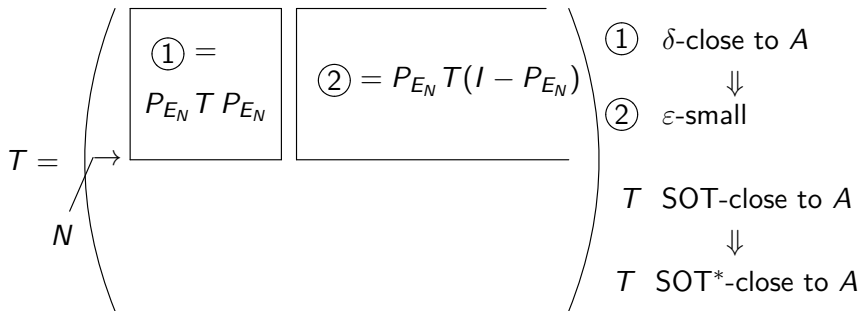
$$\text{supp}(A_{2k}(e_l)) \subseteq (N_{2k-1}, +\infty) \quad \text{for every } l > N_{2k-1}.$$

Proposition. Let $p > 2$, and let $A \in \mathcal{B}_1(E_N)$ be such that

(*) the norming vectors $x \in S_{E_N}$ of the operator A consist of unimodular multiples of a single vector $x_0 \in S_{E_N}$, and $\langle e_j^*, x_0 \rangle \neq 0$ and $\langle e_j^*, Ax_0 \rangle \neq 0$ for every $j = 0, \dots, N$.

Then for any $\varepsilon > 0$ there exists $\delta > 0$ such that for any $T \in \mathcal{B}_1(\ell_p)$,

$$\|P_{E_N} T P_{E_N} - A\| < \delta \implies \|P_{E_N} T (I - P_{E_N})\| < \varepsilon.$$



The proof breaks down for $1 < p < 2$, and we do not know the answer to the following question:

Question.

If $1 < p < 2$, is it true that a typical $T \in (\mathcal{B}_1(\ell_p), \text{SOT})$ has no eigenvalue?

Well... we are still unable to answer the following question:

Question. If $p > 1$, $p \neq 2$, is it true that a typical $T \in (\mathcal{B}_1(\ell_p), \text{SOT})$ has a non-trivial invariant subspace?

Theorem. *If $p > 1$, $p \neq 2$, a typical $T \in (\mathcal{B}_1(\ell_p), \text{SOT})$ has a non-trivial invariant cone.*

(C is a cone if $C + C \subseteq C$ and $tC \subseteq C$ for every $t \geq 0$)

This theorem follows from results of V. MÜLLER.

Summary: typical properties of $T \in (\mathcal{B}_1(\ell_p), \text{SOT})$:

	$p = 1$	$1 < p < 2$	$p = 2$	$2 < p < \infty$	C_0
$\sigma(T)$	$\overline{\mathbb{D}}$	$\overline{\mathbb{D}}$	$\overline{\mathbb{D}}$ (EISNER-MÁTRAI)	$\overline{\mathbb{D}}$	$\overline{\mathbb{D}}$
T^* is an isometry	Yes	No	Yes (EISNER-MÁTRAI)	No	No
T has a non-trivial invariant closed cone	Yes	Yes	Yes (EISNER-MÁTRAI)	Yes	?
$\sigma_p(T)$	\mathbb{D}	?	\mathbb{D} (EISNER-MÁTRAI)	\emptyset	\emptyset
T has a non-trivial invariant subspace	Yes	?	Yes (EISNER-MÁTRAI)	?	?

Thanks!